Accessibility

GoBox Mission 02



Your mission

Create a robotic guide dog that can lead someone on a pre-planned path around your home without running into walls or obstacles.

Design: Guide Harness

Investigate materials around your home to choose the one you can sense best with your eyes closed.

Material	Length	Result
Rigid Material:	long	I could easily feel I had trouble feeling
	short	I could easily feel I had trouble feeling
Flexible Material:	long	I could easily feel I had trouble feeling
	short	I could easily feel I had trouble feeling

Design: Obstacle Avoidance Program Think about how your robot should behave as it moves around the house.	ow your robot should behave as it moves around the house.
	ow your robot should behave as it moves around the house. close to an object should the GoPiGo get before it reacts?
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Think about how your robot should behave as it moves around the house.	close to an object should the GoPiGo get before it reacts?
Think about now your robot should behave as it moves around the house.	close to an object should the GoPiGo get before it reacts?
How close to an object should the GoPiGo get before it reacts?	it detects an obstacle, what should the robot do?
	it detects an obstacle, what should the robot do?
2. When it detects an obstacle, what should the robot do?	