

Heading Font Times New Roman of 14 Points On-Chip Center Aligned Wave-Pipelined Serial Interconnect (A sample Template of ccsn2023)

First Author, Second author, Third Author

Department names

National Institute of Technology, Tiruchirappalli – 620015, INDIA

xxjyyr@yyyv.edu, xxsrighantasa23@gmail.com, xxbvehjnki@xxx.edu

ABSTRACT

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Keywords: Controllable inverter pair, Differential interconnect, Method of logical effort, Repeater insertion, Self controllable, Serial link, Surfing, Wave-pipelining.

I. INTRODUCTION

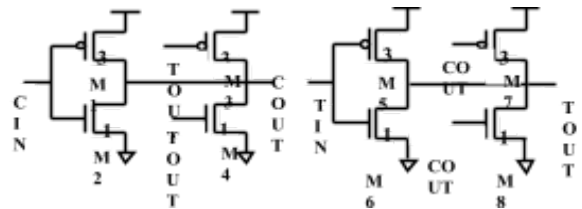
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XxxThe paper is organized as follows: Section II, III describe the design of... Section V provides the post layout simulation results and the observations. The concluding remarks are given in Section VIxxx.

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(a) (b)
Fig. 1. Dynamic Self Controllable inverter pair
a) Surfing circuit for complement path b) Surfing circuit for true data path.

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xxThe absolute delay (D) of a circuit consisting of N stages is given by [4]XX.

$$D = (N F^{1/N} + P) \tau \quad (1)$$

where,

F - path effort

P - parasitic delay of the path (sum of parasitic delay of each stage)

τ - technology constant (12ps for 180nm)

$$T_p = 0.69 \left[R_b C_{b0ntt} + \frac{R_b}{f} \cdot f C_b + \dots + \frac{R_b}{f^{N-1}} \cdot f^{N-1} C_b \right] \\ + 0.69 \frac{R_b C_w}{L} \left[a + \frac{ar}{f} + \frac{ar^2}{f^2} + \dots + \frac{ar^{N-1}}{f^{N-1}} \right] \\ + 0.69 \frac{R_w C_w}{L} \left[a + arf + ar^2 f^2 + \dots + ar^{N-1} f^{N-1} \right]$$

$$+ 0.38 \frac{R_w C_w}{L^2} \left[a^2 + a^2 r^2 + a^2 r^4 + \dots + a^2 r^{2(N-1)} \right] \quad (2)$$

III. RESULTS and DISCUSSIONS

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TABLE I
DELAY AND POWER OF THE INTERCONNECT WITH NUR FOR DIFFERENT INTERCONNECT RATIO

Ratio of interconnect segments (r)	Delay of the longest segment in NUR(ps)		Max. operating frequency in Gb/s	
	In [15]	This paper	In [15]	This paper
2.00	643.0	384.6	1.55	2.60
3.00	366.0	340.0	2.73	2.94

Results can be expressed as Fig-2

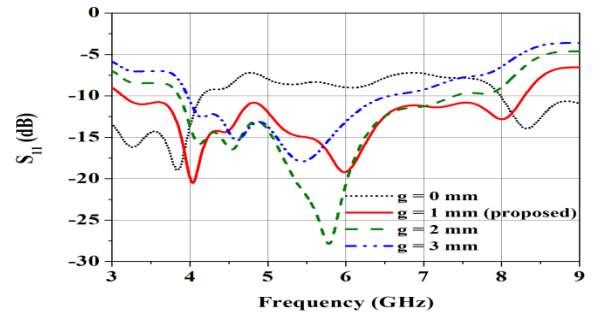


Fig. 2. S_{11} Bandwidth comparison for different values of the gap 'g'

IV. CONCLUSION

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