

BTech Project Students:

- Suresh Khetawat (121601013): Learning and Control of Dynamical System, August 2019 - May 2020
- Bipin Gami (121701004): Modeling, simulation and experiments on permanent magnet dc motor control, August 2020 - May 2021
- Konda Venkata Sai Maneesha (121801023): Control of autonomous vehicles using reinforcement learning August 2021 - May 2022
- Vipparthi Pritish (121801049): Study of control of dynamical systems using reinforcement learning algorithms, August 2021 - May 2022
- Ambati Thrinay Kumar Reddy (121901003), Komali Babaji Pattabhiram Gowd (121901022): NAF (Normalized Advantage Function) based optimal control of discrete time nonlinear system, August 2022 - May 2023
- N.V.Sumanth Reddy (121901028): Control of a self balancing robot via reinforcement learning, August 2022 - May 2023
- Dheeraj Warriar (122001015), Krishan Nair (122001023): Advanced reinforcement learning algorithms for control, August 2023 - present
- Galam Bharath Kumar (122001016): Control of robotic manipulator using reinforcement learning, August 2023 - present
- Prithiv Vijayashankar (122001037): Networked estimation and control of a dynamical systems, August 2023 - present

Open Ended Lab Project Students:

- Ambati Thrinay Kumar Reddy (121901003), Komali Babaji Pattabhiram Gowd (121901022), N.V.Sumanth Reddy (121901028): Control designs for autonomous vehicles based on reinforcement learning, January 2022 - May 2022
- Rittika Ghosh (122101047), Daksh Viral Raval (122101044): Control of mobile robot using reinforcement learning, August -December 2023
- Harishma(122101047), Siri Sure(122101034): Humanoid locomotion using reinforcement learning, August -December 2023