## **Know Questions - Python**

Check your understanding of the concepts in the **Medbot Unit** by answering these questions:

- 1. In robotics programming, what is referred to as a "behavior?"
  - a. A complex task
  - b. The way the robot acts
  - c. A simple task
  - d. All of these answers are correct.
- 2. True or False: The *drive\_for* command can be used to drive the robot forward for a specific distance.
  - a. True
  - b. False
- 3. True or False: The *wait* command will end the project.
  - a. True
  - b. False
- 4. True or False: The *drive\_for* command can be used to move the robot forward and in reverse.
  - a. True
  - b. False

## 5. In order to turn your robot 180 degrees:

- a. Use the *turn\_for* command and change the degrees to 180.
- b. Use the *drive\_for* command and set the distance to 180.
- c. Use the *drive\_for* command and change the degrees from 180 to -180 to turn in reverse.
- d. Use the *wait* command and set the seconds to 180.
- 6. True or False: Pseudocode is an actual programming language that your robot can understand.
  - a. True
  - b. False