Redmine Task#	Description	Planned work procedure	Work logs
	Power budget measurement on the IMC_REFL table (and compare with the model and the past?) (Polarization?)		
	Power budget measurement on the MCE_TRANS table		
	(and compare with the model and the past?) (Polarization?)		
	Power budget measurement on the IMMT1_TRANS table (and compare with the model and the past?) (Polarization?) (Without IFI?)		
	Beam profile on the IMC_REFL table		
	Beam profile on the MCE_TRANS table		
	Beam profile on the IMMT1_TRANS table (Without IFI?)		
	Noise budget of IMC-LSC; what can we check without the arm cavities?		
	Confirm the control topology of IMC-LSC		
	Measure finesse of IMC		
	Measure absolute length (or FSR) of IMC		
	(And the other characterization by referring <a href="http://gwwiki.icrr.u-tokyo.ac.jp/JGWwikiiKAGRA/Commissioning/Commissioning/Workshop2017/IMCInfo">http://gwwiki.icrr.u-tokyo.ac.jp/JGWwikiiKAGRA/Commissioning/Commissioning/Workshop2017/IMCInfo</a> ) though some of these are obsolete.		
	(And the other characterization by referring Enomoto thesis, Table 6.1) https://klog.icrr.u-tokyo.ac.jp/osl/?r=9073, https://klog.icrr.u-tokyo.ac.jp/osl/?r=618		
	(And the other, if any, from https://thesis.library.caltech.edu/8899/)		
	(Ref: https://gwdoc.icrr.u-tokyo.ac.jp/cgi-bin/private/DocDB/ShowDocument?docid=12594)		
	(Ref: http://gwwiki.icrr.u-tokyo.ac.jp/JGWwiki/KAGRA/Subgroups/MIF/OpticalCharacterization)		
	Noise budget of IMC-ASC		
	Confirm the control topology of IMC-ASC		
	IMC suspensions, actuator effeciency check with IMC-L -> VIS?		
	IMC suspensions, actuator DoF diagonarization? with IMC-ASC???? -> VIS? or OPT?		
	(Real-time model? Change from O3 to O4? including channel names?)		
	(MEDM??)		
	Final parameters (SDF?? github?)		
	Guardian?		
	Long-term stability?		
	Electonics check on the tables, GND,		