WebGPU An Explicit Graphics API for the Web

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> Many thanks to my teammates Corentin Wallez, Kai Ninomiya, and many others at Google

*I do not officially represent Google

Review: Why use explicit APIs like Vulkan?

Many slides taken from <u>Corentin's 2016 CIS 565 guest lecture</u> and <u>Kai's 2017 CIS 565 guest lecture</u>

Review: Why use explicit APIs like Vulkan?

- Explicit memory management
- Multithreading
- Async compute
- ...and more!

Texture resizing in OpenGL

User resizing texture:

- Resize the texture
- Use it
- :D

Driver resizing texture:

- Allocate new memory
- Use new memory

• :D

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Driver resizing texture:

- Allocate new memory
 - Insert fence
 - Check the fence every frame?
 - Garbage collect memory
- Use new memory
- :/

Texture resizing in OpenGL

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- Resize the texture
- Use it
- :D

Driver resizing texture:

- Allocate new memory
 - Insert fence
 - Check the fence every frame?
 - Garbage collect memory
 - Dirty uniforms passed to shaders
 - Dirty framebuffers
 - Dirty texture buffers
- Use new memory
- :(

Why: Predictable behavior and performance

Applications can:

- Control when expensive operations happen
- Have low variance frame timing (VR)
- Be smarter than the OpenGL driver

Why: Consoles

Graphics development on console:

- Direct access to the hardware
- Manual memory management
- Getting to that last 1% of performance
- Multithreading

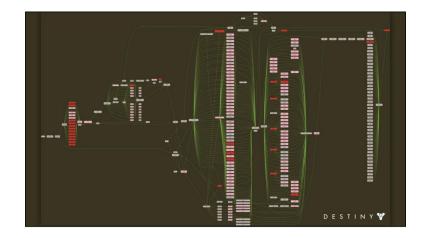
Developers want that on PC too.

Why: Multithreading

Destiny's Multi-threaded Renderer Architecture by Natalya Tatarchuk

(decouple)

- Simulation
- Determine views (for rendering, shadow-mapping, etc.)
- Compute visibility
- Extract data for rendering
- Generate draw calls



Command buffers enable multithreading

Thread 1

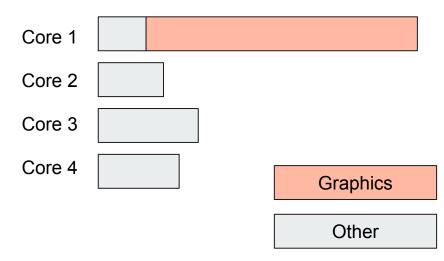
Thread 3

Thread 2

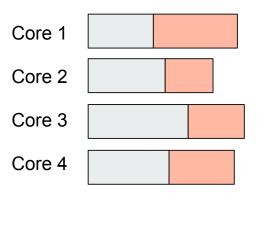
vkBeginCommandBuffer vkBeginCommandBuffer vkBeginCommandBuffer vkCmdSetPipeline vkCmdSetPipeline vkCmdSetPipeline vkCmdDrawArrays vkCmdDrawArrays vkCmdDrawArrays vkCmdSetScissor vkEndCommandBuffer vkCmdSetPipeline vkCmdSetPushConstants vkCmdDrawArrays vkEndCommandBuffer vkCmdDrawArrays vkEndCommandBuffer CmdBuf1 CmdBuf2 CmdBuf3 Queue vkQueueSubmit

Why: Multithreading

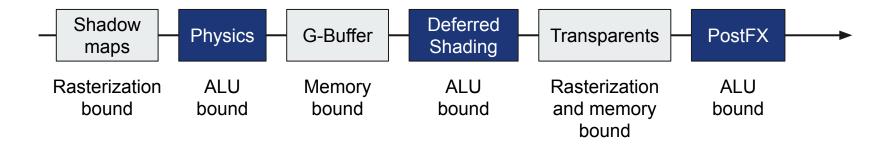
Single-threaded APIs



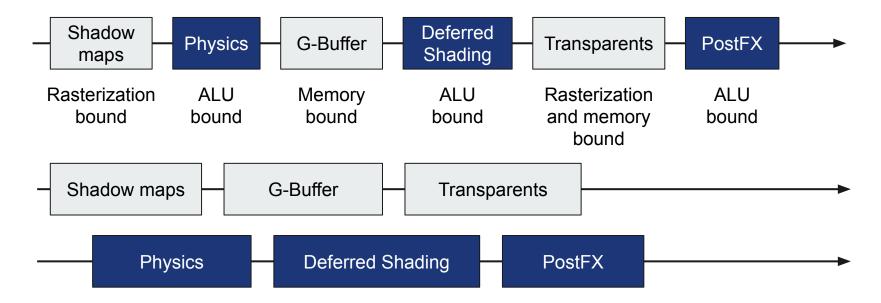
Multi-threaded APIs



Why: Async Compute



Why: Async Compute



Case Study: Vulkan Grass Rendering (project 6)

We almost have async compute! How can we do better?

- Compute:
 - \circ Apply forces
 - Update `Blade` buffer
 - Cull blades
- Memory barrier (compute->graphics) Waits for compute pipeline to finish.
- Graphics: Rasterize + Tessellate

Case Study: Vulkan Grass Rendering (project 6)

- Decouple physics and culling
 - Compute expensive physics for several frames in the future simultaneously
 - This step is camera-independent
- Compute culled blades for the next frame
- Memory barrier (compute->graphics) Does not wait. Blades were culled while rendering the previous frame.
- Graphics: Rasterize + Tessellate

Explicit Graphics APIs on the Web https://github.com/gpuweb/gpuweb

A Few Goals:

- Security & Stability
 - A website can't be allowed to read your data
 - Native APIs allow unsafe operations and undefined behavior
- Portability
 - Create an API to map onto D3D12, Metal, and Vulkan
 - The Web should work the same everywhere, no matter what platform
- Fast
 - Multithreading
 - WebAssembly
 - Web Workers

It's happening, but it's hard...

- See <u>Kai's presentation</u> to learn about the process of designing this API
- Reaching agreement with the other browser vendors takes a lot of time and discussion

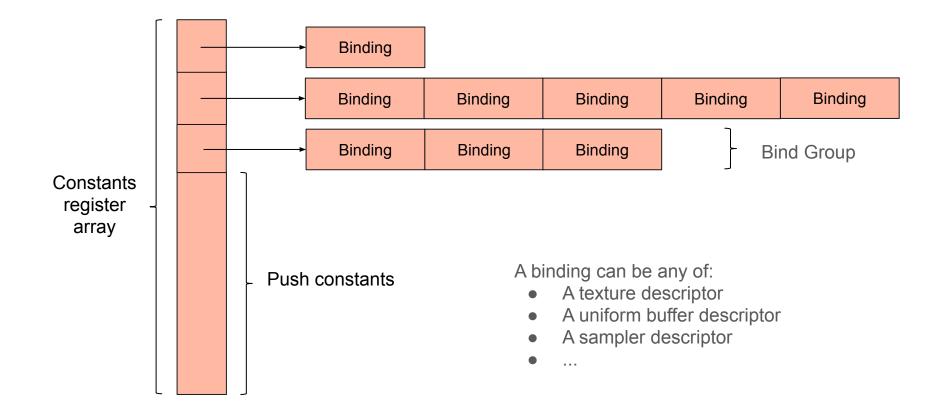
Dawn, a WebGPU implementation*

API overview, examples, assorted details, and cool things

https://dawn.googlesource.com/dawn

*API subject to change

API Overview: Resource Binding



Resource Binding

Very similar to Vulkan:

- Pipeline layouts, composed of bind group layouts, define the structure of resource bindings for a pipeline
- Bind groups are created from bind group layouts and contain references to resources (buffer views, texture views, etc.)
- Bind groups are set on a pipeline when recording a command buffer

// Create bind group layouts dawn::BindGroupBinding bufferBindings[] = { { 0, dawn::ShaderStageBit::Compute, dawn::BindingType::Sampler }, // (binding = 0) G-buffer sampler { 1, dawn::ShaderStageBit::Compute, dawn::BindingType::SampledTexture }, // (binding = 1) G-buffer { 2, dawn::ShaderStageBit::Compute, dawn::BindingType::StorageBuffer }, // (binding = 2) index buffer { 3, dawn::ShaderStageBit::Compute, dawn::BindingType::StorageBuffer }, // (binding = 3) vertex buffer { 4, dawn::ShaderStageBit::Compute, dawn::BindingType::StorageBuffer }, // (binding = 4) output color buffer };

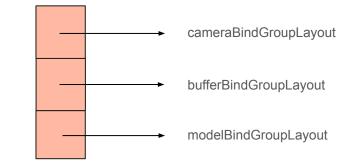
dawn::BindGroupLayoutDescriptor bufferBindGroupLayoutDesc { nullptr, 5, bufferBindings }; dawn::BindGroupLayout bufferBindGroupLayout = device.CreateBindGroupLayout(&bufferBindGroupLayoutDesc);



// Create other bind group layouts...

// Create pipeline

| <pre>dawn::BindGroupLayout bindGroupLayouts[] = {</pre> | |
|---|--------------|
| cameraBindGroupLayout, | // (set = 0) |
| bufferBindGroupLayout, | // (set = 1) |
| modelBindGroupLayout, | // (set = 2) |
| }; | |



```
dawn::PipelineLayoutDescriptor pipelineLayoutDesc { nullptr, 3, bindGroupLayouts };
dawn::PipelineLayout pipelineLayout = device.CreatePipelineLayout(&pipelineLayoutDesc);
```

dawn::ShaderModule csModule = utils::CreateShaderModule(device, dawn::ShaderStage::Compute, kComputeShaderString);

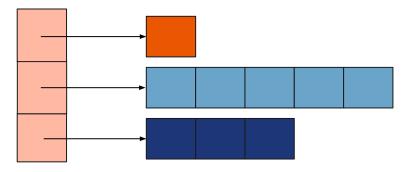
```
dawn::ComputePipelineDescriptor computePipelineDesc{nullptr, pipelineLayout, csModule, "main"};
dawn::ComputePipeline computePipeline = device.CreateComputePipeline(&computePipelineDesc);
```

```
// Create camera bind group
dawn::BindGroupBinding bindings[] = {
      { 0, dawn::BindingType::BufferView, cameraBufferView },
};
dawn::BindGroupDescriptor bindGroupDesc { cameraBindGroupLayout, 1, bindings }
dawn::BindGroup cameraBindGroup = device.CreateBindGroup(&bindGroupDesc);
// Create bind groups for all models
for (Model* model : models) {
      dawn::BindGroupBinding bindings[] = {
             { 0, dawn::BindingType::BufferView, model->bufferView },
             { 1, dawn::BindingType::TextureView, model->textureView },
             { 2, dawn::BindingType::Sampler, model->sampler },
      };
      dawn::BindGroupDescriptor bindGroupDesc { modelBindGroupLayout, 3, bindings }
      model->modelBindGroup = device.CreateBindGroup(&bindGroupDesc);
```

// Set bind groups

dawn::ComputePassEncoder pass = builder.BeginComputePass(); pass.SetComputePipeline(computePipeline); pass.SetBindGroup(0, cameraBindGroup);

```
for (ModelGroup* modelGroup : modelGroups) {
    pass.SetBindGroup(1, modelGroup->bufferBindGroup);
    for (Model* model : modelGroup->GetModels()) {
        pass.SetBindGroup(2, model->modelBindGroup);
        pass.Dispatch(1280, 960, 1);
    }
}
pass.EndPass();
```



API Overview: Pipelines

Render / Compute Pipelines

A big object that defines fixed-function state and format of the inputs and outputs:

- Pipeline layout (set of bind group layouts)
- Compiled shaders

Render pipelines only:

- Various state
 - Blending, depth, stencil, input format, etc.
- Framebuffer attachment formats

Creating a Render Pipeline

// Create depth stencil state

// Create vertex input and attribute state

dawn::VertexAttributeDescriptor vertexAttribs[] = {

- $\{0, 0, 0, dawn:: VertexFormat:: FloatR32G32B32A32\},\$
- {1, 1, 0, dawn::VertexFormat::FloatR32}};
- dawn::VertexInputDescriptor vertexInputs[] = {

inputStateDesc.inputs = vertexInputs:

inputStateDesc.numInputs = 2:

// Create pipeline layout

dawn::PipelineLayoutDescriptor pipelineLayoutDesc; pipelineLayoutDesc.numBindGroupLayouts = 4; pipelineLayoutDesc.bindGroupLayouts = bindGroupLayouts; dawn::PipelineLayout pipelineLayout =

device.CreatePipelineLayout(&pipelineLayoutDesc);

// Create render pipeline

dawn::RenderPipelineDescriptor renderPipelineDesc; renderPipelineDesc.vertexStage =

dawn::PipelineStageDescriptor { vsModule, "main" }; renderPipelineDesc.fragmentStage =

dawn::PipelineStageDescriptor { fsModule, "main" }; renderPipelineDesc.primitiveTopology = dawn::PrimitiveTopology::TriangleList; renderPipelineDesc.depthStencilState = depthStencilState; renderPipelineDesc.inputState = inputState; renderPipelineDesc.attachmentsState = attachmentsState;

// Create attachment states

dawn::Attachment colorAttachments[] = {{ dawn::TextureFormat::R8G8B8A8Uint }}; dawn::Attachment depthStencilAttachment { dawn::TextureFormat::D32FloatS8Uint }; dawn::AttachmentsState attachmentsState { colorAttachments, 1, depthStencilAttachment };

API Overview: Command Submission

Render/Compute Passes

• Encode a group of commands into the command buffer *Render passes:* setVertexBuffers(...), draw(...), etc. *Compute passes:* dispatch(...)

Render passes:

- Contain attachment descriptions
 - g-buffers, color buffers, etc.

Implicit Resource Transitions

- Resources must not change usage within a pass ex.) Transition from vertex to uniform buffer
- Resources are synchronized:
 - At pass boundaries, to transition usage
 - For UAVs between dispatch() calls
- Implicit resource transitions make application development significantly easier
- Explicit transitions are faster, but forgetting them leads to undefined behavior

Example Render / Compute Passes

```
// Example command buffer for a particle simulation
                                                                                              static uint32_t pingpong = 0;
dawn::CommandBuffer createCommandBuffer(
                                                                                              void frame() {
                 const dawn::RenderPassDescriptor& renderPass,
                                                                                                      dawn::CommandBuffer commandBuffer =
                 uint32_t i) {
                                                                                                               createCommandBuffer(renderPass, pingpong);
        static const uint32 t zero = 0u:
                                                                                                      queue.Submit(1, &commandBuffer);
        auto& bufferDst = particleBuffers[(i + 1) % 2]; // ping pong between these
                                                                                                      pingpong = (pingpong + 1) % 2;
        dawn::CommandBufferBuilder builder = device.CreateCommandBufferBuilder();
                 dawn::ComputePassEncoder pass = builder.BeginComputePass();
                 pass.SetComputePipeline(computePipeline)
                 pass.SetBindGroup(0, bindGroups[i]); // This where bufferDst is bound for writing the particle attributes
                 pass.Dispatch(kNumParticles, 1, 1);
                 pass.EndPass();
                 dawn::RenderPassEncoder pass = builder.BeginRenderPass(renderPass);
                 pass.SetRenderPipeline(renderPipeline)
                 pass.SetVertexBuffers(0, 1, &bufferDst, &zero): // Bind bufferDst as a vertex buffer for particles
                 pass.SetVertexBuffers(1, 1, &modelBuffer, &zero);
                 pass.DrawArrays(3, kNumParticles, 0, 0);
                 pass.EndPass();
        return builder.GetResult();
```

Implementing Timeline Fences (simplified)

And cool things I've learned in my first few months about interprocess communication and GPU servicification.

What is a Fence?

- A synchronization primitive used to wait for execution on the GPU to complete
- For WebGPU, we've settled on "numerical fences"
 - Monotonically increasing values indicate a timestamp in GPU execution history.
 - Hence, the name "timeline fences"

What is a Fence?

```
queue.Submit(1, &commands1); // submit commands1
queue.Signal(fence, 1u);
queue.Submit(1, &commands2); // submit commands2
queue.Signal(fence, 2u);
queue.Submit(1, &commands3); // submit commands3
queue.Signal(fence, 3u);
```

// Some time later...
uint64_t completedValue = fence.GetCompletedValue();

```
// Suppose completedValue == 2.
// That means that commands1 and commands2 have finished executing.
// commands3 may not have finished executing.
```

```
struct Fence {
    uint64_t signalValue = 0;
    uint64_t completedValue = 0;
};
```

```
struct Queue {
    struct SignaledFence {
        Fence fence;
        VkFence nativeFence;
        uint64_t signalValue;
    };
```

std::vector<SignaledFence> signaledFences;

```
};
```

fence, nativeFence, signalValue});

```
A Fence stores the last signaled
struct Fence {
                                                                                ence fence, uint64_t signalValue)
                                         value and the value that has
      uint64_t signalValue = 0;
                                         completed execution on the
      uint64_t completedValue = 0;
                                                                                le <= fence.signalValue) {</pre>
};
                                                                                 dation error: Fence values must
                                         GPU
                                                                                 ease monotonically
struct Oueue
                                                                          return:
      struct SignaledFence {
             Fence fence:
                                                                   fence.signalValue = signalValue;
             VkFence nativeFence:
                                                                   VkFence nativeFence:
             uint64_t signalValue;
                                                                   vkCreateFence(device, createInfo, nullptr,
      };
                                                                                 &nativeFence):
                                                                   vkQueueSubmit(queue, 0, nullptr, nativeFence);
      std::vector<SignaledFence> signaledFences;
                                                                   signaledFences.push_back(
};
                                                                     SignaledFence{
                                                                       fence, nativeFence, signalValue});
```

When we signal a Fence, create a native vkFence and signal it on a queue.

Add the fence to a list of signaled fences we will check later

```
struct Queue {
    struct SignaledFence {
        Fence fence;
        VkFence nativeFence;
        uint64_t signalValue;
    };
```

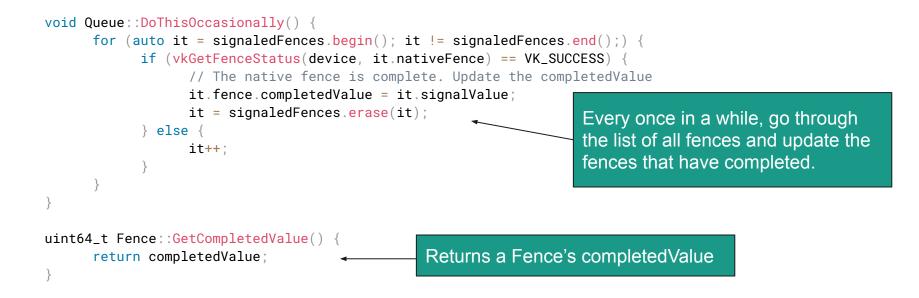
std::vector<SignaledFence> signaledFences;

};

void Queue::Signal(Fence fence, uint64_t signalValue)

if (signalValue <= fence.signalValue) {
 // Validation error: Fence values must
 // increase monotonically
 return;</pre>

fence, nativeFence, signalValue});



```
void Queue::DoThisOccasionally() {
      for (auto it = signaledFences.begin(); it != signaledFences.end();) {
            if (vkGetFenceStatus(device, it.nativeFence) == VK_SUCCESS) {
                  // The native fence is complete. Update the completedValue
                  it.fence.completedValue = it.signalValue;
                  it = signaledFences.erase(it);
            } else {
                  it++:
uint64_t Fence::GetCompletedValue() {
      return completedValue;
```

This doesn't "just work" on the Web :(

The client browser talks to our server Dawn implementation via interprocess communication using a command buffer.

The client does not run Dawn, it asks a service to execute commands.



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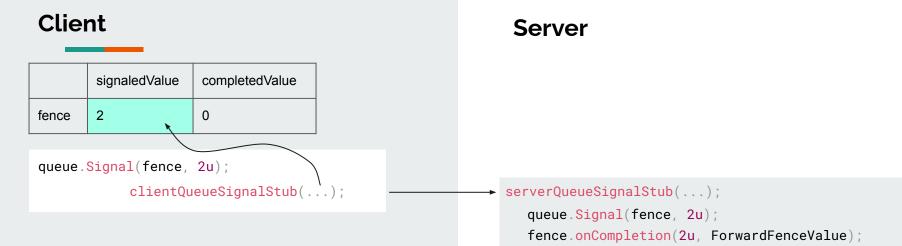
| Client | | Server |
|---|------------------------------|--|
| <pre>int x = fence.GetCompletedValue</pre> | ();fence.GetCompletedValue() | I'll compute that and let you know in just a bit |
| ?!? This is supposed to be synchronous. What do I assign to x!? | | |

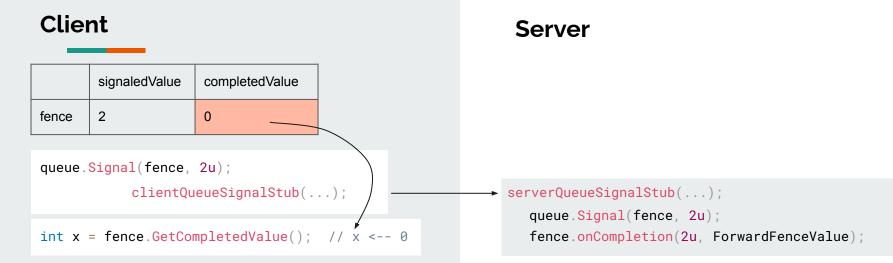
Client

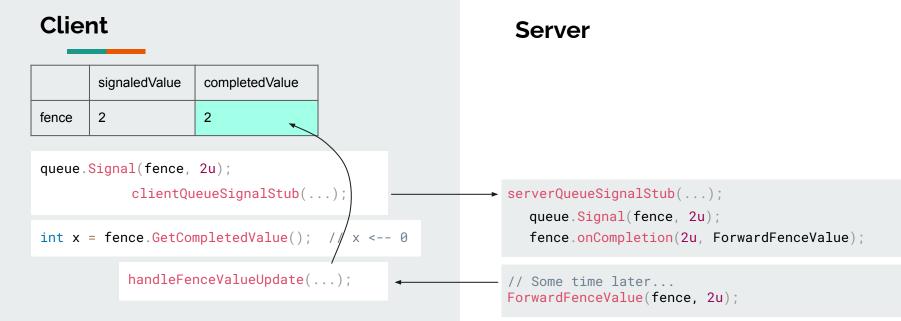
Server

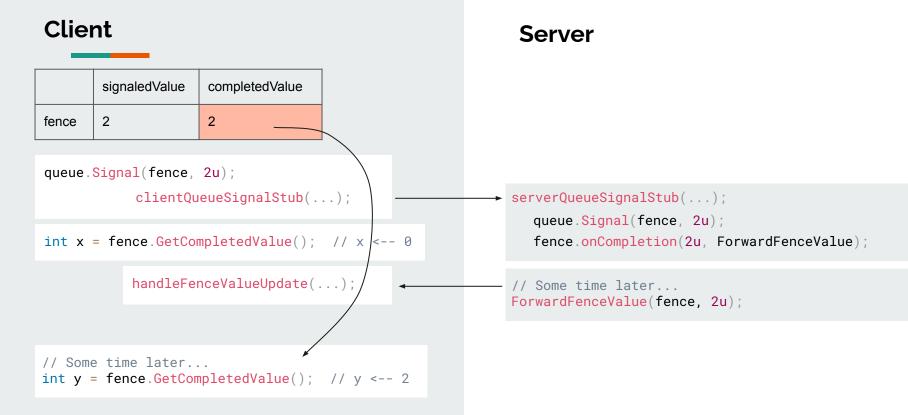
| | signaledValue | completedValue |
|-------|---------------|----------------|
| fence | 0 | 0 |

queue.Signal(fence, 2u);









This Client / Server separation exists for *every* object in Dawn.

It's actually pretty simple, but this concept was foreign to me when I was first introduced

What is actually happening here?

dawn::Buffer buffer =
 device.CreateBuffer(&descriptor);

buffer.SetSubData(0, 10, data);

- The Client doesn't have any real buffers
- The Client asks the Server to execute commands
- How does this code actually call buffer.SetSubData(0, 10, data);?

dawn::Buffer buffer =
 device.CreateBuffer(&descriptor);

- Get a free **ObjectID*** for the bind group
- Allocate a "Buffer" Object
 - o This is pretty much just
 struct ClientBuffer {
 uint32_t id;
 };
- Tell the server to create a real bind group and map it to ObjectID
- Return the ClientBuffer

*This is actually two ids for reasons I won't explain

dawn::Buffer buffer =
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- Get a free **ObjectID*** for the bind group
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};

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- Return the ClientBuffer

- Actually create a real Buffer
- Map the **ObjectID** to the created buffer

*This is actually two ids for reasons I won't explain

buffer.SetSubData(0, 10, data);

BufferSetSubDataCmd cmd {
 buffer.id,
 0, 10, data
 };

buffer.SetSubData(0, 10, data);

BufferSetSubDataCmd cmd {
 buffer.id,
 0, 10, data
 };

- Lookup the ObjectID and get a pointer to a Buffer
- Execute buffer.SetSubData(0, 10, data);

Summary

Communicating between the Client and Server can be slow

- Transfer as little information as possible
 - Don't send large objects between the Client and Server
 - Use ObjectIds which give the Client a "handle" to Server objects
- Reduce Client-Server dependencies so the Client is not blocked
 - Objects can be created and their ObjectIds used in other commands without needing to wait for the server

Demo :)

Career Advice?

To prepare for the future, Don't optimize for the future.

Tomorrow is inherently uncertain.

Don't pour too much energy into perfecting a future that may never occur.

More specifically: • Don't make decisions out of fear of future regret. Appreciate and enjoy the opportunities before you now.