

# OAT Bootcamp Physics Equation Sheet

LINEAR KINEMATICS		
	Formula	Notes
Average Velocity	$v_{avg} = \frac{d}{t}$	$v_{avg}$ = velocity (units: m/s) d = displacement (units: m) t = time (units: s)
Displacement	$d = v_i t + \frac{1}{2} a t^2$	d = displacement (units: m) $v_i$ = initial velocity (units: m/s) a = acceleration (units: m/s <sup>2</sup> ) t = time (units: s)
Final Velocity (Time)	$v_f = v_i + a t$	$v_f$ = final velocity (units: m/s) $v_i$ = initial velocity (units: m/s) a = acceleration (units: m/s <sup>2</sup> ) t = time (units: s)
Final Velocity (Displacement)	$v_f^2 = v_i^2 + 2 a d$	$v_f$ = final velocity (units: m/s) $v_i$ = initial velocity (units: m/s) a = acceleration (units: m/s <sup>2</sup> ) d = displacement (units: m)
Average Acceleration	$a_{avg} = \frac{(v_f - v_i)}{t}$	$a_{avg}$ = acceleration (units: m/s <sup>2</sup> ) $v_f$ = final velocity (units: m/s) $v_i$ = initial velocity (units: m/s) t = time (units: s)

FORCES		
	Formula	Notes
Net Force	$F_{net} = m a$	$F_{net}$ = net force (units: N) m = mass (units: kg) a = acceleration (units: m/s <sup>2</sup> )
Weight	$F_w = m g$	$F_w$ = weight (units: N) m = mass (units: kg) g = acceleration due to gravity (g = 10 m/s <sup>2</sup> )
Normal Force	$F_N = F_w \cos(\theta)$	$F_N$ = normal force (units: N) $F_w$ = weight (units: N) m = mass (units: kg) $\theta$ = angle between horizontal and force
Friction Force	$F_f = \mu F_N$	$F_f$ = friction force (units: N) $F_N$ = normal force (units: N) $\mu$ = friction coefficient

GRAVITATIONAL		
	Formula	Notes
<b>Gravitational Force (Two bodies)</b>	$F = \frac{Gm_1m_2}{d^2}$	F = gravitational force (units: N) G = gravity constant ( $G = 6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$ ) $m_1$ = mass object 1 (units: kg) $m_2$ = mass object 1 (units: kg) d = distance between centers of objects (units: m)
<b>Gravitational Acceleration (One body)</b>	$g = \frac{Gm}{r^2}$	g = acceleration due to gravity ( $g = 10 \text{ m/s}^2$ ) G = gravity constant ( $G = 6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$ ) m = mass single body (units: kg) r = radius of body (units: m)

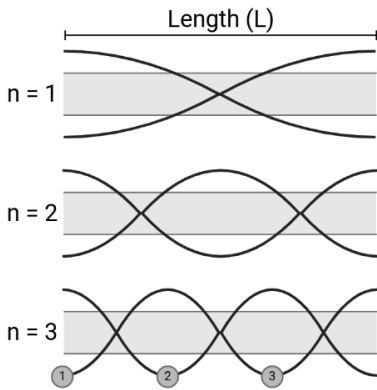
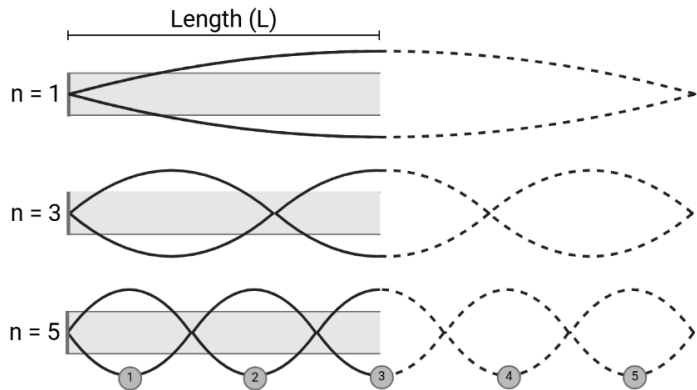
ROTATIONAL & CIRCULAR MOTION		
	Formula	Notes
<b>Uniform Circular Motion Velocity</b>	$v_c = \frac{2\pi r}{T}$	$v_c$ = velocity (units: m/s) r = radius (units: m) T = period (units: s)
<b>Centripetal Acceleration</b>	$a_c = \frac{v^2}{r}$	$a_c$ = centripetal acceleration (units: $\text{m/s}^2$ ) v = velocity (units: m/s) r = radius (units: m)
<b>Centripetal Force</b>	$F_c = ma_c = \frac{mv^2}{r}$	$F_c$ = centripetal force (units: N) m = mass (units: kg) $a_c$ = centripetal acceleration (units: $\text{m/s}^2$ ) v = velocity (units: m/s) r = radius (units: m)
<b>Torque</b>	$\tau = r \times F$ $ \tau  =  r  F \sin\theta$	$\tau$ = torque vector (units: $\text{N} \cdot \text{m}$ ) r = lever arm vector (units: m) F = force vector (units: N) $\theta$ = angle between lever arm and force <b>Note:</b>  x  denotes magnitude or absolute value
<b>Linear Displacement</b>	$d = r\theta$	d = linear displacement (units: m) r = radius (units: m) $\theta$ = angular displacement (units: rad)
<b>Linear Velocity</b>	$v = r\omega$	v = linear velocity (units: m/s) r = radius (units: m) $\omega$ = angular velocity (units: rad/s)
<b>Linear Acceleration</b>	$a = r\alpha$	a = linear acceleration (units: $\text{m/s}^2$ ) r = radius (units: m) $\alpha$ = angular acceleration (units: $\text{rad/s}^2$ )

# ENERGY AND MOMENTUM

	Formula	Notes
<b>Kinetic Energy</b>	$KE = \frac{1}{2}mv^2$	KE = kinetic energy (units: J) m = mass (units: kg) v = velocity (units: m/s)
<b>Potential Energy</b>	$PE = mgh$	PE = potential energy (units: J) m = mass (units: kg) g = acceleration due to gravity (g = 10 m/s <sup>2</sup> ) h = height (units: m)
<b>Total Mechanical Energy</b>	$E_{TME} = KE + PE$	E <sub>TME</sub> = total mechanical energy (units: J) KE = kinetic energy (units: J) PE = potential energy (units: J)
<b>Work (Done by Force)</b>	$W = Fd\cos(\theta)$	W = work (units: J) F = force (units: N) d = displacement (units: m) θ = angle between F and d
<b>Work-Energy Theorem</b>	$W = \Delta KE$	W = work (units: J) ΔKE = change in kinetic energy (units: J)
<b>Power</b>	$P = \frac{W}{t}$	P = power (units: W) W = work (units: J) t = time (units: s)
<b>Momentum</b>	$p = mv$	p = momentum (units: kg · m/s) m = mass (units: kg) v = velocity (units: m/s)
<b>Impulse</b>	$\Delta p = F\Delta t$	Δp = impulse (units: N · s) F = force applied (units: N) Δt = duration of time (units: s)
<b>Inelastic Collisions</b>	$m_1v_1 + m_2v_2 = m_3v_3$	m <sub>1</sub> = mass object 1 (units: kg) v <sub>1</sub> = velocity object 1 (units: m/s) m <sub>2</sub> = mass object 2 (units: kg) v <sub>2</sub> = velocity object 2 (units: m/s) m <sub>3</sub> = total mass of objects 1 & 2 (units: kg) v <sub>3</sub> = velocity object 3 (units: m/s)
<b>Elastic Collisions</b>	$m_1v_{1,i} + m_2v_{2,i} = m_1v_{1,f} + m_2v_{2,f}$	m <sub>1</sub> = mass object 1 (units: kg) v <sub>1,i</sub> = initial velocity object 1 (units: m/s) v <sub>1,f</sub> = final velocity object 1 (units: m/s) m <sub>2</sub> = mass object 2 (units: kg) v <sub>2,i</sub> = initial velocity object 2 (units: m/s) v <sub>2,f</sub> = final velocity object 2 (units: m/s)
<b>Photon Energy</b>	$E = \frac{hc}{\lambda}$	E = photon energy (units: J) h = Planck's constant (6.626 x 10 <sup>-34</sup> J · s) c = speed of light (3 x 10 <sup>8</sup> m/s) λ = wavelength (units: m)

CENTER OF MASS		
	Formula	Notes
Center of Mass	$COM = \frac{m_1 x_1 + m_2 x_2 + \dots}{m_1 + m_2 + \dots}$	COM = center of mass (units: m) m = mass of object (units: kg) x = distance of object (units: m)

SIMPLE HARMONIC MOTION (SPRINGS & PENDULUMS)		
	Formula	Notes
Spring Force (Hooke's Law)	$F = -kx$ <p> <b>Stretched:</b> x is positive (+)  <b>Compressed:</b> x is negative (-)         </p>	F = force from the spring (units: N) k = spring constant (units: N/m) x = distance stretched/compressed (units: m)
Work (Spring)	$W = \frac{1}{2}kx^2$	W = work (units: J) k = spring constant (units: N/m) x = distance stretched/compressed (units: m)
Potential Energy (Spring)	$PE = \frac{1}{2}kx^2$	PE = potential energy (units: J) k = spring constant (units: N/m) x = distance stretched/compressed (units: m)
Period (Spring)	$T = 2\pi\sqrt{\frac{m}{k}}$	T = period (units: s) m = mass of object (units: kg) k = spring constant (units: N/m)
Period (Pendulum)	$T = 2\pi\sqrt{\frac{L}{g}}$	T = period (units: s) L = length of pendulum (unit: m) g = acceleration due to gravity ( $g = 10 \text{ m/s}^2$ ) <b>Note:</b> the period is independent of mass
Angular Frequency	$\omega = \frac{2\pi}{T}$ $\omega = 2\pi f$	$\omega$ = angular frequency (units: rad/s) T = period (units: s) F = frequency (units: Hz)
Angular Frequency (Oscillating Spring)	$\omega = \sqrt{\frac{k}{m}}$	$\omega$ = angular frequency (units: rad/s) k = spring constant (units: N/m) m = mass (units: kg)

WAVES		
	Formula	Notes
Wave Velocity	$v = \lambda f$	v = velocity (units: m/s) $\lambda$ = wavelength (units: m) f = frequency (units: Hz)
Period	$T = \frac{1}{f}$	T = period (units: s) f = frequency (units: Hz)
Wave / Sound Intensity	$I = \frac{P}{A} = \frac{P}{4\pi x^2}$	I = sound intensity (units: W/m <sup>2</sup> ) P = power (units: W) A = area (units: m <sup>2</sup> ) x = distance from point source (units: m)
Sound Intensity (in Decibels)	$dB = 10log\left(\frac{I}{I_0}\right)$	dB = change in decibels I = intensity of sound (units: W/m <sup>2</sup> ) I <sub>0</sub> = intensity of the softest sound perceivable by the human ear (I <sub>0</sub> = 10 <sup>-12</sup> W/m <sup>2</sup> )
Standing-Wave Harmonics Conventions	<div><div><div>Open Air Column</div><div></div></div><div><div>Closed Air Column</div><div></div></div></div>	
	n = 1, 2, 3... any <u>positive</u> integers	
	$\lambda_n = \frac{2L}{n}$ $f_n = n\left(\frac{v}{2L}\right)$	
	n = 1, 3, 5... any <u>odd</u> integers	
	$\lambda_n = \frac{4L}{n}$ $f_n = n\left(\frac{v}{4L}\right)$	
$\lambda_n$ = wavelength, $f_n$ = frequency, n = harmonic number (overtone + 1), v = speed		

FLUID STATICS		
	Formula	Notes
Density	$\rho = \frac{m}{V}$	<p><math>\rho</math> = density (units: kg/m<sup>3</sup>)</p> <p><math>m</math> = mass (units: kg)</p> <p><math>V</math> = volume (units: m<sup>3</sup>)</p>
Buoyant Forces	$F_B = \rho V g$ <p>For floating objects: <math>F_B = mg</math></p>	<p><math>F_B</math> = buoyant force (units: N)</p> <p><math>\rho</math> = density of fluid displaced (units: kg/m<sup>3</sup>)</p> <p><math>V</math> = volume of fluid displaced (units: m<sup>3</sup>)</p> <p><math>g</math> = acceleration due to gravity (<math>g = 10 \text{ m/s}^2</math>)</p> <p><math>m</math> = mass of floating object (kg)</p>
Pressure	$P = \frac{F}{A}$	<p><math>P</math> = pressure (units: Pa)</p> <p><math>F</math> = force (units: N)</p> <p><math>A</math> = area (units: m<sup>2</sup>)</p>
Hydrostatic Pressure	$P = P_o + \rho g h$	<p><math>P</math> = pressure (units: Pa)</p> <p><math>P_o</math> = surface level pressure (units: Pa)</p> <p><math>\rho</math> = density (units: kg/m<sup>3</sup>)</p> <p><math>g</math> = acceleration due to gravity (<math>g = 10 \text{ m/s}^2</math>)</p> <p><math>h</math> = height (units: m)</p>
Pascal's Principle (Hydraulics)	$\frac{F_1}{F_2} = \frac{A_1}{A_2}$	<p><math>F_1</math> = force, region 1 (units: N)</p> <p><math>F_2</math> = force, region 2 (units: N)</p> <p><math>A_1</math> = area, region 1 (units: m<sup>2</sup>)</p> <p><math>A_2</math> = area, region 2 (units: m<sup>2</sup>)</p>
Partially Submerged Object Relationships	$\frac{V_{sub}}{V_{obj}} = \frac{\rho_{obj}}{\rho_{fluid}}$	<p><math>V_{sub}</math> = volume of submerged portion (units: m<sup>3</sup>)</p> <p><math>V_{obj}</math> = volume of entire object (units: m<sup>3</sup>)</p> <p><math>\rho_{obj}</math> = density of object (units: kg/m<sup>3</sup>)</p> <p><math>\rho_{fluid}</math> = density of fluid (units: kg/m<sup>3</sup>)</p>

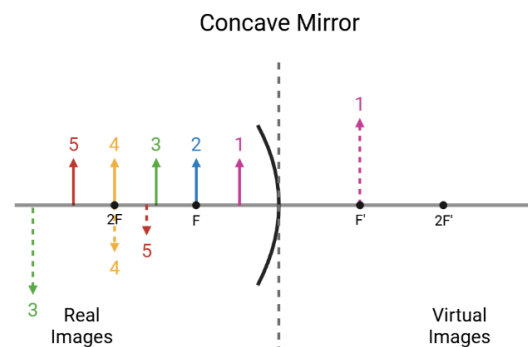
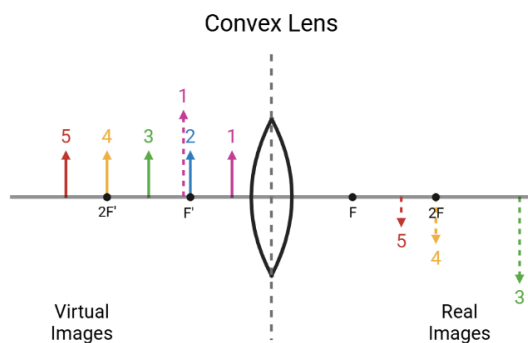
OPTICS		
	Formula	Notes
Index of Refraction	$n = \frac{c}{v}$	n = index of refraction of medium c = speed of light constant ( $c = 3 \times 10^8$ m/s) v = speed of light in medium (units: m/s)
Snell's Law	$n_1 \sin \theta_1 = n_2 \sin \theta_2$	$n_1$ = index of refraction, medium 1 $\theta_1$ = angle from normal, incident wave $n_2$ = index of refraction, medium 2 $\theta_2$ = angle from normal, refracted wave
Apparent Depth	$D_{\text{apparent}} = D_{\text{actual}} \left( \frac{n_2}{n_1} \right)$	$D_{\text{apparent}}$ = object's apparent depth (units: m) $D_{\text{actual}}$ = object's actual depth (units: m) $n_2$ = index of refraction, medium of observer $n_1$ = index of refraction, medium of object
Critical Angle	$\sin \theta_c = \frac{n_2}{n_1}$ For total internal reflection: $n_1 > n_2$	$\theta_c$ = angle from normal, incident wave $n_1$ = index of refraction, medium 1 $n_2$ = index of refraction, medium 2
Thin Lens Equation	$\frac{1}{o} + \frac{1}{i} = \frac{1}{f}$	o = objects distance from lens (units: cm, mm) i = image distance from lens (units: cm, mm) f = focal length (units: cm, mm)
Optical Power	$P = \frac{1}{f}$	P = power (units: D) f = focal length (units: <b>MUST</b> be in meters)
Magnification	$M = \frac{h_i}{h_o}$ $M = - \frac{i}{o}$ (+M) = <i>upright</i> image (-M) = <i>inverted</i> image	M = magnification $h_i$ = image height (units: cm, mm) $h_o$ = object height (units: cm, mm) o = object distance from lens (units: cm, mm) i = image distance from lens (units: cm, mm)
Image Height	$\frac{h_i}{h_o} = \frac{d_i}{d_o}$	$h_o$ = object height (units: cm, mm) $h_i$ = image height (units: cm, mm) $d_o$ = object distance from lens (units: cm, mm) $d_i$ = image distance from lens (units: cm, mm)
Focal Length (Spherical Mirrors)	$f = \frac{r}{2}$	f = focal length (units: cm, mm) r = radius of spherical mirror (units: cm, mm)

## Thin Lens & Mirrors Sign Conventions

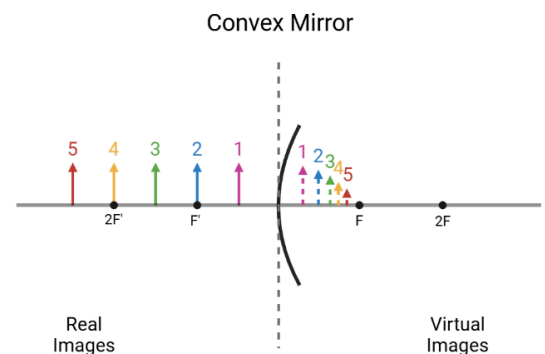
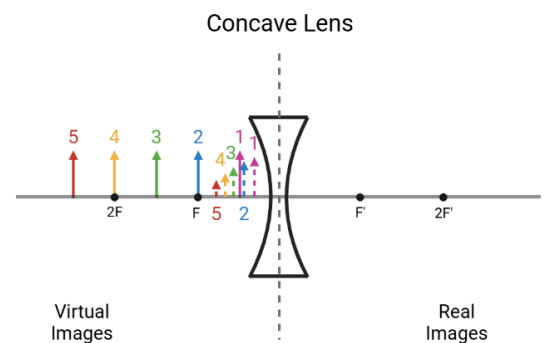
- $i (+)$  → real, inverted image formed on opposite side of lens or same side of mirror
- $i (-)$  → virtual, upright image formed on same side of lens or opposite side of mirror

	Focal Length (f)	Object Distance (o)	Image Distance (i)	Image Formed	Magnification (m)
<b>Converging Systems:</b> Convex Lens & Concave Mirror	f (+)	$o < f$	i (-)	<b>lens:</b> virtual, upright, in front of lens <b>mirror:</b> virtual, upright, behind mirror	magnified
		$o = f$	i (0)	No image	
		$o > f$	i (+)	<b>lens:</b> real, inverted, behind lens <b>mirror:</b> real, inverted, in front of mirror	$o > 2f$ : reduced $o = 2f$ : same size $f < o < 2f$ : magnified
<b>Diverging Systems:</b> Concave Lens & Convex Mirror	f (-)	$o < f$ , $o = f$ , $o > f$	i (-)	<b>lens:</b> virtual, upright, in front of lens <b>mirror:</b> virtual, upright, behind mirror	reduced

### Converging Systems



### Diverging Systems



↑ Object      ↑ Image

#### Notes:

- All of the objects in this diagram are real.
- For mirrors, real images are formed on the same side as the object.
- For lenses, real images are formed on the opposite side as the object.



THERMODYNAMICS		
	Formula	Notes
<b>Change in Internal Energy</b>	$\Delta U = Q + W$ Work done BY the system = (-W) Work done ON the system = (+W)	$\Delta U$ = change in internal energy (units: J) Q = heat added to system (units: J) W = work done by/on system (units: J)
<b>Pressure-Volume Work</b>	$W = -P\Delta V$ Work done BY the gas = (-W) Work done ON the system = (+W)	W = work done by/on gas (units: J) P = external pressure on gas (units: atm) $\Delta V$ = change in volume (units: L)
<b>Heat Energy Gained / Lost</b>	$Q = mC\Delta T$	Q = heat energy gained/lost (units: J) m = mass (units: g) C = specific heat capacity (units: J/g·°C) $\Delta T$ = change temperature (units: °C or K)
<b>Linear Thermal Expansion</b>	$\Delta L = \alpha L_0 \Delta T$	$\Delta L$ = change in object length (units: m) $L_0$ = original object length (units: m) $\alpha$ = linear expansion coefficient (units: °C <sup>-1</sup> ) $\Delta T$ = change in temperature (units: °C)
<b>Ideal Gas Equation</b>	$PV = nRT$	P = pressure (units: atm, Pa) V = volume (units: L, m <sup>3</sup> ) n = moles of gas (units: mol) T = absolute temperature (units: K) R = gas constant (L·atm/mol·K, J/mol·K)
	<u>Version 1</u> Use <b>R = 0.0821 L·atm/mol·K</b> when: <ul style="list-style-type: none"> <li>• solving for (P) in atm</li> <li>• solving for (V) in L</li> </ul>	<u>Version 2</u> Use <b>R = 8.31 J/mol·K</b> when: <ul style="list-style-type: none"> <li>• Solving for (P) in Pa</li> <li>• Solving for (V) in m<sup>3</sup></li> </ul>

DC CIRCUITS		
	Formula	Notes
<b>Voltage</b> (Ohm's Law)	$V = IR$	V = voltage (units: V) I = current (units: A) R = resistance (units: $\Omega$ )
<b>Power</b>	$P = IV = I^2R = \frac{V^2}{R}$	P = power (units: W) I = current (units: A) V = voltage (units: V) R = resistance (units: $\Omega$ )
<b>Current</b>	$I = \frac{q}{t}$	I = current (units: A) q = charge (units: C) t = time (units: s)
<b>Resistance</b> (of wire)	$R = \frac{\rho L}{A}$	R = resistance (units: $\Omega$ ) $\rho$ = resistivity constant (units: $\Omega \cdot m$ ) L = length of wire (units: m) A = area of wire (units: $m^2$ )
<b>Equivalent Capacitance</b> (Series Capacitors)	$\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots$	$C_{eq}$ = equivalent capacitance (units: F) $C_n$ = individual capacitance (units: F)
<b>Equivalent Resistance</b> (Series Resistors)	$R_{eq} = R_1 + R_2 + R_3 + \dots$	$R_{eq}$ = equivalent resistance (units: $\Omega$ ) $R_n$ = individual resistance (units: $\Omega$ )
<b>Equivalent Capacitance</b> (Parallel Capacitors)	$C_{eq} = C_1 + C_2 + C_3 + \dots$	$C_{eq}$ = equivalent capacitance (units: F) $C_n$ = individual capacitance (units: F)
<b>Equivalent Resistance</b> (Parallel Resistors)	$\frac{1}{R_{eq}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots$	$R_{eq}$ = equivalent resistance (units: $\Omega$ ) $R_n$ = individual resistance (units: $\Omega$ )
<b>Charge</b> (on a Capacitor)	$Q = CV$	Q = charge (units: C) C = capacitance (units: F) V = voltage differential (units: V)
<b>Energy</b> (in a Capacitor)	$E = \frac{1}{2}CV^2$	E = energy (units: J) C = capacitance (units: F) V = voltage differential (units: V)

ELECTROSTATICS		
	Formula	Notes
<b>Coulomb's Law</b>	$F = \frac{k q_1  q_2 }{x^2}$	F = electric force (units: N) k = Coulomb's constant ( $k = 9 \times 10^9 \text{ N}\cdot\text{m}^2/\text{C}^2$ ) q <sub>1</sub> = charge 1 magnitude (units: C) q <sub>2</sub> = charge 2 magnitude (units: C) x = distance between charges (units: m)
<b>Electric Field</b>	$E = \frac{F}{q}$	E = electric field strength (units: N/C or V/m) F = force (units: N) q = charge (units: C)
<b>Electric Field of a Point Charge</b>	$E = \frac{k q }{x^2}$  +q = direction of E is radially outwards -q = direction of E is radially inwards	E = electric field strength (units: N/C or V/m) q = point charge (units: C) k = Coulomb's constant of $9 \times 10^9$ (units: $\text{Nm}^2/\text{C}^2$ ) x = distance from point charge q (units: m)
<b>Electric Potential (Point Charge)</b>	$V = \frac{kq}{r}$	V = electric potential (units: V) q = charge (units: C) k = Coulomb's constant ( $k = 9 \times 10^9 \text{ N}\cdot\text{m}^2/\text{C}^2$ ) r = distance from source charge (units: m)
<b>Electric Potential Energy</b>	$\Delta U = q\Delta V$	$\Delta U$ = change in electric potential energy (units: J) q = charge (units: C) $\Delta V$ = change in electric potential (units: V)

Sine & Cosine		
Angle	Sin	Cos
0°	0	1
30°	1/2	$\sqrt{3}/2$
45°	$1/\sqrt{2}$	$1/\sqrt{2}$
60°	$\sqrt{3}/2$	1/2
90°	1	0