Self-Driving Vehicle Project: Week 2

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Zhuohuan Li (GR)



Anthony Siu (UG)



Sandeep Alankar (UG)

Who we are



Adas Bankauskas (UG)



Abia Mallick (UG)



Malav Majmudar (UG)

Who we are

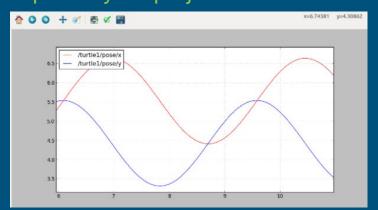
Current Progress

- Working on ROS tutorial with PuTTY
 - Reserved nodes on intersection and retrieved/plotted data from TurtleSim
- Learned about remote graphical access and how to X forward using the correct ssh commands (created X image for ROS simulations)

Learned how to duplicate PuTTY session with tmux and practiced basic tmux

shortcuts

Created GitHub repository for project code





Future Plans

- Working on creating our own website (Django)
- Learn Gazebo Simulator which we will eventually use to create the simulation environment for our self-driving car
- Continue learning ROS to develop code for the vehicle
- Learn self-driving machine learning algorithms for our vehicle to learn from its surroundings and become autonomous
- Learn about neural networks and how to properly train and test data



