

Catalog of Benchmarks, Software, and Datasets for the DUNE Project's Fast Machine Learning Initiatives from Gemini

1. Introduction

The Deep Underground Neutrino Experiment (DUNE) stands as a leading international endeavor in the field of neutrino science, aiming to unravel fundamental questions about neutrino oscillations, the potential for proton decay, and the characteristics of supernova neutrinos. The experiment's design incorporates massive liquid argon time projection chamber (LArTPC) detectors, which are expected to generate an unprecedented volume of data requiring advanced computational methods for effective analysis¹. In this context, machine learning (ML) has become an increasingly vital tool in high-energy physics, offering solutions for a wide array of tasks, including the crucial areas of real-time event triggering, precise particle identification, accurate track reconstruction, and efficient reduction of background noise³.

This report provides a systematic catalog of the benchmarks, software artifacts, and datasets that are associated with the Fast Machine Learning (FastML) efforts within the DUNE project, based on the provided research materials. The primary objective is to create a well-structured and detailed resource that outlines the key ML-related developments, available resources, and their measured performance metrics. This compilation aims to enhance understanding and facilitate collaboration within the DUNE research community and among interested parties in the broader scientific landscape. The information presented herein is exclusively derived from the provided URLs and their content, which includes presentation slides and any linked resources referenced within those materials. The methodology employed involves a thorough extraction of all mentions of benchmarks, software, and datasets, along with their corresponding descriptions, application areas, and pertinent technical specifications. This extracted information is then organized into a tabular format to address the user's request for an Excel spreadsheet representation.

2. Detailed Catalog of DUNE Artifacts

This section presents a comprehensive catalog of the benchmarks, software, and datasets identified within the research materials. The information is structured in a table to offer a clear and organized overview, directly addressing the user's requirement for an Excel spreadsheet format. Each row in the table represents a distinct artifact, with the columns detailing the specific attributes requested in the user query.

DUNE FastML Artifact Catalog

Artifact Name	Description	Application Field	Nature of Model	Is model Deep Learning or not ?	Size of model	Nature of Data	Modality of Data	Size of Data with units	Nature of benchmarks with machines used	Links to Papers	Links to data and software (GitHub)
NVIDIA Triton	An online inference framework.	Fast AI/ML inference in DUNE Data Acquisition.	Used to query a server containing pre-loaded models .	Yes (serves deep learning models)	Not detailed.	Can process data in a format read by DUNE DAQ or reformatted data.	Not detailed.	Not detailed.	Testing inference rate with a "simple" model (adds two vectors) . Observed increasing inference	Non mentioned .	Non mentioned .

									ce time with mor e req uest s. Mac hine s use d not spe cifie d.		
Nu Son ic fra me wor k	A fra me wor k impl em ent ed by Mik e Wa ng et al.	Wor ked in LAr Soft for DU NE.	Not det aile d.	Not det aile d.	Not det aile d.	Rea ds dat a in a for mat use d by LAr Soft .	Not det aile d.	Not det aile d.	Not det aile d.	Non e me ntio ned in this doc um ent.	Me ntio ned as wor king in the larr eco dnn rep osit ory.
DU NE DA Q	A coll ecti on of cma ke pac kag es ma	Dat a acq uisit ion for the Dee p Und ergr	Aim s to inte grat e onli ne infe ren ce usin	Not appl icab le.	Not appl icab le.	Rea ds raw dat a as "fra mes " (64 time tick	Ra w det ecto r sign als.	Not det aile d.	Cur rent ly testi ng Trit on with fake dat a	Non e me ntio ned .	Non e me ntio ned in this doc um ent.

	naged by Spark, an independent data acquisition system for DUNE.	ound Neuro Experiment.	g models trained on its data format.			s x 64 channels), processed into TPs, "activities," and "candidates." TPs and Trigger Records written to HDF5. Can use configurable "fake data" trigger with TP generation			(HSL with 3 readout elements ~12 kHz of TPs), sending requests to a "simple" model every 100 TPs (~0.10) inference requests per second, each taking ~3		
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						for testi ng.			ms) . Mac hine s use d not fully spe cifie d (like ly stan dar d serv er har dwa re for Trit on).		
DUNE Near Detector (ND) data	Data from the near detec tor at Fermi lab.	Long-b aseline neutrino oscillation experiment.	Models will eventually be trained on this data.	Not applicab le.	Not applicab le.	Not fully detectable.	Not detectable.	Not detectable.	Data rates in Iceberg (DUNE cold electronics test stand at Fermi lab) are a	Non e men tioned .	Non e men tioned .

									subject of future work.		
DUNE Far Detector (FD) data	Data from the far detector at SURF.	Long-baseline neutrino oscillation experiment.	Models will eventually be trained on this data.	Not applicable.	Not applicable.	Liquid argon time projection chamber (LArTPC) technology.	Detector signals.	Not detected.	Not detected.	Non mentioned.	Non mentioned.
ProDUNE-S P data	Data from the ProDUNE-S P detector at CERN.	Testing LArTPC technology for DUNE.	Models can be trained on this data.	Not applicable.	Not applicable.	Liquid argon time projection chamber (LArTPC) technology.	Detector signals.	Raw trigger records were around 75 MB compressed.	Not detected.	Non mentioned.	Non mentioned.
2D	A	Eve	Con	Yes.	19,	Initi	Ima	Not	Perf	Non	Non

CNN for radiological background rejection	2D Convolutional Neural Network.	threshold trigger to reject frames containing only radiological background on raw data.	convolutional Neural Network.		750 parameters.	ally simulated in LArSoft for raw data readout, now developing datasets and training techniques to perform inference on TP based images.	ges derived from detector signals.	detected.	performance on simulated data: 99.42% signal efficiency, 99.69% background rejection. GPU inference time for optimal batch: 80 us per image. FPGA inference	mentioned.	mentioned.
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									ce time : 850 us per eve nt. Res our ce usa ge on FP GA: LUT : 5.2 2%, BR AM: 18. 95 %, Reg ister : 4.2 6%, DS P: 8.1 7*. Mac hine s use d: GP U and FP GA.		
Neu	A	Ide	Loc	No	Not	Not	Not	Not	AU	Non	Non

trino Interaction Identification (LBP+ Dense)	model using Local Binary Patterns (LBP) and a dense layer.	identifying neuron interactions for superovulation.	al Binary Patterns (LBP) and a dense neural network.	(LBP is feature engineering).	detailed.	yet implemented in LArSoft.	detailed.	detailed.	C: 0.85, 83% eES -> eES. GPU and FPGA inference times not measured or implemented in this context.	mentioned.	mentioned.
1D CNN for finding Region of Interest (ROI)	A 1D Convolutional Neural Network.	Finding regions of interest in the data.	Convolutional Neural Network.	Yes.	Not detailed.	The ROI looks similar to "trigger primitives" (TP	1D signal data.	Not detailed.	Not detailed.	Mentioned in the context of a presentation by Mike	Non mentioned.

						s).				Wa ng.	
1D Aut oen cod er for den oisi ng	A 1D Aut oen cod er.	Den oisi ng dat a.	Aut oen cod er.	Yes.	Not det aile d.	Use d for elec tron ics nois e red ucti on.	1D sign al dat a.	Not det aile d.	~69 % pri mar y trac k effic ienc y, ~99 % bac kgr oun d reje ctio n. GP U infe ren ce time : 0.0 61 sec/ nuC C eve nt, 0.0 31 sec/ eES eve nt. Mac hine use d:	Me ntio ned in the cont ext of a pre sent atio n by Mik e Wa ng and J. Mitr evs ki's Fas t ML talk fro m 202 3.	Non e me ntio ned .

									GP U.		
Spa ck	A pac kag e ma nag er use d to ma nag e DU NE DA Q.	Ma nag em ent of soft war e dep end enci es for DU NE DA Q.	Not appl icab le.	Not appl icab le.	Not appl icab le.	Not appl icab le.	Not appl icab le.	Not appl icab le.	Not appl icab le.	Non e me ntio ned .	Non e me ntio ned .
LAr Soft	Soft war e use d for sim ulati on and rec onst ructi on in liqui d arg on TP C exp eri me	Offli ne mo del dev elop me nt and sim ulati on for DU NE.	Use d for initi al dev elop me nt and sim ulati on of the 2D CN N.	Not appl icab le.	Not appl icab le.	Rea ds raw dat a in its own for mat .	Det ecto r sign als.	Not det aile d.	Initi al sim ulati ons of the 2D CN N wer e perf orm ed in LAr Soft .	Non e me ntio ned .	Non e me ntio ned in this doc um ent.

	nts.										
CNN for neutrino interaction classification	A Convolutional Neural Network.	Neutrino interaction classification in the DUNE far detector.	Convolutional Neural Network.	Yes.	Not fully detailed.	Data from the DUNE far detector, which utilizes liquid argon time projection chamber (LArTPC) technology. Supernova neutrino interactions appear as	Detector signals.	Not detailed.	Capable of exceeding its design sensitivity on simulated data. Machines used not specified.	Abi et al. (2020a), "Neutrino interaction classification with a convolutional neural network in the DUNE far detector"; Abi (2020), "Deep Underground Neu	Not mentioned in this snippet.

						small (tens of cm spatial scale).				trino Experiment (DUNE) Far Detector Technical Design Report, Volume II DUNE Physics".	
Machine learning in DUNE's triggering framework	Machine learning techniques.	Triggering system for DUNE.	Not specified.	Potentially Yes.	Not detailed.	Data from the liquid argon time projection chamber.	Detector signals.	Not detailed.	Not detailed.	Ongoing efforts related to real-time event selection and reconstruction	Not mentioned in this snippet.

										ructi on in neu trin o det ecto rs, incl udin g DU NE, with ass ocia ted pap ers liste d in the refe ren ces of the artic le.	
GAr Soft	An art- bas ed soft war e suit e use d to sim ulat e the	Sim ulati on and rec onst ructi on of eve nts in gas eous	Incl ude s sim ulati on of ioni zati on and scin tillat ion, elec	No.	Not det aile d.	Can imp ort ene rgy depo sits fro m ede p-si m.	Sim ulat ed part icle inte racti ons.	Not det aile d.	Not det aile d.	Not expl icitl y me ntio ned in the text.	Not expl icitl y me ntio ned in the text.

	ND-GAr detector.	argon time-projection chamber (GArTPC) detectors.	electron drift with diffusion and attenuation, and models of anomalous depolarizations (IROCs and OROCs).								
learn-d-sim	ND-LAr detector simulation software written entirely in Python and compiled	Simulation of the ND-LAr (pixel readout LArTPC) detector.	Takes into account quenching and drifting effects for ionization electrons in	No.	Not detailed.	Takes energy deposits from edep-sim as input (converted to HD F5	Simulated particle interactions.	Not detailed.	Not detailed.	Not explicitly mentioned in the text.	Not explicitly mentioned in the text.

	d on the GP U usin g Nu mb a for CU DA.		liqui d arg on and calc ulat es the curr ent indu ced on pixe ls. Sim ulat es elec tron ics res pon se and pho ton det ecti on usin g a GP U-o ptim ized look up tabl e.			for mat) and sav es out put in HD F5 for mat .					
ede p-si m	A Gea nt4- bas	Sim ulati ng part	Bas ed on Gea	No.	Not det aile d.	Out puts RO OT	Sim ulat ed part	Not det aile d.	Not det aile d.	Not expl iciti ly	Not expl iciti ly

	ed model used to propagate particles through the near detectors.	icle propagation and energy deposition in the near detector components.	nt4.			tree s with energy deposit information and associated truth labels.	icle interactions.			mentioned in the text.	mentioned in the text.
Wire-Cell Toolkit (WCT)	Used for detailed 2D modeling of wire responses in wire-based LArTPCs.	Signal processing and reconstruction in wire-based LArTPCs.	Includes effects of induced currents on neighboring wires and folds in the electronics	No.	Not detailed.	Takes signal waveforms as input and produces a 3D model of ionization distribution	Detector signals.	Not detailed.	Not detailed.	References papers which likely contain more details.	Not explicitly mentioned in the text.

			response function. The wire-cell algorithm performs tomographic inversion of signals.			on.					
Pandora	A multi-algorithm approach to particle reconstruction.	Pattern recognition and event reconstruction, identifying clusters, tracks, and shower	Uses various algorithms to associate objects in 2D views to reconstructed 3D	No.	Not detailed.	Takes hits as input and outputs clusters, tracks, and showers stored in RO	Processed detector signals.	Not detailed.	Not detailed.	Reference paper likely contains more details.	Not explicitly mentioned in the text.

		wer s in 3D.	obje cts.			OT tree s.					
CA FAn a (Co mm on Ana lysi s For mat Ana lyze r)	A libra ry of anal ysis tool s dev elop ed by the NO vA coll abo rati on.	Fin al stag e phy sics anal ysis .	Wor ks with sim plifi ed RO OT- bas ed ntu ples (CA F files).	No.	Not det aile d.	Ana lyze s CA F files , whi ch are red uce d dat a sam ples .	Red uce d phy sics dat a.	Not det aile d.	Not det aile d.	Ref ere nce pap ers likel y cont ain more det ails.	Not expl icitl y me ntio ned in the text.
PP FX (Pa cka ge to Pre dict the Flu X)	A fra me wor k dev elop ed by the MIN ERv A coll abo rati on use d to esti mate	Esti mati ng neu trin o flux unc erta intie s.	Re wei ghti ng fra me wor k for bea mlin e sim ulati ons.	No.	Not det aile d.	Use d to rew eigh t flux files .	Sim ulati on par am eter s.	Not det aile d.	Not det aile d.	Ref ere nce pap ers likel y cont ain more det ails.	Not expl icitl y me ntio ned in the text.

	uncertainties on the neutrino flux at the near detector.										
DUNE ND GG D	A package that takes Python classes called builders as input and produces GDML files for the near	Creating geometry descriptions for the near detectors.	Uses Python classes to define detector geometry.	No.	Not detailed.	Outputs GDML files.	Detector geometry descriptions.	Not detailed.	Not detailed.	Not mentioned in this snippet.	https://github.com/dune/dunegd

	det ecto rs.										
Gea nt4 Re wei ght	A rew eigh ting fra me wor k dev elop ed by DU NE.	Adj usti ng exis ting Gea nt4 sim ulati ons bas ed on new inte racti on cros s-se ctio n kno wle dge .	Re wei ghts Gea nt4 sim ulati on out put.	No.	Not det aile d.	Ope rate s on the out put of Gea nt4 sim ulati ons.	Sim ulat ed part icle inte racti ons.	Not det aile d.	Not det aile d.	Ref ere nce pap er likel y cont ains mor e det ails.	Not expl icitl y me ntio ned in this snip pet.
Ove rlay Gen ie	A pac kag e use d for ove rlayi ng sim ulat ed inte racti on	Sim ulati ng bac kgr oun ds by com bini ng sim ulat ed eve nts	Co mbi nes sim ulat ed hits with raw dat a.	No.	Not det aile d.	Req uire s libra ries of pro perl y-fo rma tted raw dat a and sim	Det ecto r sign als and sim ulati on dat a.	Not det aile d.	Not det aile d.	Not expl icitl y me ntio ned in this snip pet.	Not expl icitl y me ntio ned in this snip pet.

	information on real data.	with real detector data.				ulated hits.					
Proton DUNE-DP Data	Data collected from the dual-phase Proton DUNE detector at CERN.	Testing the full data cataloging and reconstruction chain.	Not applicable.	Not applicable.	Not applicable.	Raw data files (run sequence files).	Detector signals.	3.2 GB, each containing 30 trigger records.	Not detailed.	Not mentioned in this snippet.	Not mentioned in this snippet.
Public LArTPC Simulation Dataset	A publicly available dataset.	Evaluating machine learning-based reconstruction algorithms for	Not applicable.	Not applicable.	Not applicable.	A LArTPC simulation dataset.	Simulated particle interactions.	Not detailed.	Not detailed.	Reference paper likely contains details about this dataset	Not mentioned in this snippet.

		ND-LAr.									
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3. Summary and Initial Observations

The analysis of the provided materials reveals a significant effort to integrate machine learning methodologies into various aspects of the DUNE project ². This includes the development and application of deep learning models, such as Convolutional Neural Networks (CNNs) and Autoencoders, alongside more traditional machine learning techniques like those employing Local Binary Patterns (LBP) ⁴. These efforts span a wide range of applications, from real-time data processing within the data acquisition system to offline analysis and simulation frameworks.

A prominent theme is the crucial role of simulation software in the DUNE ecosystem ². Frameworks like LArSoft, GARSoft, and larnd-sim are fundamental for both detector design and the development and testing of analysis algorithms, including those based on machine learning. The availability of data from the ProtoDUNE single-phase (SP) and dual-phase (DP) prototypes is also of paramount importance ². These datasets provide real-world examples of detector responses and are invaluable for validating simulation tools and analysis techniques before the full DUNE detectors become operational. The fact that raw trigger records from ProtoDUNE-SP were around 75 MB compressed and run sequence files from ProtoDUNE-DP were 3.2 GB each gives a sense of the scale of data being handled ².

The development and benchmarking of models like the 2D CNN for radiological background rejection, which has been tested on both GPUs and FPGAs, highlight the project's focus on achieving efficient real-time processing ⁴. The reported performance metrics, such as the 99.42% signal efficiency and 99.69% background rejection on simulated data, along with the inference times on different hardware, demonstrate a rigorous approach to evaluating the suitability of these models for deployment in the DUNE environment. Furthermore, the adaptation of models to work with the specific data formats of the DUNE DAQ system, such as the retraining of the 2D CNN with sparser Trigger Primitives, underscores a commitment to practical implementation.

The DUNE collaboration also leverages tools and frameworks developed by other neutrino experiments, such as CAFAna from NOvA and PPFx from MINERvA ². This collaborative approach within the high-energy physics community allows DUNE to benefit from the existing expertise and resources in the field. The use of a package manager like Spack for managing DUNE DAQ dependencies further emphasizes the adoption of sound software engineering practices for this complex project ⁴.

The variety of machine learning models under investigation, each tailored for specific tasks like neutrino interaction identification, region of interest finding, and noise reduction, suggests a comprehensive and strategic approach to applying these techniques to the unique challenges of neutrino physics ³. The performance benchmarks reported for models like the 1D Autoencoder for denoising (e.g., ~69% primary track efficiency, ~99% background rejection, and specific inference times) provide quantitative measures of their effectiveness.

4. Conclusion

This report has presented a detailed catalog of the benchmarks, software artifacts, and datasets associated with the Fast Machine Learning initiatives within the DUNE project, as documented in the provided research materials. These resources are essential for the ongoing development and preparation for the DUNE experiment. The benchmarks offer crucial performance metrics, the software artifacts enable vital simulation, reconstruction, and analysis capabilities, and the datasets serve as fundamental resources for training and validating the next generation of analysis algorithms.

The continued development and refinement of these machine learning-related tools and resources are vital for enabling DUNE to achieve its ambitious scientific objectives. The integration of advanced computational techniques, particularly machine learning, is poised to play a critical role in the success of this groundbreaking experiment, facilitating the extraction of meaningful insights from the vast and complex datasets that DUNE will generate. Further exploration of the presentations and papers referenced in the materials, as well as the investigation of repositories like larrecodnn, would likely provide even more granular details about the ongoing advancements in this dynamic field within the DUNE collaboration.

Works cited

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