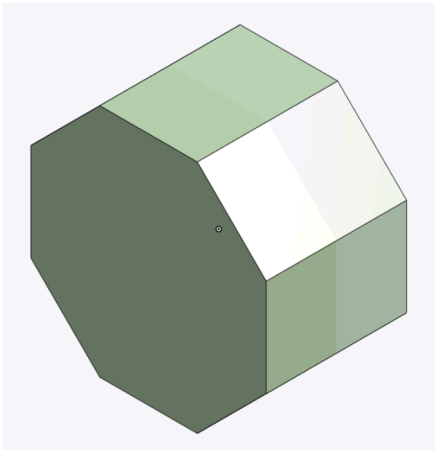
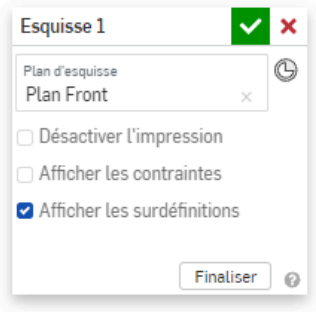
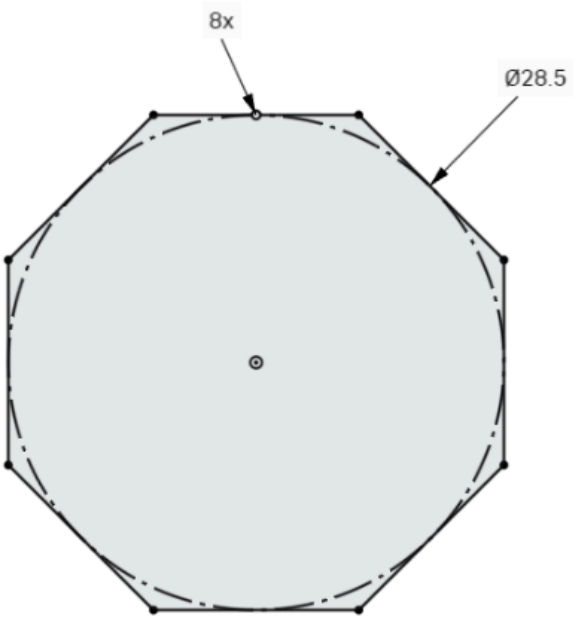
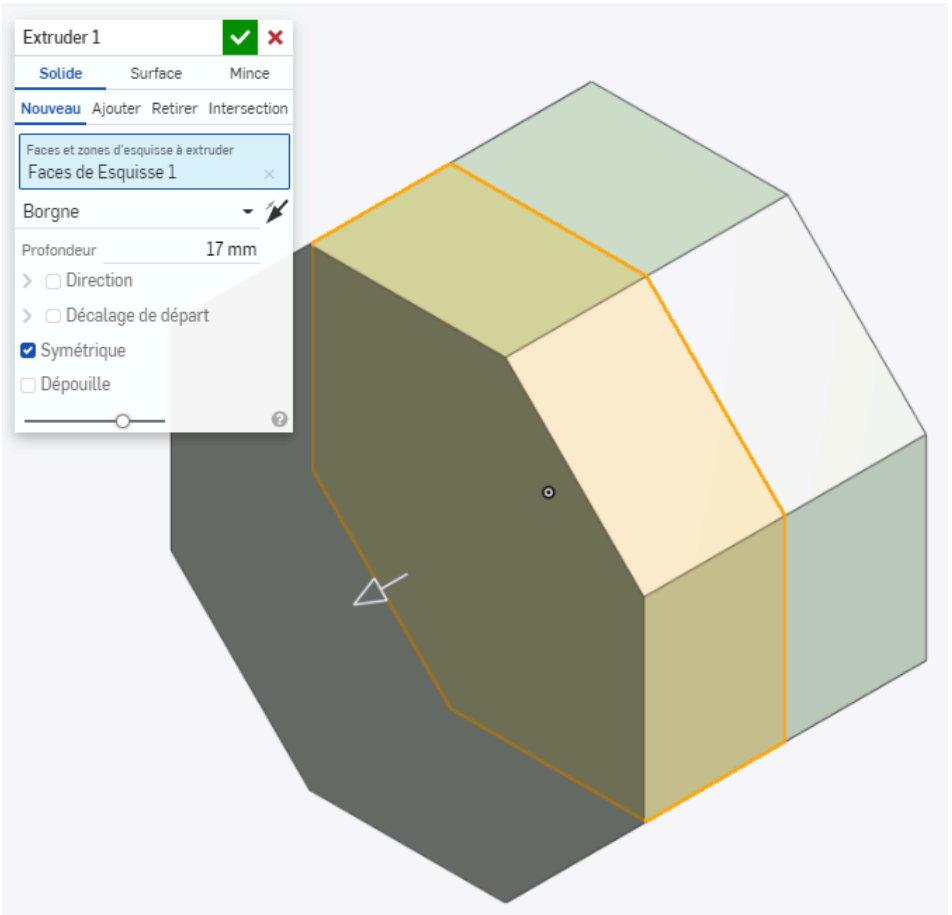
Robot Smars - Roues + Jantes

1.Base

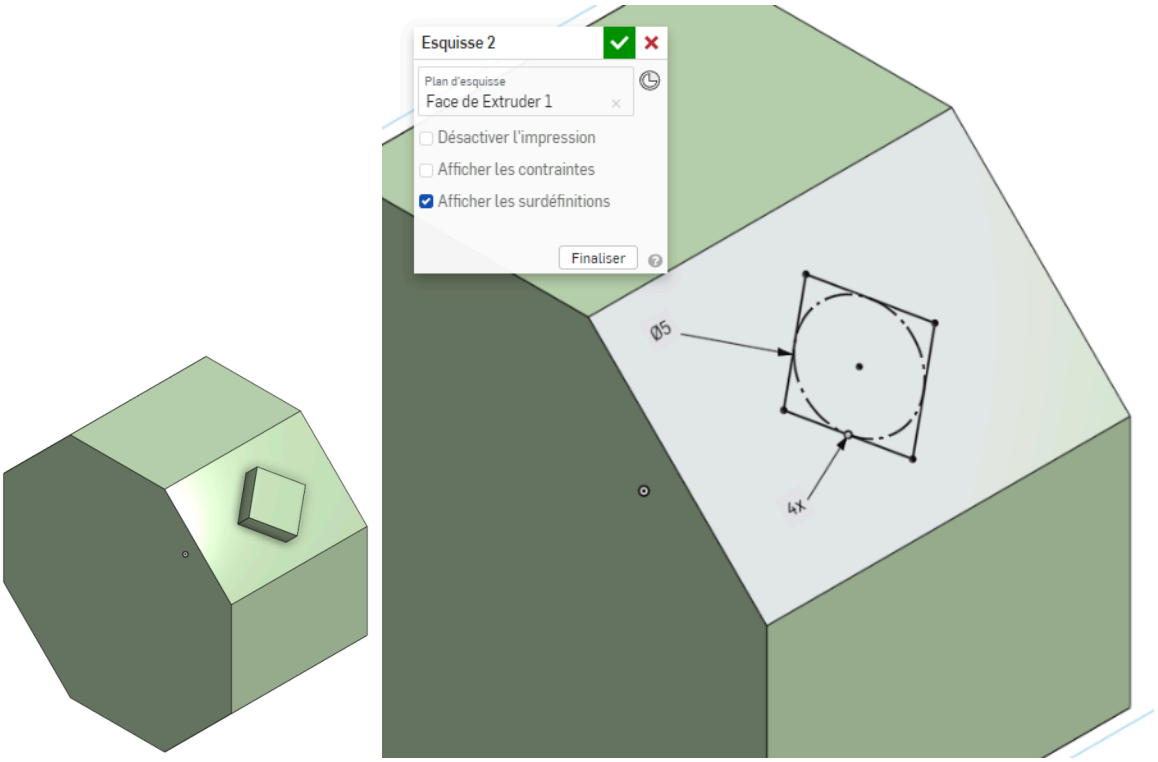


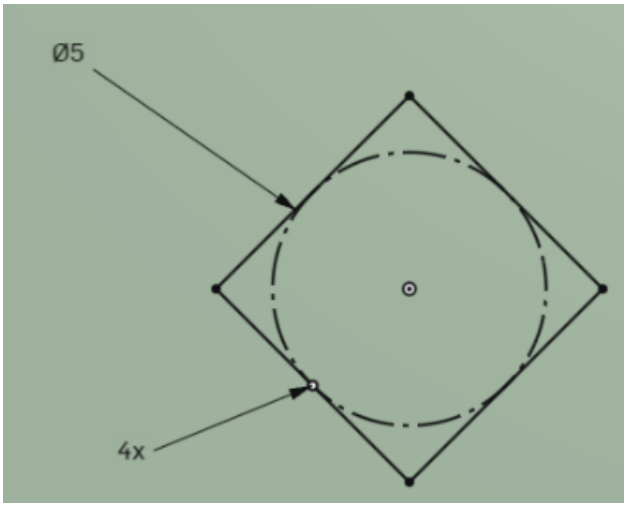


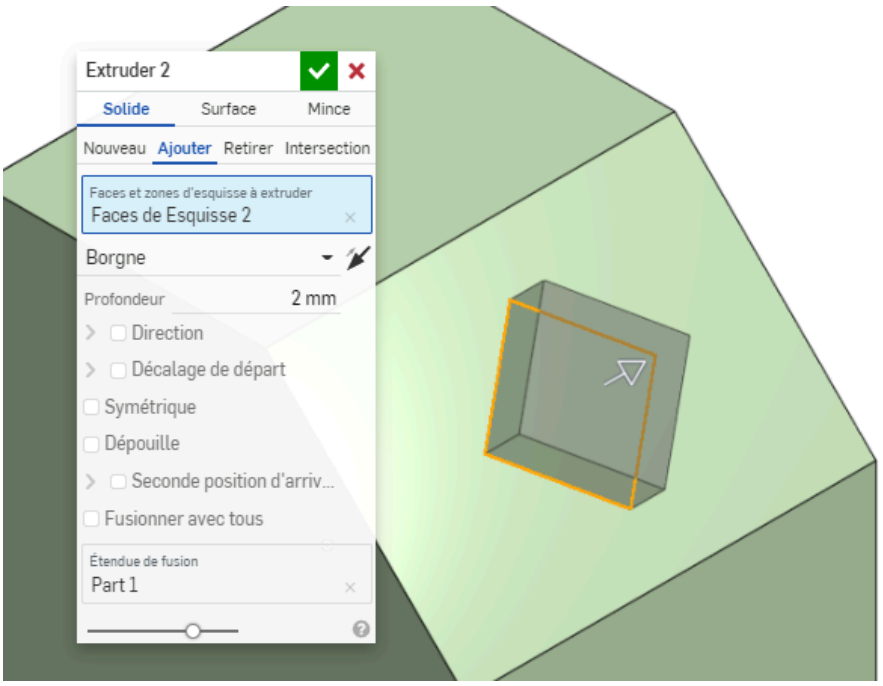




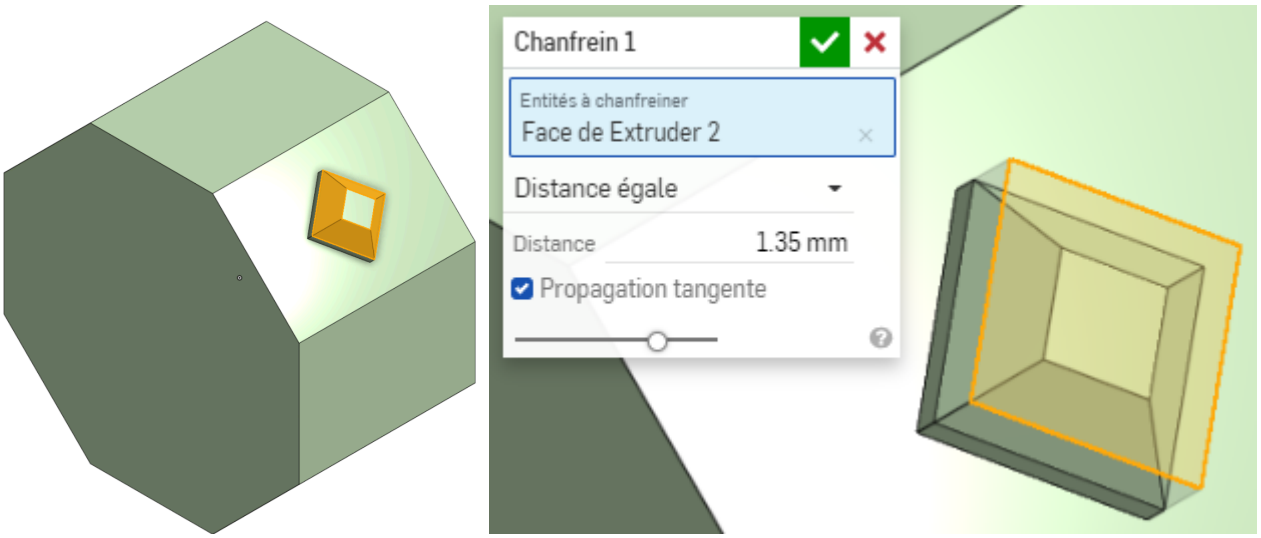
2. Petit carré



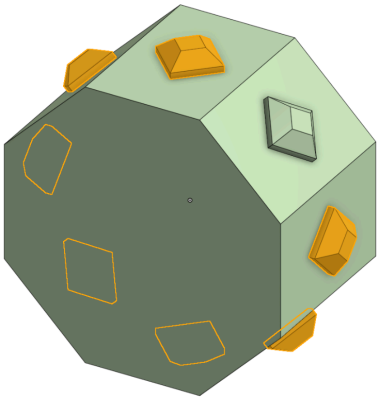


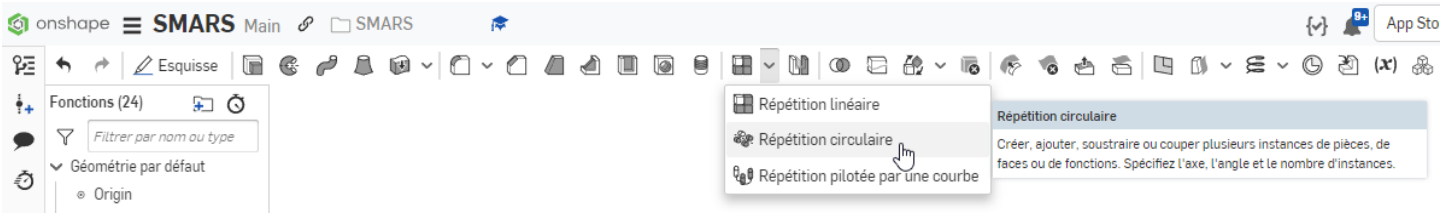


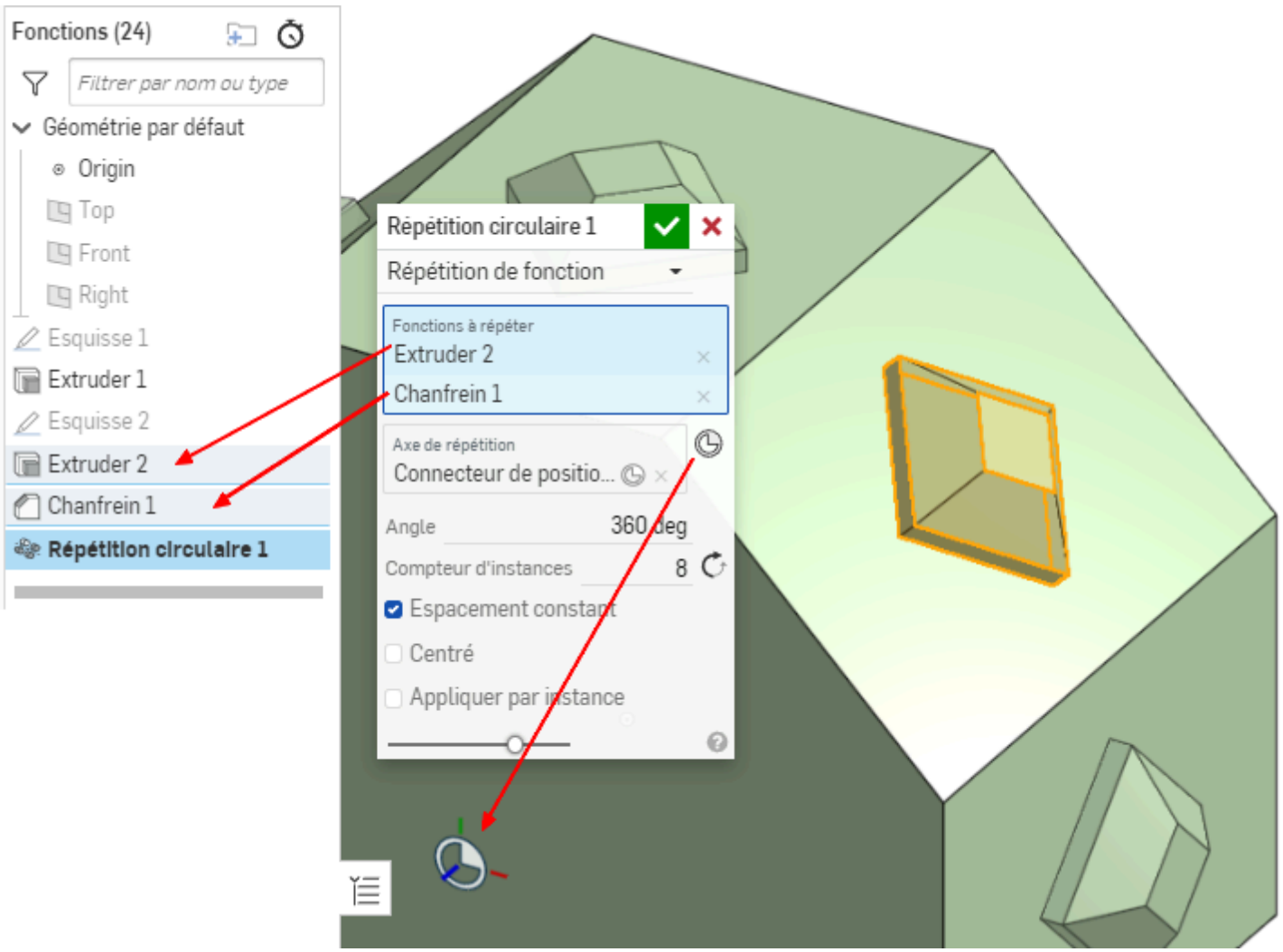
3. Chanfrein du petit carré



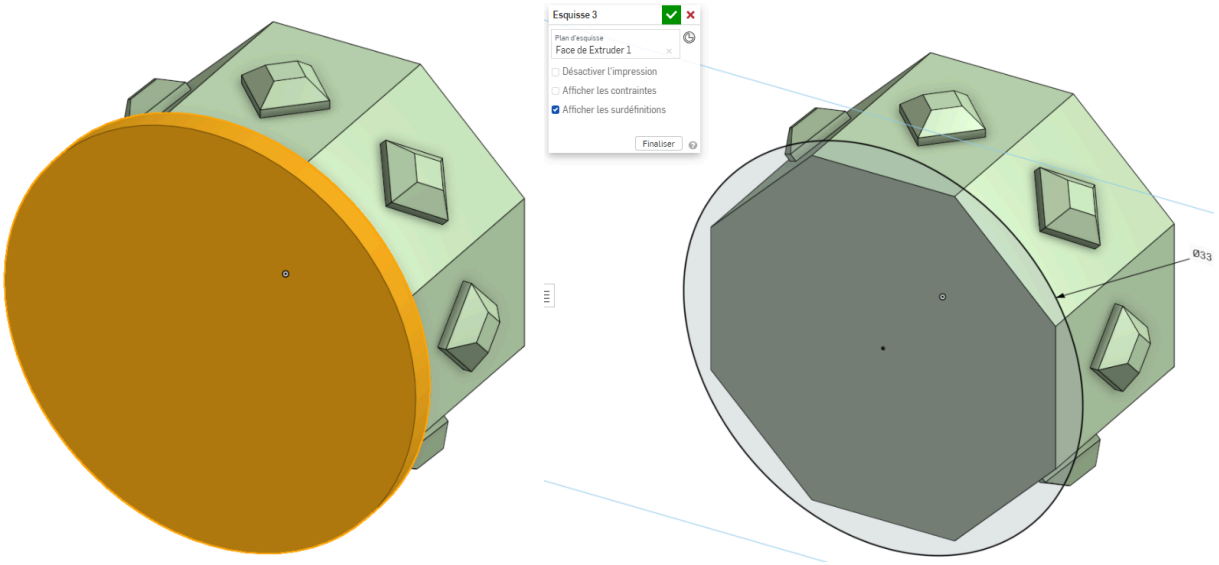
4. Répétition des petits carrés

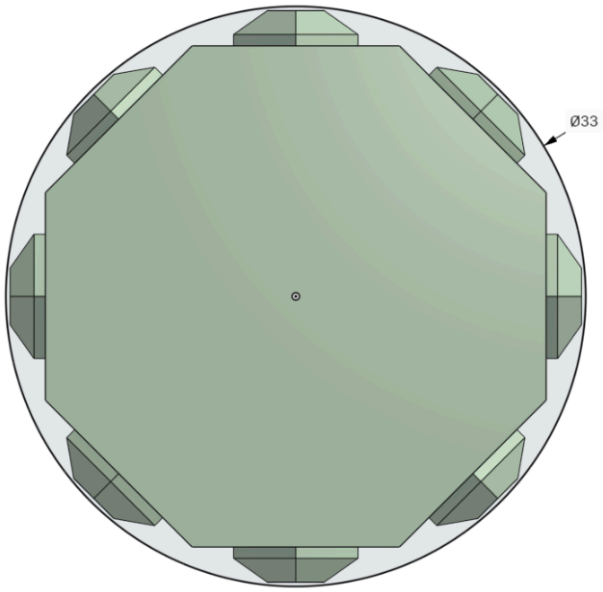


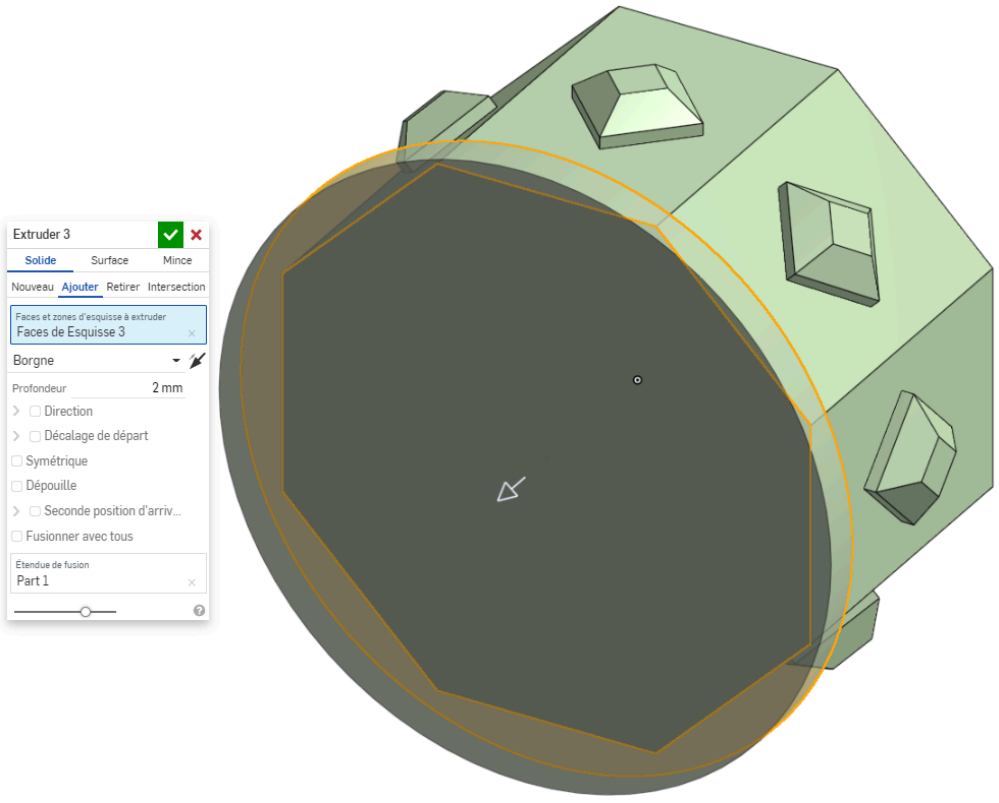




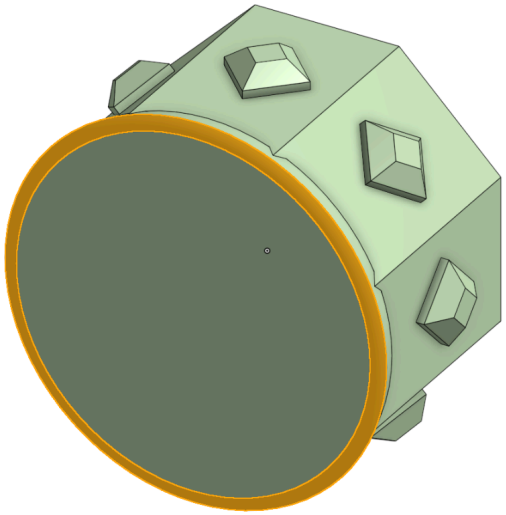
5.Face avant de la roue

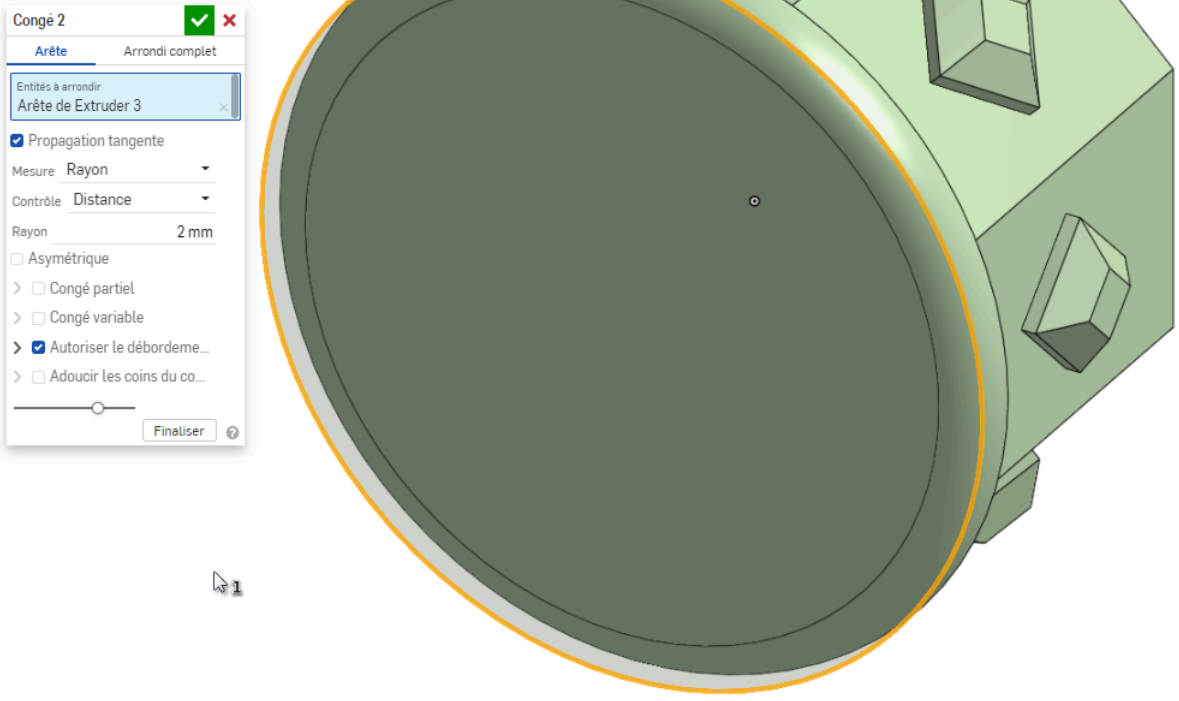




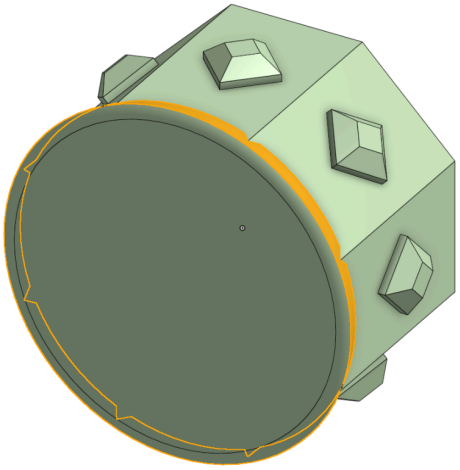


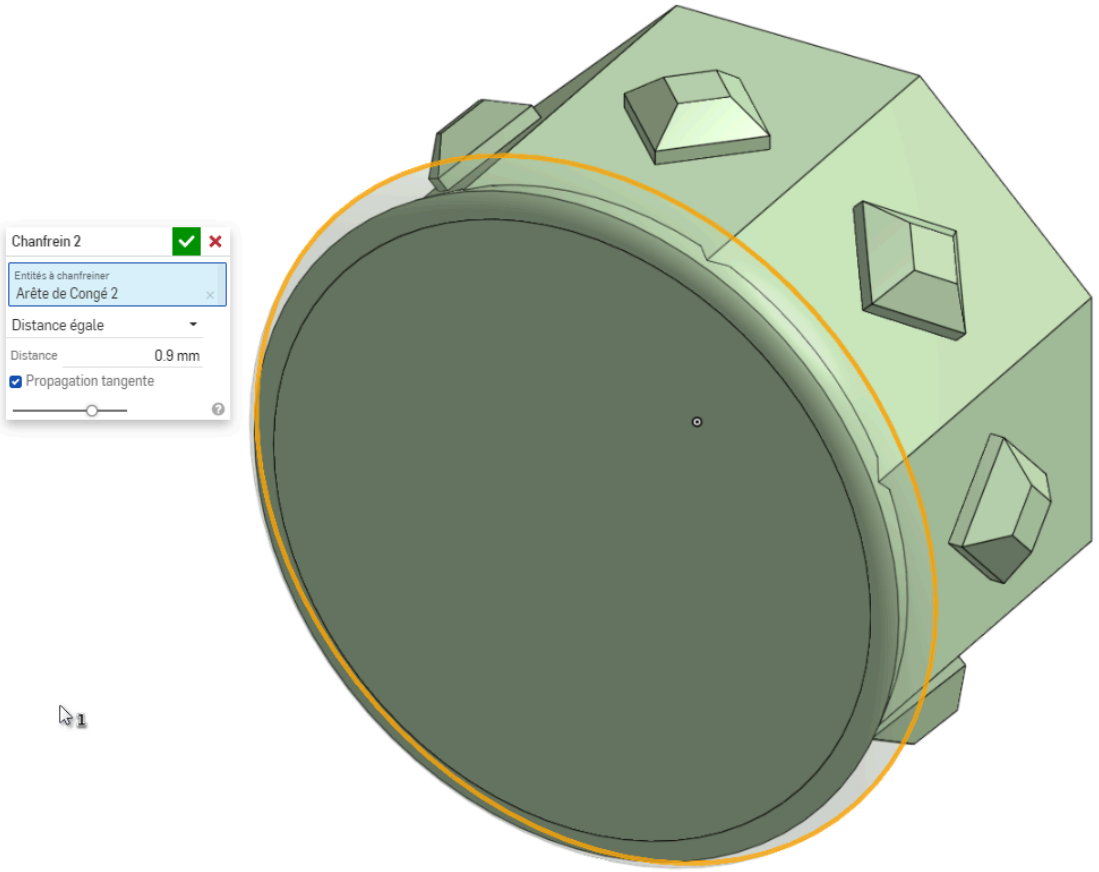
6. Congé



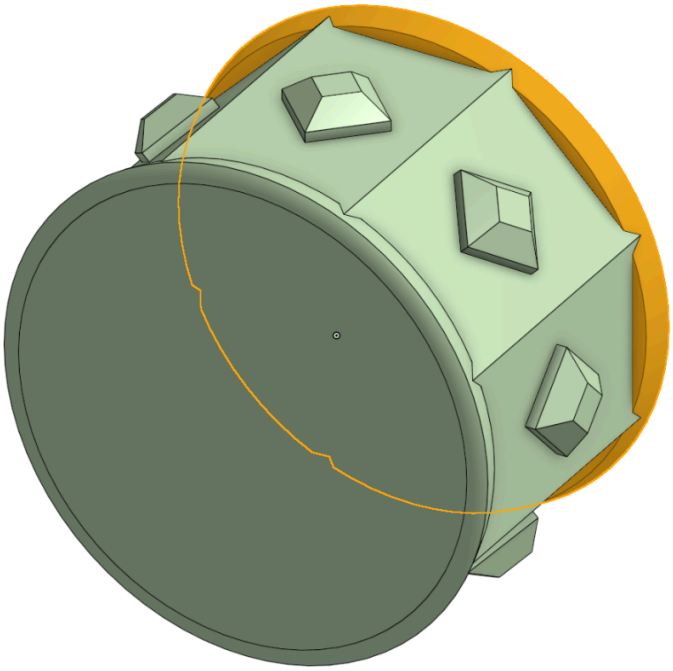

Congé 2
Arête
Arrondi complet
Entités à arrondir
Arête de Extruder 3
Propagation tangente
Mesure
Rayon
Contrôle
Distance
Rayon
2 mm
Asymétrique
Congé partiel
Congé variable
Autoriser le débordeme...
Adoucir les coins du co...
Finaliser

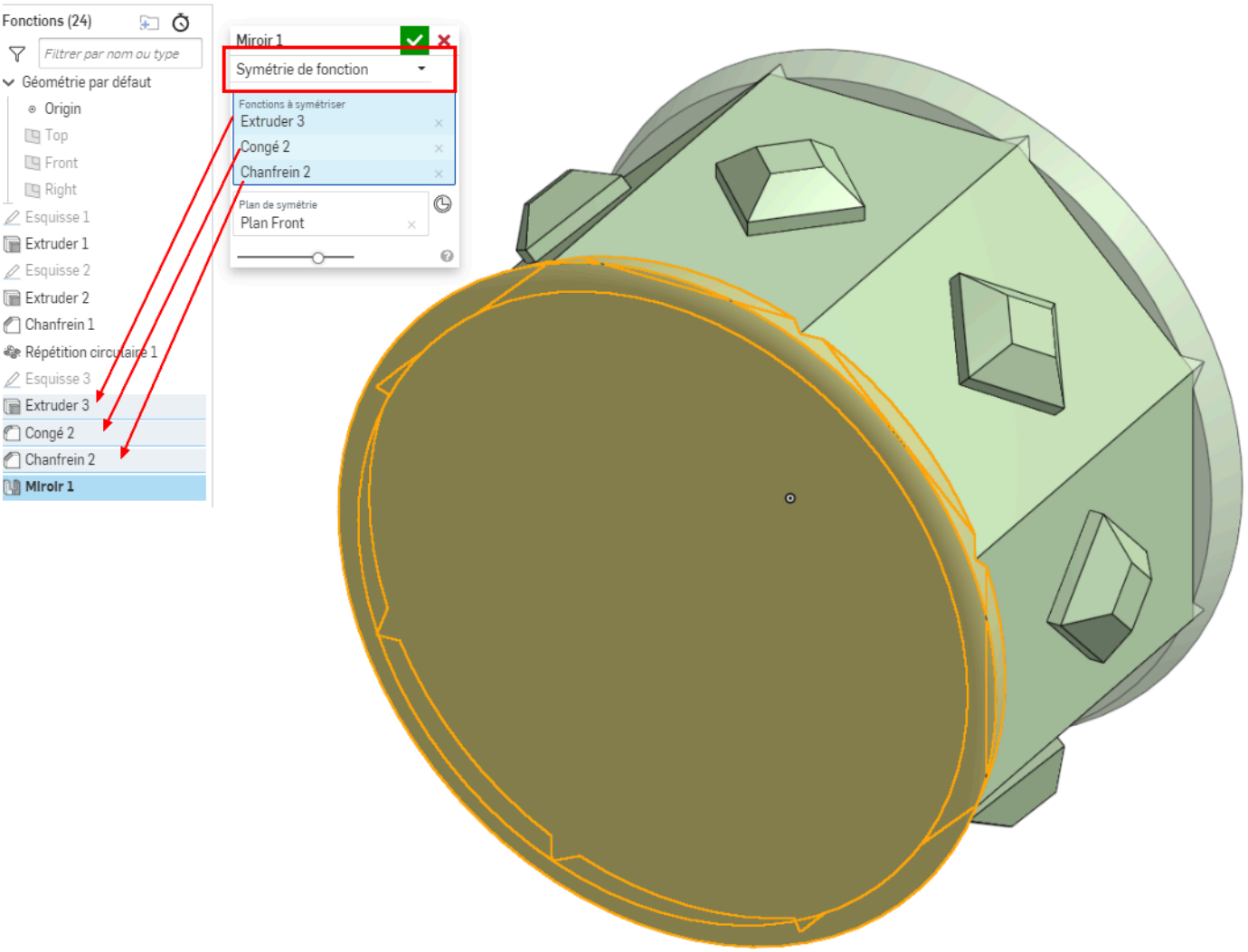
7. Chanfrein



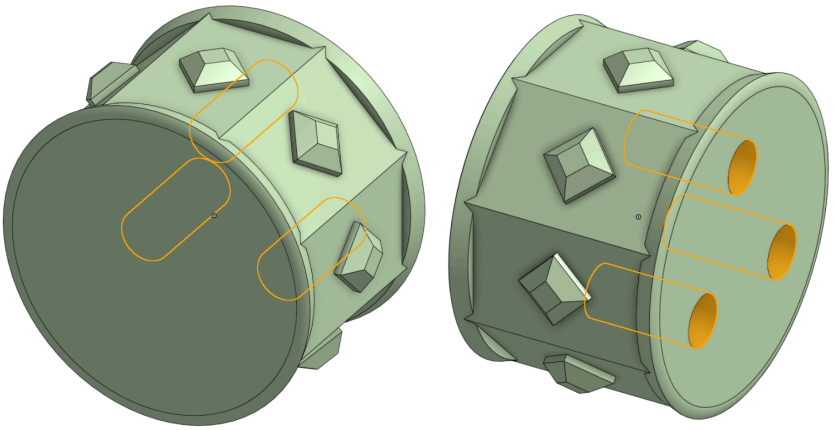

Chanfrein 2
Entités à chanfreiner
Arête de Congé 2
Distance égale
Distance
0.9 mm
Propagation tangente
1

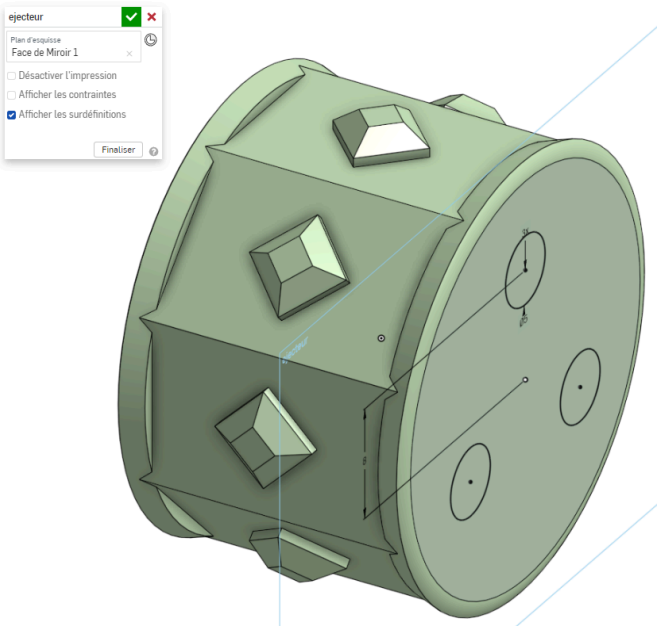
8. Symétrie

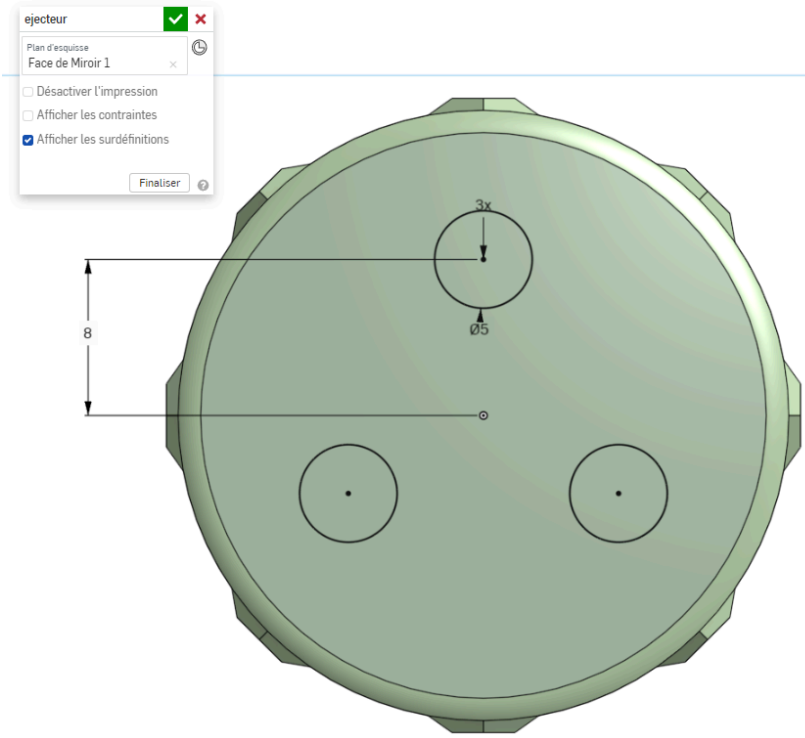


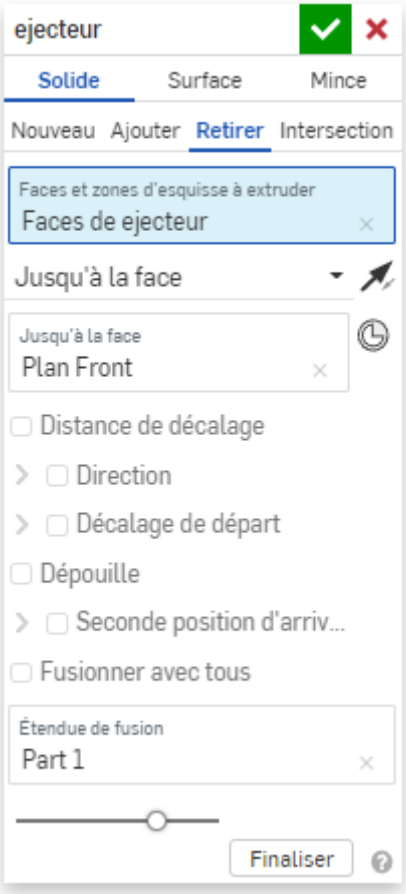

Fonctions (24)
Filtrer par nom ou type
Géométrie par défaut
Origin
Top
Front
Right
Esquisse 1
Extruder 1
Esquisse 2
Extruder 2
Chanfrein 1
Répétition circulaire 1
Esquisse 3
Extruder 3
Congé 2
Chanfrein 2
Miroir 1
Miroir 1
Symétrie de fonction
Fonctions à symétriser
Extruder 3
Congé 2
Chanfrein 2
Plan de symétrie
Plan Front

9. Trou des éjecteurs

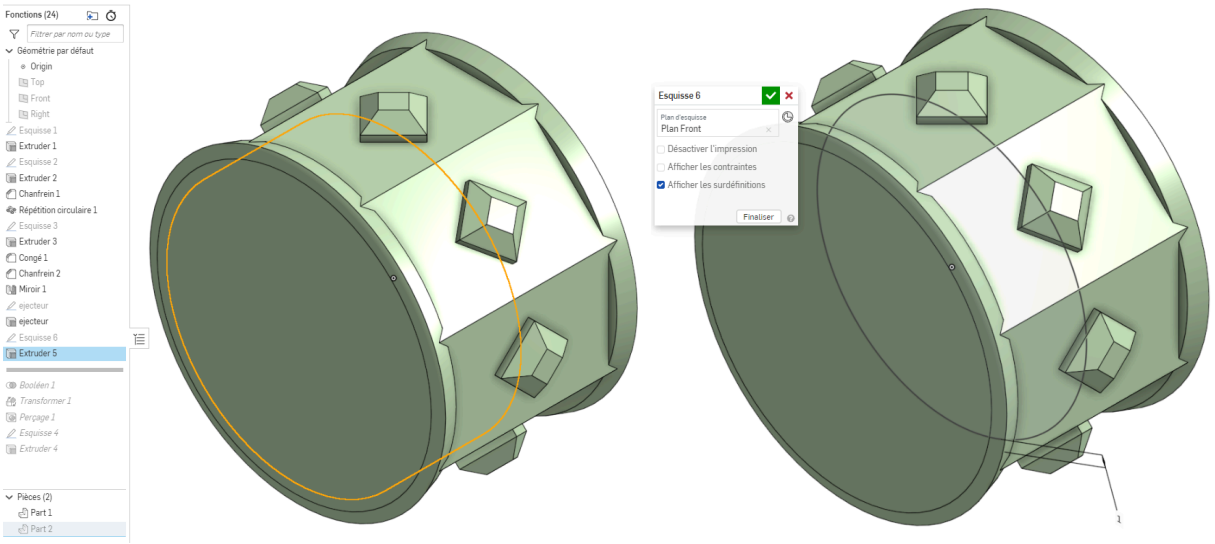


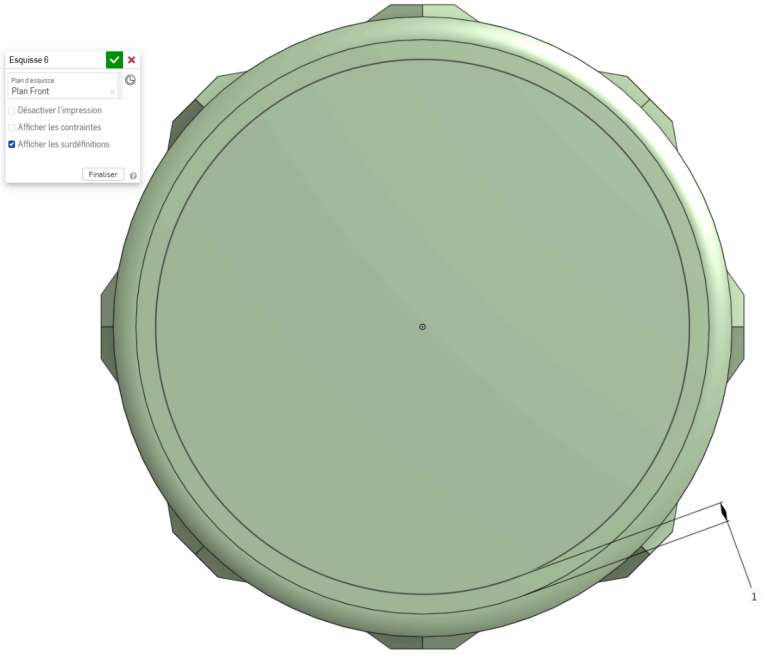


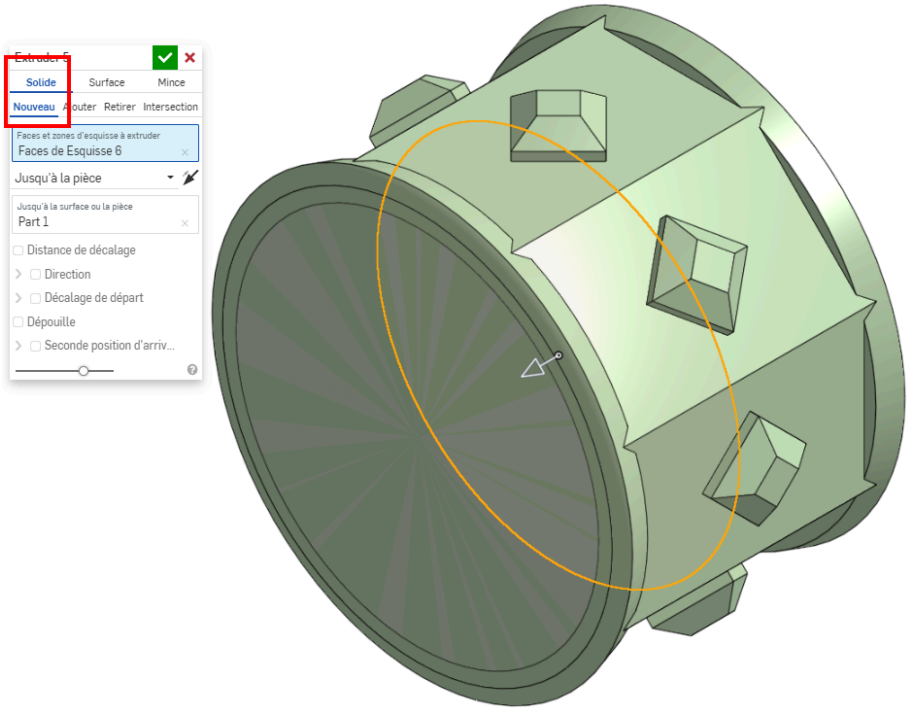




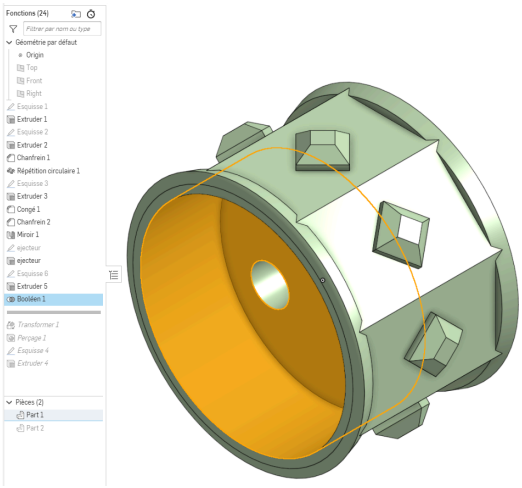
10. Création de la jante

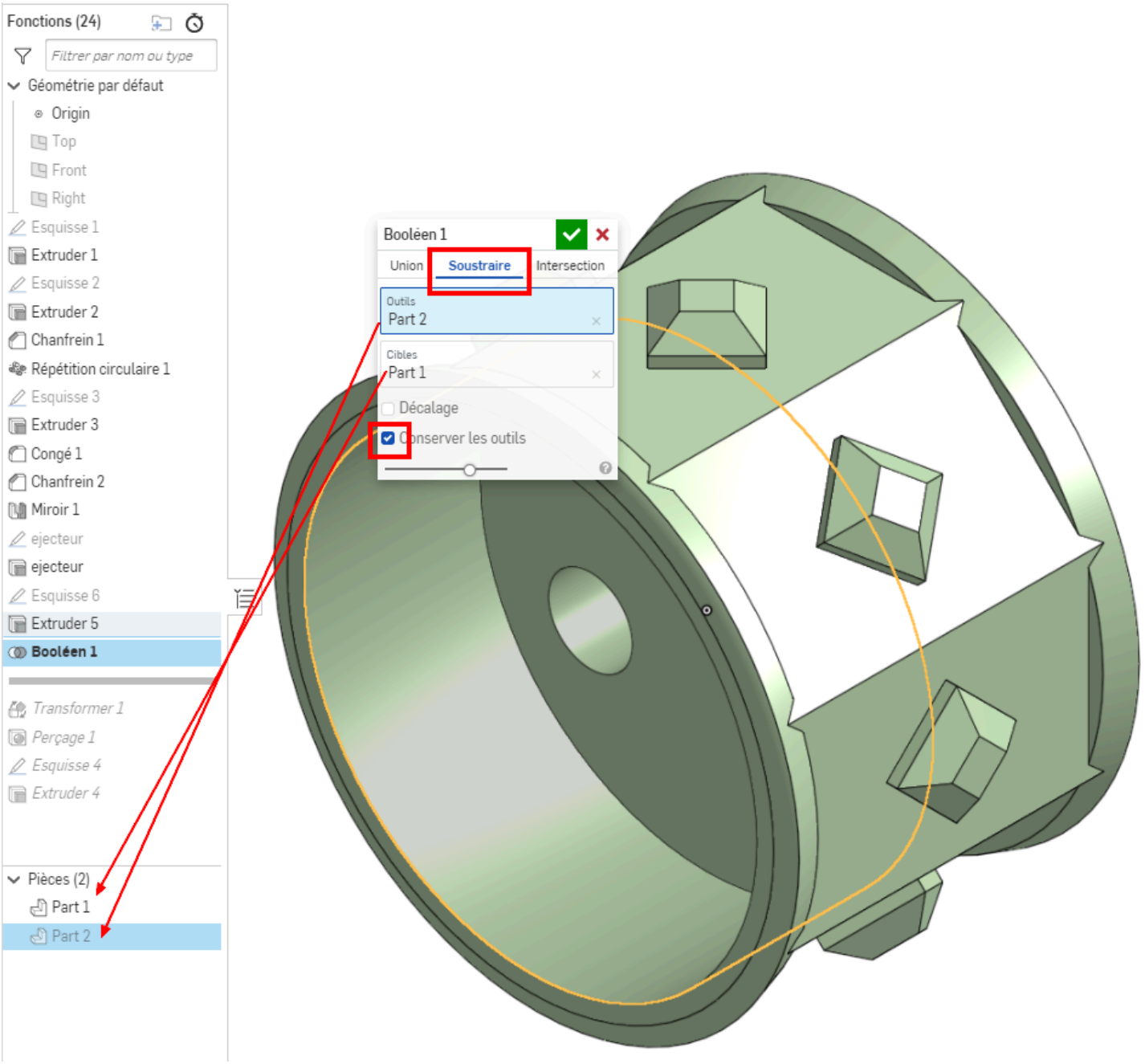




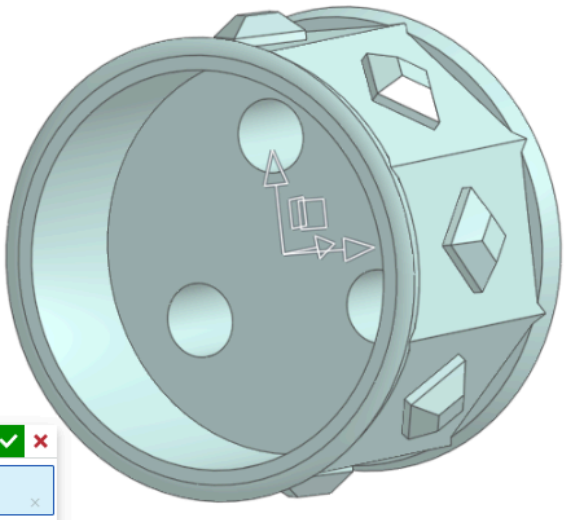


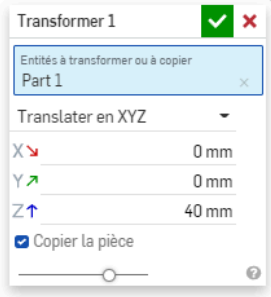
11. Évidement de la roue

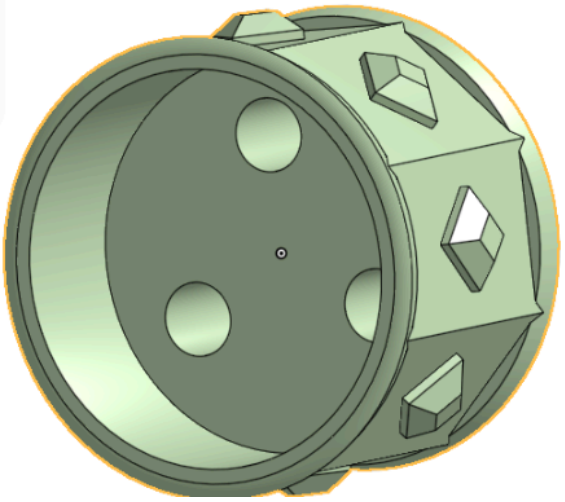




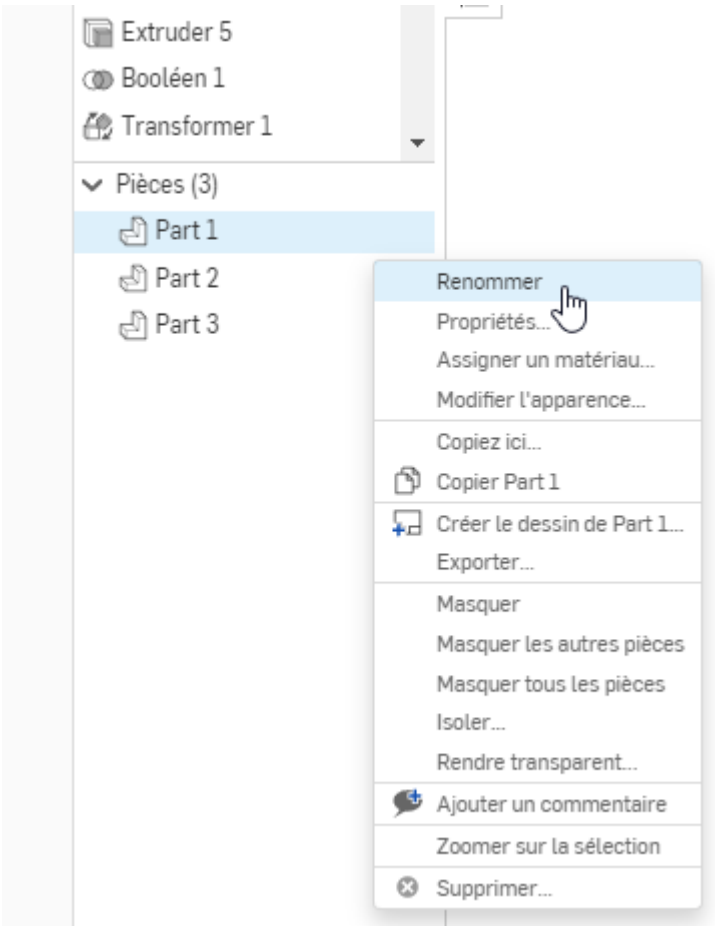
12. Copier la roue





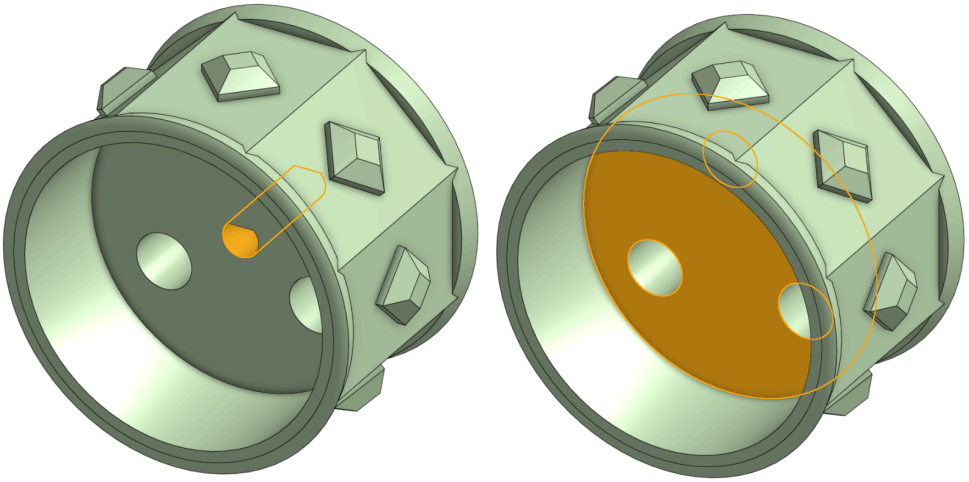


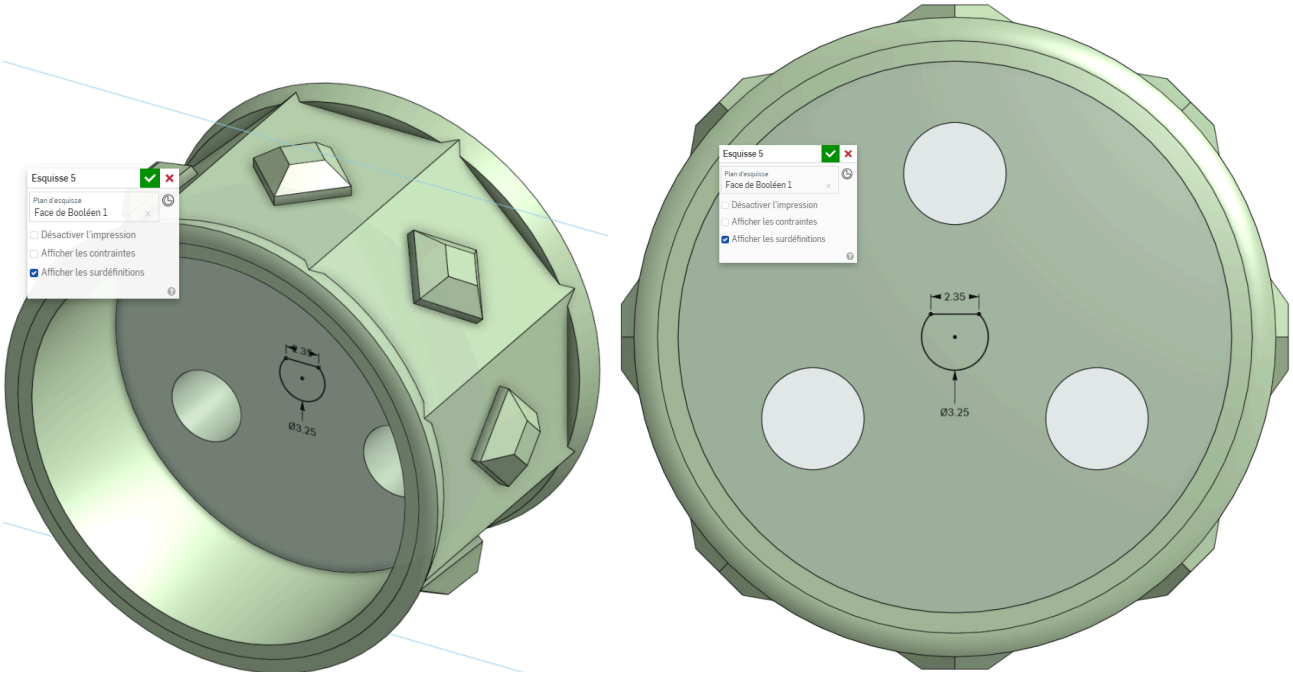
13. Renommer les roues et la jante

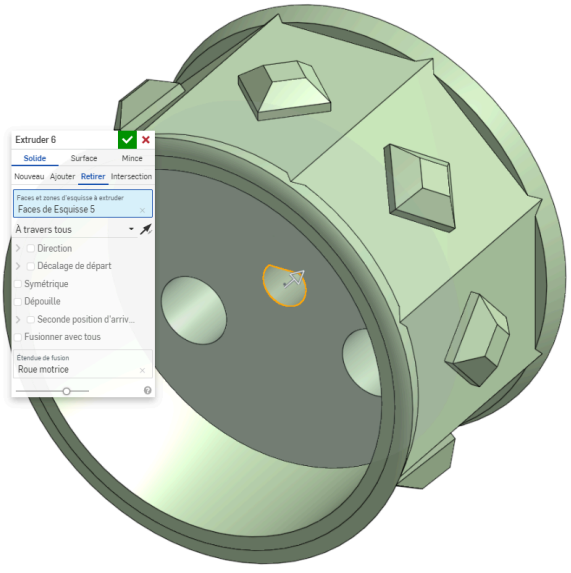


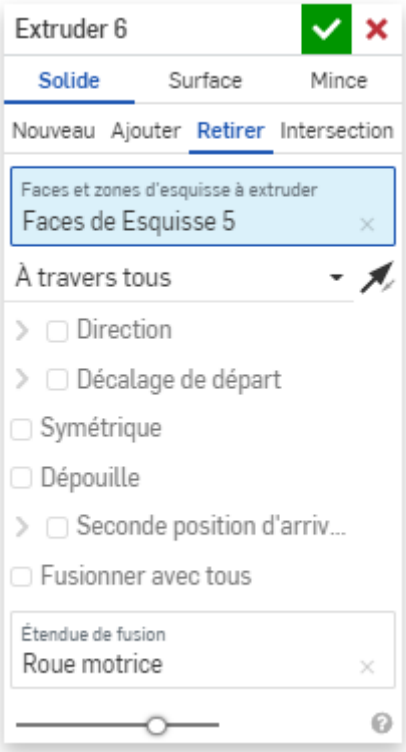
Part 1 = « Roue motrice »
Part 2 = « Jante »
Part 3 = « Roue libre »

14. Alésage avec méplat de la roue motrice

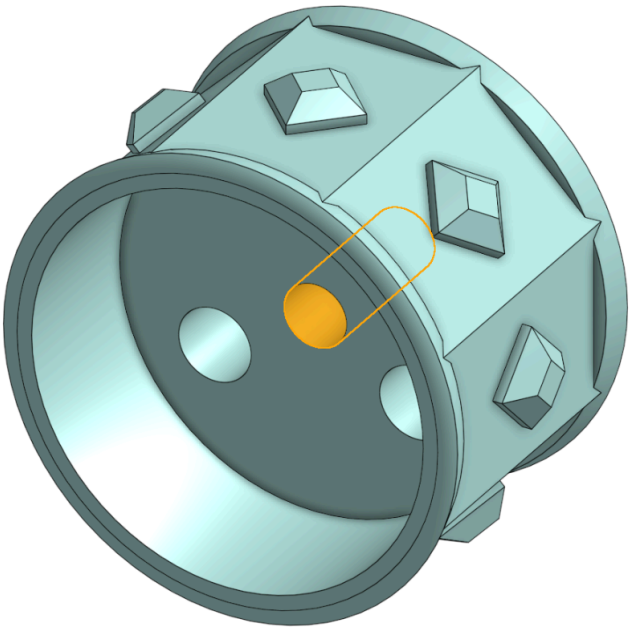


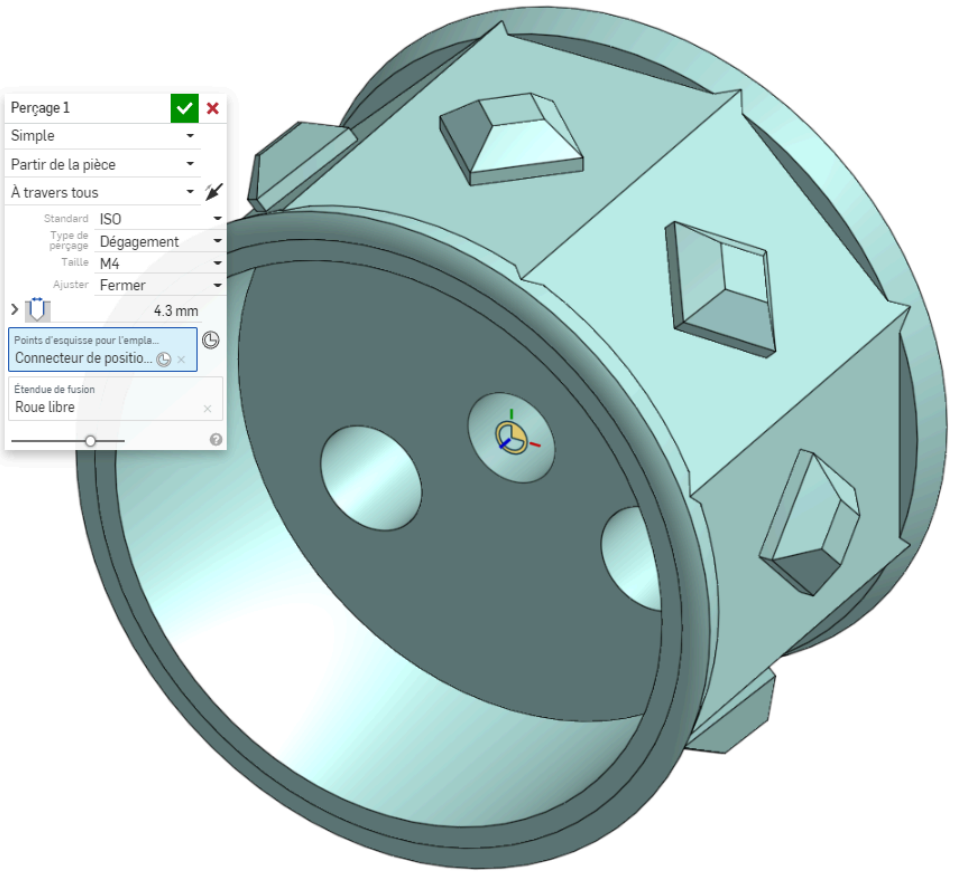


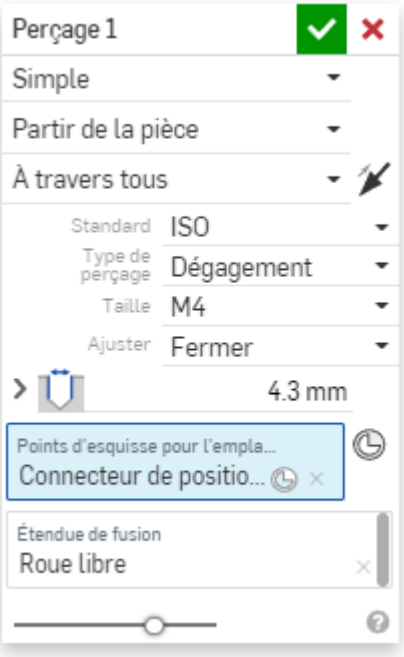




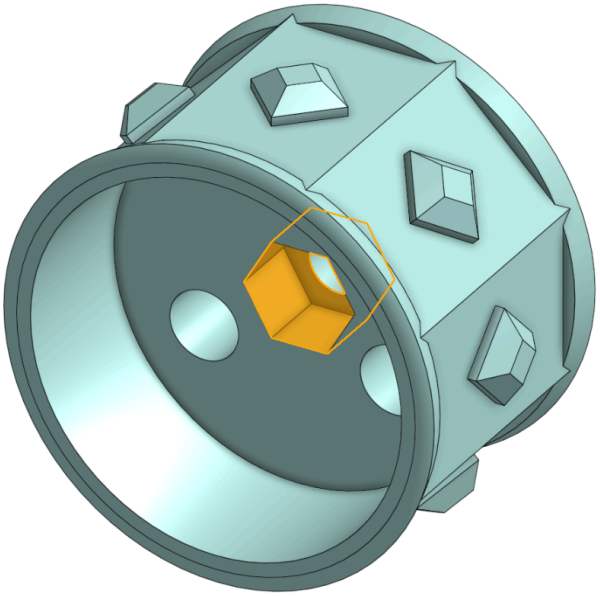
15. Perçage de la roue libre

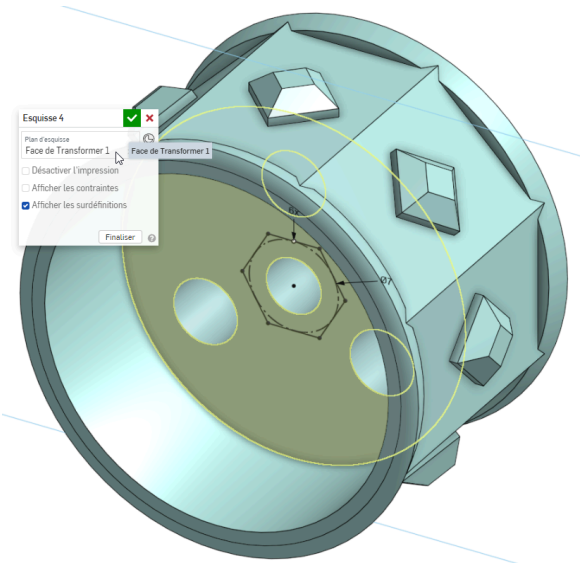


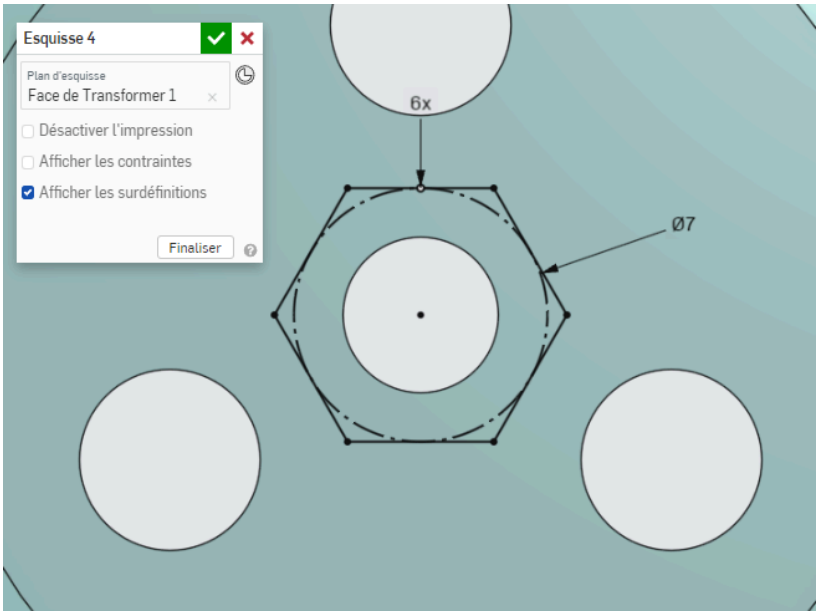


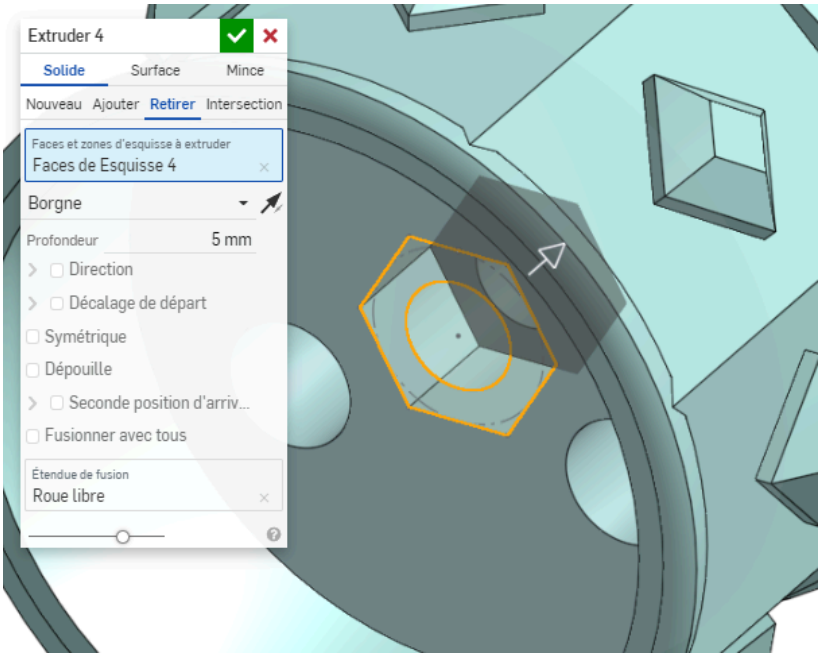


16. Réalisation de la poche pour noyer l’écrou









17. Votre jante