



# Yashoda Technical Campus, Satara

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**A.Y: 2024-25 (Sem- II)**

**Class: FY – Mtech. CSE**

**Course code and Name: MTCSEPE203C Program Elective-II**

**Distributed System Principle**

**Course Coordinator: Dr. S V Balshetwar**

**Unit-III: 3 Marks Questions**

◆ **Q1 (Level 3 – Apply):**

**Apply the Ricart-Agrawala algorithm to explain how three processes coordinate access to the critical section.**

**Solution:**

Each process sends a REQUEST message with its timestamp to the other two.

- A process enters its **critical section (CS)** only after receiving REPLY messages from both.
  - After exiting the CS, it sends REPLY to any pending requests.  
This ensures mutual exclusion using **timestamp-based ordering** and **direct communication**.
- 

◆ **Q2 (Level 3 – Apply):**

**Apply token-based mutual exclusion in a ring topology with 4 processes. Describe how token passing ensures exclusive access.**

**Solution:**

- The token circulates among  $P1 \rightarrow P2 \rightarrow P3 \rightarrow P4 \rightarrow P1$ .
  - A process enters the CS **only when it holds the token**.
  - If a process doesn't need the CS, it simply forwards the token.  
This ensures only one process accesses the CS at any time (mutual exclusion).
- 

◆ **Q3 (Level 3 – Apply):**

**Apply the concept of performance metrics to evaluate a mutual exclusion algorithm with high message overhead.**

**Solution:**

- Analyze message complexity (e.g., Ricart-Agrawala uses  $2*(n-1)$  messages).



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- High message count increases **network traffic** and **latency**.
  - Suggest a **token-based algorithm** with fewer messages per CS entry (1 message/token).
- 

#### ♦ Q4 (Level 4 – Analyze):

Analyze the drawbacks of centralized mutual exclusion when the coordinator crashes.

**Solution:**

- The coordinator is a **single point of failure**.
  - When it crashes, all processes are **blocked from entering CS**.
  - Recovery is non-trivial—requires **new coordinator election** and **state restoration**. This limits reliability and fault tolerance.
- 

#### ♦ Q5 (Level 4 – Analyze):

Analyze and compare fairness in Ricart-Agrawala vs Token Ring algorithms.

**Solution:**

- **Ricart-Agrawala**: Ensures fairness through **timestamp comparison**, processes with earlier requests are prioritized.
  - **Token Ring**: Provides fairness via **round-robin scheduling**, but can delay access if token travels long.
  - Both prevent starvation but differ in latency and message usage.
- 

#### ♦ Q6 (Level 4 – Analyze):

A distributed system experiences delays in entering CS. Analyze which performance metric is being affected and why.

**Solution:**

- The affected metric is **Synchronization Delay**.
- Causes may include **network latency**, **message processing time**, or **high contention** for CS.



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- Performance is impacted as processes **wait longer** despite fairness being maintained.
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#### Unit II- 3 marks Question

##### ♦ Q1 (Level 3 – Apply):

Apply Lamport's logical clock rules to the following events and assign logical timestamps:

- P1: e1, e2
- P2: f1, f2
- Message m is sent from e2 to f2.

**Solution:**

- P1: e1 = 1, e2 = 2
- Message m sent from e2 = 2
- On receiving m, P2 updates clock: f2 = max(clock at f1 + 1, received timestamp + 1)
- If f1 = 1, then f2 = max(2, 3) = 3

**Timestamps:**

- e1 = 1, e2 = 2
  - f1 = 1, f2 = 3
- 

##### ♦ Q2 (Level 3 – Apply):

Apply vector clocks to determine causality. Given:

- VC(A) = [2, 0], VC(B) = [1, 1]  
Determine if the events are causally related or concurrent.

**Solution:**

Compare element-wise:

- [2, 0] vs [1, 1] → A > B in first element, A < B in second  
→ No total ordering

**Conclusion:** Events are **concurrent**

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#### ◆ Q3 (Level 3 – Apply):

Apply the concept of physical clocks in synchronizing distributed systems using Cristian's algorithm. Describe the basic idea.

##### Solution:

- A client requests time from a time server
  - Server replies with its time
  - Client adjusts local clock = server\_time +  $\frac{1}{2}(\text{RTT})$
  - Assumes symmetric delay
- Used to **synchronize physical clocks** in distributed systems.
- 

#### ◆ Q4 (Level 4 – Analyze):

Analyze how Lamport's logical clocks fail to capture causality completely.

##### Solution:

- Lamport timestamps ensure **happened-before relation** (if  $a \rightarrow b$ , then  $L(a) < L(b)$ )
  - But  $L(a) < L(b)$  doesn't imply  $a \rightarrow b$
  - Can't distinguish **concurrent events**
- Thus, Lamport clocks **preserve order but not causality**.
- 

#### ◆ Q5 (Level 4 – Analyze):

Analyze how vector clocks solve the limitations of Lamport clocks.

##### Solution:

- Vector clocks use a **vector of counters**, one per process
  - Allow detection of **causal relationships** by comparing vectors element-wise
  - Can distinguish between  $a \rightarrow b$  and  $a \parallel b$  (concurrent)
- Hence, vector clocks are more expressive for causality tracking.
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#### ◆ Q6 (Level 4 – Analyze):

Analyze how the Chandy-Lamport algorithm ensures a consistent global state in a distributed system.

**Solution:**

- **Marker messages** are used to initiate snapshot
  - Each process records its state and the **state of incoming channels**
  - Messages in transit are captured
- This guarantees a **consistent global snapshot** without stopping the system.
- 

### Unit -I - 3 marks Question

#### ◆ Q1 (Level 3 – Apply):

Apply your understanding of RISC and CISC architectures to justify which one is better suited for real-time embedded systems.

**Solution:**

- RISC uses a **smaller set of simple instructions** that execute faster.
  - It has **faster instruction execution and lower power consumption**.
  - For real-time systems requiring speed and predictability, **RISC is more suitable**.
- 

#### ◆ Q2 (Level 3 – Apply):

Apply the OSI model to explain which layers are involved when a user accesses a website using a browser.

**Solution:**

- **Application Layer:** Handles HTTP requests.
  - **Transport Layer:** Ensures reliable delivery (TCP).
  - **Network Layer:** Handles IP addressing and routing.
- These layers work together to **deliver and manage web content to the user**.



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#### ◆ Q3 (Level 3 – Apply):

Apply the concept of multi-core processing to explain how distributed applications can achieve better performance.

**Solution:**

- Multi-core processors enable **parallel execution of threads**.
  - Distributed applications can be divided into tasks that run concurrently.
  - This leads to **faster execution and resource optimization**.
- 

#### ◆ Q4 (Level 4 – Analyze):

Analyze how the evolution of operating systems has contributed to the development of distributed systems.

**Solution:**

- Early OSes were single-user and single-tasking.
  - Modern OSes support **multiprocessing, networking, and virtualization**.
  - This evolution allows **process migration, remote execution, and resource sharing**—key for distributed systems.
- 

#### ◆ Q5 (Level 4 – Analyze):

Analyze how different types of transparency improve user experience in a distributed computing system.

**Solution:**

- **Location transparency:** Users access resources without knowing their location.
- **Access transparency:** Same operations for local and remote resources.
- **Failure transparency:** System recovers from failures without user intervention. These transparencies provide a **seamless and consistent user experience**.



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#### ◆ Q6 (Level 4 – Analyze):

Analyze the fundamental design goals of distributed systems and explain how they affect system performance.

#### Solution:

- **Scalability:** Ensures the system handles growth.
  - **Fault tolerance:** Maintains operation despite failures.
  - **Resource sharing:** Improves efficiency.
- Meeting these goals enhances **availability, reliability, and responsiveness** of distributed systems.
- 

### Unit III -8 marks question

#### ◆ Q1 (Level 3 – Apply):

**Q:** Apply the Ricart-Agrawala algorithm for mutual exclusion to a system of 3 processes (P1, P2, P3). Show how P2 gains access to the critical section and how messages are exchanged.

#### Solution:

1. **P2 wants to enter the critical section:**
  - It timestamps the request and sends it to P1 and P3.
2. **P1 and P3 receive the request:**
  - If not interested or P2's timestamp is earlier, they send **REPLY** to P2.
  - If they are also requesting the CS, they compare timestamps and may defer reply.
3. **P2 enters the CS** only after receiving **REPLY from both P1 and P3**.
4. After completing its CS, P2 sends any **deferred REPLY messages** to others.

#### Messages exchanged:

- 2 REQUESTs from P2
  - 2 REPLYs to P2
- ➡ **Total: 4 messages** (for P2 to enter CS)



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#### ◆ Q2 (Level 4 – Analyze):

**Q:** Analyze the trade-offs between token-based and permission-based distributed mutual exclusion algorithms. Provide a comparative table and discuss performance metrics.

**Solution:**

Feature	Token-Based	Permission-Based (e.g., Ricart-Agrawala)
Messages per CS entry	1 (token passing)	2(n-1) request/reply messages
Fairness	Fair (token circulates)	Fair (based on timestamps)
Fault Tolerance	Token loss = recovery needed	Coordinator/process crash affects replies
Synchronization Delay	Low	Medium to High
Starvation	Prevented if token circulates	Prevented if processes respond fairly

- **Analysis:**

- **Token-based** is efficient under low contention.
- **Permission-based** is better if message loss is rare and requires no token recovery.
- Choice depends on network reliability and number of processes.

#### ◆ Q3 (Level 4 – Analyze):

**Q:** Analyze the performance of centralized, token-based, and Ricart-Agrawala mutual exclusion algorithms using metrics like message complexity, delay, fault tolerance, and scalability.

**Solution:**

Algorithm	Msgs per Entry	Delay	Fault Tolerance	Scalability
Centralized	3	Low	Poor (single point fail)	Moderate
Token-Based	1	Low	Needs token recovery	High



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Algorithm	Msgs per Entry	Delay	Fault Tolerance	Scalability
Ricart-Agrawala	$2(n-1)$	Medium	Better than centralized	Limited by n

- **Conclusion:**

- **Centralized:** Simple, low overhead, but not fault-tolerant.
- **Token-Based:** Scales well but needs token management.
- **Ricart-Agrawala:** Reliable in permission-based systems, but more message-heavy.

- ◆ **Q4 (Level 3 – Apply):**

**Q:** Apply the concept of performance metrics to evaluate a distributed mutual exclusion algorithm in a system of 5 processes. Consider metrics: message complexity, response time, and synchronization delay.

**Solution:**

Assume the use of **Ricart-Agrawala algorithm:**

- **Message Complexity** =  $2(n-1) = 2 \times 4 = 8$  messages per CS entry
- **Response Time** depends on message delay + queue wait → Higher under load
- **Synchronization Delay** = Time to receive all REPLY messages  
→ Delay increases with **network latency and contention**

**Evaluation:**

- Efficient in small systems
- Message overhead grows with n
- Not ideal for high-frequency CS access or large networks

**Conclusion:** Use token-based or quorum-based algorithms when system scales or latency becomes critical.

### Unit -II 8 marks question

- ◆ **Q1 (Level 3 – Apply):**



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**Q:** Apply Lamport's logical clock algorithm to a system of 3 processes (P1, P2, P3) with the following events:

- P1:  $a \rightarrow b \rightarrow$  sends m1 to P2
- P2:  $c \rightarrow$  receives m1  $\rightarrow d \rightarrow$  sends m2 to P3
- P3: receives m2  $\rightarrow e$

Assign Lamport timestamps to each event.

#### **Solution:**

#### **Lamport's Rules:**

1. Increment local clock before each event.
2. On receiving a message, set clock =  $\max(\text{local}, \text{received}) + 1$ .

#### **Step-by-step:**

- P1:
  - $a = 1$
  - $b = 2$
  - send m1 = 3
- P2:
  - $c = 1$
  - receive m1  $\rightarrow \max(1, 3) + 1 = 4$
  - $d = 5$
  - send m2 = 6
- P3:
  - receive m2  $\rightarrow \max(0, 6) + 1 = 7$
  - $e = 8$

#### **Final Timestamps:**

- P1:  $a=1, b=2, \text{send}=3$
  - P2:  $c=1, \text{receive}=4, d=5, \text{send}=6$
  - P3:  $\text{receive}=7, e=8$
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#### ◆ Q2 (Level 4 – Analyze):



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**Q:** Analyze the differences between Lamport clocks and vector clocks in capturing causal relationships. Give an example to justify your answer.

**Solution:**

Feature	Lamport Clocks	Vector Clocks
Type	Scalar	Vector (size = number of processes)
Ordering Capability	Partial ( $a \rightarrow b \Rightarrow L(a) < L(b)$ )	Total (can detect concurrency)
Causal Relationship	Cannot detect concurrency	Can detect both causal and concurrent events

**Example:**

Let P1 send to P2 and P3 perform independent events.

- Lamport:
  - P1:  $a = 1$ , send  $m1 = 2$
  - P2: receive  $m1 = 3$
  - P3:  $e = 2$
  - $L(e) = 2$ ,  $L(\text{receive}) = 3 \rightarrow L(e) < L(\text{receive}) \rightarrow$  falsely assumes  $e \rightarrow$  receive
- Vector:
  - P1 VC:  $[1, 0]$
  - P2 after receiving:  $[1, 1]$
  - P3 VC:  $[0, 0, 1]$
  - $VC(P3) \text{ not } \leq VC(P2) \rightarrow$  events are **concurrent**

Vector clocks provide **more accurate causal tracking** than Lamport clocks.

◆ **Q3 (Level 3 – Apply):**

**Q:** Apply Chandy-Lamport's snapshot algorithm to record a consistent global state in a system with 3 processes communicating over channels. Explain the steps and state how channel messages are handled.

**Solution:**

**Steps:**



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1. **Initiator** records local state and sends **marker** to all outgoing channels.
2. On receiving a **marker** for the first time:
  - o Record local state
  - o Send marker to other outgoing channels
  - o Start recording messages on other incoming channels
3. On receiving **subsequent markers**:
  - o Stop recording that channel
  - o Messages recorded between receiving the first marker and subsequent marker are considered **in-transit**

#### Application:

- P1 initiates snapshot
- Records its state
- Sends markers to P2, P3
- P2 and P3 record local states and start recording incoming messages until they receive marker on all channels.

Snapshot represents a **consistent global state** including in-transit messages.

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#### ◆ Q4 (Level 4 – Analyze):

**Q:** Analyze the use of physical clocks in distributed systems. How do synchronization algorithms (e.g., Cristian's or Berkeley's) address clock drift and skew?

#### **Solution:**

##### **Issues with Physical Clocks:**

- **Clock skew:** Difference in clock times among systems
- **Clock drift:** Clocks run at slightly different speeds
- Causes inconsistencies in timestamps, logs, and event ordering

##### **Cristian's Algorithm:**

- Client requests time from time server
- Adjusts for estimated network delay
- Limited by **network latency asymmetry**



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#### Berkeley's Algorithm:

- Master polls all clocks
- Computes average
- Sends adjustments to all nodes
- Works well in systems without external reference (e.g., no GPS)

#### Conclusion:

- Synchronization minimizes skew
  - Physical clocks alone are unreliable
  - These algorithms **approximate a global clock** essential for coordination
- 

### Unit I - 8 marks question

#### ◆ Q1 (Level 3 – Apply):

**Q:** Apply your understanding of CISC and RISC architectures to compare their performance in distributed computing environments. Provide real-world examples where applicable.

#### **Solution:**

- **CISC (Complex Instruction Set Computing):**
    - Uses **complex instructions** that execute multiple tasks in a single instruction.
    - Example: x86 architecture used in traditional desktop systems.
    - Suitable for systems with limited memory but high instruction flexibility.
  - **RISC (Reduced Instruction Set Computing):**
    - Uses **simple, uniform instructions** that execute quickly.
    - Example: ARM architecture used in mobile and embedded devices.
    - Favoured in distributed systems requiring **speed, power efficiency, and parallelism**.
  - **Application in Distributed Systems:**
    - **RISC** processors in edge devices and IoT nodes.
    - **CISC** may be used in backend servers with complex computational needs.
    - **RISC** is preferred where **low latency and high throughput** are critical.
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#### ◆ Q2 (Level 3 – Apply):



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**Q:** Apply the ISO/OSI model to explain how communication occurs in a distributed file-sharing application. Identify the relevant layers and their roles.

**Solution:**

In a distributed file-sharing system, layers involved:

1. **Application Layer:**
  - o Interfaces with the user and application (e.g., HTTP, FTP).
  - o Manages file requests and responses.
2. **Presentation Layer:**
  - o Handles **data encoding**, compression, and encryption.
3. **Session Layer:**
  - o Manages **sessions and connections** between nodes.
4. **Transport Layer:**
  - o Ensures **reliable data delivery** (e.g., TCP), error recovery.
5. **Network Layer:**
  - o Provides **routing and logical addressing** (e.g., IP).
6. **Data Link Layer:**
  - o Handles **frame creation**, MAC addressing, error detection at link level.
7. **Physical Layer:**
  - o Transmits raw bits via cables, wireless signals.

**Conclusion:**

The ISO/OSI model ensures **modular, reliable, and scalable communication** in distributed systems.

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◆ **Q3 (Level 4 – Analyze):**

**Q:** Analyze how the evolution of operating systems has supported the development of distributed systems. Include key milestones and their impact.

**Solution:**

Evolution Stage	Contribution to Distributed Systems
<b>Batch Systems</b>	Limited – no interactivity or resource sharing
<b>Multiprogramming</b>	Allowed multiple processes – essential for concurrency
<b>Time-Sharing Systems</b>	Enabled <b>remote login</b> , basic <b>networking features</b>
<b>Network OS</b>	Added support for <b>communication between systems</b>
<b>Distributed OS</b>	Provided <b>single-system image, resource transparency</b>



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#### Impact:

- OS now supports **remote process execution, file sharing, inter-process communication (IPC)**.
- Modern OS (e.g., Linux, Windows Server) includes **thread libraries, socket APIs, and virtualization** tools critical for distributed computing.

#### Conclusion:

OS evolution from standalone execution to **networked and distributed operation** has been central to enabling today's distributed systems.

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#### ◆ Q4 (Level 4 – Analyze):

**Q:** Analyze the design goals and transparency types in distributed computing systems. How do they contribute to system performance and user experience?

#### Solution:

##### Design Goals of Distributed Systems:

- **Transparency:** Hide system complexity.
- **Openness:** Standard interfaces, interoperability.
- **Scalability:** Ability to grow (e.g., horizontally).
- **Fault Tolerance:** Continue service despite failures.
- **Resource Sharing:** Maximize hardware/software utilization.

##### Types of Transparency:

Type	Description
<b>Location</b>	Hide where resources are located
<b>Access</b>	Uniform access to local/remote resources
<b>Replication</b>	Users unaware of resource duplication
<b>Concurrency</b>	Multiple users can access same resources
<b>Failure</b>	System masks failure recovery
<b>Migration</b>	Resources/processes move without affecting performance

##### Contribution to Performance/User Experience:

- **Improved usability** through seamless access.

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- **Increased reliability** by masking failures.
  - **Optimized performance** through load balancing and replication.
-