Arduino Coding Pre-Practical Assignment (Kieron Foo Kai-En)

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^{*}Table of contents is designed for easy access to the different code sections*

^{*}Some videos are uploaded onto youtube and some are on google drive as the video takes very long to process via google drive*

1. Hello World

```
Blink
 Turns an LED on for five seconds, then off for three second, repeatedly.
 Most Arduinos have an on-board LED you can control. On the UNO, MEGA and ZERO
 it is attached to digital pin 13, on MKR1000 on pin 6. LED BUILTIN is set to
 the correct LED pin independent of which board is used.
 If you want to know what pin the on-board LED is connected to on your Arduino
 model, check the Technical Specs of your board at:
 https://www.arduino.cc/en/Main/Products
 modified 8 May 2014
 by Scott Fitzgerald
 modified 2 Sep 2016
 by Arturo Guadalupi
 modified 8 Sep 2016
 by Colby Newman
 This example code is in the public domain.
 https://www.arduino.cc/en/Tutorial/BuiltInExamples/Blink
// the setup function runs once when you press reset or power the board
void setup() {
 // initialize digital pin LED_BUILTIN as an output.
 pinMode(9, OUTPUT);
// the loop function runs over and over again forever
void loop() {
 digitalWrite(9, HIGH); // turn the LED on (HIGH is the voltage level)
 delay(5000);
 digitalWrite(9, LOW); // turn the LED off by making the voltage LOW
```

```
delay(3000);  // wait for 3 seconds
}
```

Turns on LED Output - L9 for 5 seconds (HIGH) and off for 3 seconds (LOW), repeatedly.

To copy this code, head to Arduino IDE > Examples > 01.Basic > Blink

Delete the code and repaste sheet with this code. The code will play by itself once uploaded.

Video Evidence:

This is what the code should look like when played

https://drive.google.com/file/d/1d4r7c0aGRvHSgfB8wECKuoI98hmpwoGs/view?usp=sharing

2. Programmable Button Challenge

```
Input Pull-up Serial
Turns on LED for 5 blinks via programmed button, before turning off.
 This example demonstrates the use of pinMode(INPUT_PULLUP). It reads a digital
 input on pin 2 and prints the results to the Serial Monitor.
 The circuit:
 - momentary switch attached from pin 2 to ground
 - built-in LED on pin 13
 Unlike pinMode(INPUT), there is no pull-down resistor necessary. An internal
 20K-ohm resistor is pulled to 5V. This configuration causes the input to read
 HIGH when the switch is open, and LOW when it is closed.
 created 14 Mar 2012
 by Scott Fitzgerald
 This example code is in the public domain.
 https://www.arduino.cc/en/Tutorial/BuiltInExamples/InputPullupSerial
void setup() {
 //start serial connection
 Serial.begin(9600);
 //configure pin 2 as an input and enable the internal pull-up resistor
 pinMode(2, INPUT_PULLUP);
 pinMode(5, OUTPUT);
void loop() {
 //read the pushbutton value into a variable
 int sensorVal = digitalRead(2);
 //print out the value of the pushbutton
 Serial.println(sensorVal);
```

```
// Keep in mind the pull-up means the pushbutton's logic is inverted. It goes
// HIGH when it's open, and LOW when it's pressed. Turn on pin 13 when the
// button's pressed, and off when it's not:
if (sensorVal == HIGH) {
    digitalWrite(5, LOW);
} else {
    for (int i=0; i< 5; i++)
    {
        digitalWrite(5, HIGH);
        delay(500);
        digitalWrite (5, LOW);
        delay(500);
}
</pre>
```

Turns on and off (Blink) LED Output - L5 for 5 repetitions, before turning it off completely.

To copy this code, head over to Arduino IDE > Examples > 02.Digital > DigitalInputPullup

Delete and repaste the code sheet with the provided code and run.

The code will play via the pressing of the registered programmed button.

Video Evidence:

This is what the code should look like when played

https://www.youtube.com/shorts/yMgcxCTktPo

3. Make some noise!

```
Plays a melody when button is pressed.
  circuit:
 - 8 ohm speaker on digital pin 8
  created 21 Jan 2010
 modified 30 Aug 2011
 by Tom Igoe
 This example code is in the public domain.
 https://www.arduino.cc/en/Tutorial/BuiltInExamples/toneMelody
#include "pitches.h"
// notes in the melody:
int melody[] = {
 NOTE_C4, NOTE_G3, NOTE_G3, NOTE_A3, NOTE_G3, 0, NOTE_B3, NOTE_C4
};
// note durations: 4 = quarter note, 8 = eighth note, etc.:
int noteDurations[] = {
 4, 8, 8, 4, 4, 4, 4, 4
};
```

```
void setup() {
 //start serial connection
 Serial.begin(9600);
 //configure pin 2 as an input and enable the internal pull-up resistor
 pinMode(2, INPUT_PULLUP);
 pinMode(13, OUTPUT);
void loop() {
 //read the pushbutton value into a variable
 int sensorVal = digitalRead(2);
 //print out the value of the pushbutton
 Serial.println(sensorVal);
 // Keep in mind the pull-up means the pushbutton's logic is inverted. It goes
 // HIGH when it's open, and LOW when it's pressed. Turn on pin 13 when the
 if (sensorVal == HIGH) {
 } else {
     for (int thisNote=0; thisNote < 8; thisNote++) {</pre>
   // to calculate the note duration, take one second divided by the note type.
   //e.g. quarter note = 1000 / 4, eighth note = 1000/8, etc.
   int noteDuration = 1000 / noteDurations[thisNote];
```

```
tone(8, melody[thisNote], noteDuration);

// to distinguish the notes, set a minimum time between them.

// the note's duration + 30% seems to work well:

int pauseBetweenNotes = noteDuration * 1.30;

delay(pauseBetweenNotes);

// stop the tone playing:
noTone(8);
}
```

Plays a melody when button is pressed.

When the button is pressed, the Output pin - L8 lights up simultaneously as each sound melody is played.

This is hence, a programmable command button-operated melody player. (Piezo Buzzer)

To copy this code, using Arduino IDE > File > Examples > 02.Digital > toneMelody

Delete the "toneMelody.ido" section, and copy and paste this code to the application code sheet.

Leave "pitches.h" undisturbed.

Video Evidence:

This is what the code should look like when played

https://www.youtube.com/shorts/-c2kYzgSax0

4. Servo Challenge

```
by BARRAGAN <http://barraganstudio.com>
This example code is in the public domain.
modified 8 Nov 2013
by Scott Fitzgerald
https://www.arduino.cc/en/Tutorial/LibraryExamples/Sweep
#include <Servo.h>
Servo myservo; // create servo object to control a servo
// twelve servo objects can be created on most boards
int pos = 0;  // variable to store the servo position
void setup() {
 myservo.attach(9); // attaches the servo on pin 9 to the servo object
void loop() {
 for (pos = 20; pos <= 150; pos += 1) { // goes from 20 degrees to 150 degrees
   // in steps of 1 degree
                                  // tell servo to go to position in variable
   myservo.write(pos);
   delay(50);
                                   // waits 50 ms for the servo to reach the
position
 for (pos = 150; pos >= 20; pos -= 1) { // goes from 150 degrees to 20 degrees
   myservo.write(pos);
                                   // tell servo to go to position in variable
   delay(50);
position
 for (pos = 20; pos <= 150; pos += 1) { // goes from 20 degrees to 150 degrees
   // in steps of 1 degree
   myservo.write(pos);
                                   // tell servo to go to position in variable
 pos'
   delay(10);
                                   // waits 10 ms for the servo to reach the
position
 }
```

- Servo motor will move to position 20 degrees at start of code.
- From 20 degrees, servo motor moves slowly to 150 degrees
- From 150 degrees, servo motor moves slowly back down to 20 degrees
- From 20 degrees, servo motor immediately ramps up back to 150 degrees
- Sequence repeats.

To copy this code, head to Arduino IDE > Files > Examples > Servo > Sweep

Sweep.ino

Delete the example code and replace it with the attached code and upload to run code sequence.

readme.md

Leave undisturbed

Video Evidence:

This is what the code should look like when played

https://drive.google.com/file/d/1Xdt PAwVICrt nT9Ct6GGMY0vjvMIO0x/view?usp=sharing

5. Link to the Folder for all 4 Code Videos in Google Drive
https://drive.google.com/drive/folders/1FEtl4aLsS-vhxBamkhiN2ASaR0Uh0GjK?usp=sharing