

| task/milestone | description | person/people with primary responsibility | start date | finish date | Mon 4/13 | Tue 4/14 | Wed 4/15 | Thu 4/16 | Fri 4/17 | Sat 4/18 | Sun 4/19 | Mon 4/20 | Tue 4/21 | Wed 4/22 | Thu 4/23 | Fri 4/24 | Sat 4/25 | Sun 4/26 | Mon 4/27 |
|--|---|---|------------|-------------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|
| Generic example below: | | | | | | | | | | | | | | | | | | | |
| major task | here is where you write something brief that spells this task out | Pat, Sam | 4/13 | 4/17 | x | x | x | x | x | | | | | | | | | | |
| subtask 1 | here is where you write a bit about this subtask | Sam | 4/13 | 4/14 | x | x | | | | | | | | | | | | | |
| subtask 2 | here is where you write a bit about this subtask | Tam | 4/14 | 4/17 | | x | x | x | x | | | | | | | | | | |
| task milestone | here is where you describe a milestone, which may fall "during" a task/subtask, or at the end of it (note that a milestone has the same start and end date) | Pat | 4/17 | 4/17 | | | | | ! | | | | | | | | | | |
| More fleshed-out example of one system below: | | | | | | | | | | | | | | | | | | | |
| interaction system | Electronic interaction is modeled with Tinkercad Circuits. | Pat | 4/14 | 4/21 | | x | x | x | x | x | x | x | x | | | | | | |
| scoping | Define inputs, outputs, and write pseudocode | Sam, Tam, Pat | 4/14 | 4/15 | | x | x | | | | | | | | | | | | |
| implementing code | Write Arduino code | Pat | 4/16 | 4/18 | | | | x | x | x | | | | | | | | | |
| implementing circuit | Build out Tinkercad circuit | Sam | 4/16 | 4/18 | | | | x | x | x | | | | | | | | | |
| integrate code & circuit | Combine code and circuit, do comprehensive testing with serial feedback to confirm internal state. | Pat, Sam | 4/19 | 4/19 | | | | | | | ! | | | | | | | | |
| complete | Wrap up details, make small adjustments as needed. | Sam, Tam | 4/20 | 4/21 | | | | | | | | x | x | | | | | | |