

# **SYLLABUS**

**EC630202**

**SIGNALS AND SYSTEMS**

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## **COURSE OBJECTIVE:**

- To analyze the characteristics of continuous, discrete signals and systems.
- To characterize different transforms and their application in system analysis.
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- To characterize different transforms and their application in system analysis.
- To analyze the characteristics of continuous, discrete signals and systems.

## **COURSE OUTCOMES:**

After completing this course, the student will be able to:

CO1:Classify the Signals and Systems using properties.

CO2: Analyze any continuous time signals and systems using Fourier Methods.

CO3: Analyze the continuous time signals and systems using Laplace Transform. CO4:Analyze any discrete time signals and systems using DTFT and Z transforms CO5:Apply DFT effectively in signal analysis.

## **UNIT I CLASSIFICATION OF SIGNALS AND SYSTEMS**

**12**

Continuous time signals (CT signals) – discrete time signals (DT signals) – Step, Ramp, Pulse, Impulse, Exponential – Transformation of the independent variable – Classification of CT and DT signals – CT systems and DT systems – Basic system properties – Linear Time invariant (LTI) Systems and properties.

## **UNIT II FOURIER SERIES REPRESENTATION AND CT FOURIER TRANSFORM 12**

Fourier Series representation of CT periodic signals – Convergence of Fourier Series – Properties – Differential equation – Convolution integral – Properties – Impulse response of Interconnected systems – Fourier Transform Representation of an aperiodic signal – Convergence of Fourier Transforms – Properties – Analysis of LTI Systems using Fourier Transform – Impulse response – Frequency response.

### **UNIT III LAPLACE TRANSFORM**

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Laplace Transform – Region of Convergence for Laplace Transform – Inverse Laplace Transform – Unilateral Laplace Transform – Properties – Analysis of LTI Systems using Laplace Transform – Impulse response – State variable equations and matrix representation of systems.

### **UNIT IV DISCRETE-TIME FOURIER TRANSFORM AND Z TRANSFORM 12**

Difference equation – Convolution sum – Properties – Impulse response of Interconnected systems

– DTFT and properties. Z-Transform – Region of Convergence for Z-Transform – Inverse Z-

Transform –Unilateral Z-Transform –Properties – Analysis of LTI Systems using Z-Transform –

Impulse response – State variable equations and matrix representation of systems

### **UNIT V DFT & FFT**

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Discrete Fourier Transform (DFT) - deriving DFT from DTFT, properties of DFT - periodicity, symmetry, circular convolution. Fast computation of DFT - Radix-2 Decimation-in-time (DIT) Fast Fourier transform (FFT), Decimation- in-frequency (DIF) Fast Fourier transform (FFT). Linear filtering using FFT.

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### **TOTAL: 45 PERIODS TEXT BOOKS:**

1. Allan V.Oppenheim, S.Wilsky and S.H.Nawab, “Signals and Systems”, Pearson Education, 2007.
2. Robert A. Gabel and Richard A.Roberts, “Signals & Linear Systems”, 3rd Edition, John Wiley, 1987

### **REFERENCES:**

- 1.H P Hsu and RakeshRanjan,“ Signals and Systems, Schaum’s Outlines”, Tata McGraw Hill, 2007
- 2.S.Salivahanan, “Digital Signal Processing”, 3rd Edition, McGraw Hill International/TMH, 2015.
- 3.Simon Haykin and Barry Van Veen, “Signals and Systems” John Wiley &sons, Inc, 2004