

Weekly Dev Call: November 8, 2017

[Previous meeting minutes](#)

[Release 1.7 Milestones](#)

- [v1.7 release coordination](#)
 - Which features didn't make it?
 - What is blocking?
- General Q&A

Merged Pull Requests for Release notes

<https://github.com/PX4/Firmware/pulls?utf8=%E2%9C%93&q=is%3Apr%20is%3Amerged%20merged%3A%3E2017-06-01>

- Pixhawk mini Flashing in QGC
 - FMUv3 - v2 previously
 - **Action:** send Daniel a PHM
- Testing for Release
 - Flight Cards
 - 1.7 should work with QGC stable
 - **Action:** ping everyone in about 2 hours
- Setpoint changes in fixed wing controller side
- Release notes
 - <https://github.com/PX4/Firmware/pulls?utf8=%E2%9C%93&q=is%3Apr%20is%3Amerged%20merged%3A%3E2017-06-01>
 - Automate and write proper release notes
- Release
 - Ask community for feedback
 - Discourse
 - Slack
 - Newsletter

CI

- Help with new Jenkins

- Old Jenkins migrate to DroneCore
- **Action:** Jenkins needs clarity when it fails
- **Action:** something that doesn't require ROS to do our Integration Tests
 - We need to enable developers that don't normally run ROS
- **Action:** Testing needs to be much more visible
 - WebUI similar to flight review that shows the full test context in a human controls engineer perspective
 - Understand what the vehicle did, where and how it failed
 - High level overview of the whole statistics
 - Help to understand performance
 - Link back to github
 - Statistics for the test run

v1.8

- **Action:** make sure platform coordination happens