## TableTanks Architecture

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# Status Update

### **Project Summary**

TableTanks is an interactive touch table that also interacts with physical objects in the real world.

### **Finalizing the Design**

 Motors and wheels for physical feedback

#### Parts-dependent:

 Whether Kinect can detect through the film/while projecting

#### **Status**

All parts have been ordered within the budget

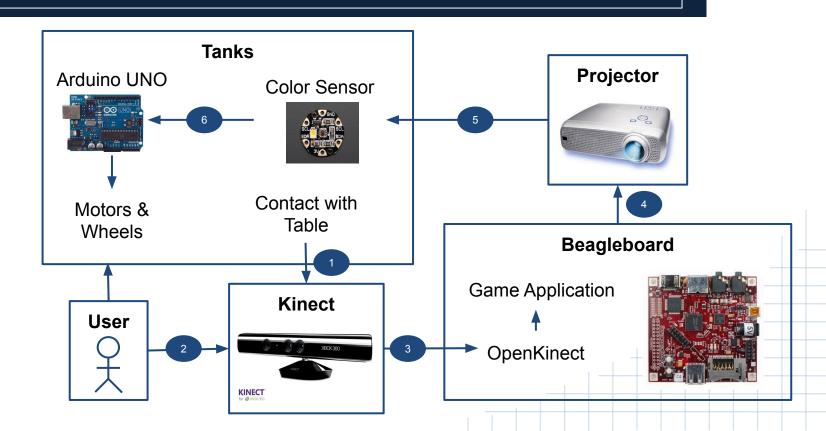
#### Parts acquired

Table

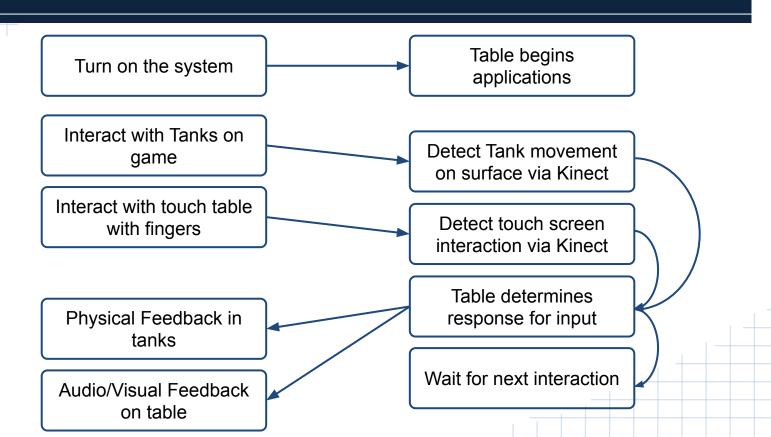
### Architecture

#### **Protocols**

- 1. Kinect Depth Image
- 2. Kinect Depth Image
- 3. USB
- 4. HDMI
- 5. Color-coded light signal
- 6. Adafruit library



### **Use Cases**



# Risks and Mitigation

Risks	Mitigation	
Compatibility issues with Kinect on Linux with Dragonboard	Use a Raspberry Pi instead	
Touch screen isn't responsive/does not work	Use Dragonboard inputs	
Can't identify tanks with QR codes	Use computer vision on Tanks	
Wireless communication with tanks (color sensor)	Use wired connection	
Projector interferes with object tracking	Mount Kinect above the table	
Visibility/readability of projected surface	Add semi-transparent film for increased visibility	

## Plans for features

Plan A	Plan B	Plan C
<ul> <li>Use Dragonboard with Kinect</li> <li>Object ID/tracking using QR codes</li> <li>Communicate with tanks using color sensor</li> <li>Physical feedback from game pieces</li> <li>Touch interaction</li> </ul>	<ul> <li>Use Dragonboard with Kinect</li> <li>Object ID/tracking using computer vision</li> <li>Use RF transmitters</li> <li>LED feedback from game pieces</li> </ul>	<ul> <li>Use Raspberry Pi with Kinect</li> <li>Object ID/tracking using computer vision</li> <li>Connect to tanks with a cable</li> </ul>