## **Electrical And Electronic Measurement (22325)**

## **Class Test I**

| 1. |  | is the act or result of a quantitative comparison between an unknown                     |  |
|----|--|--|--|
|    | quanti   | ty & a predefined standard quantity.   |  |
|    | _  | Measurement  |  |
|    | b)   | Calibration  |  |
|    | c)   | Instrument   |  |
|    | d)   | Characteristics.   |  |
| 2. | Which  | is the type of standard??  |  |
|    | a)   | Primary  |  |
|    | b)   | Secondary  |  |
|    | c)   | Working  |  |
|    | d)   | All of these   |  |
| 3. | The sta  | ndard with highest possible accuracy   |  |
|    | a)   | Primary  |  |
|    | b)   | Secondary  |  |
|    | c)   | International  |  |
|    | d)   | Working  |  |
| 4. | The ins  | truments which are used to measure the quantity under measurement indirectly ie.in terms |  |
|    | of deflection, degrees.  |  |  |
|    | a)   | Primary  |  |
|    | b)   | Absolute   |  |
|    | c)   | Secondary  |  |
|    | d)   | None of these  |  |
| 2. | The absolute instrument is   |  |  |
|    | a)   | Voltmeter  |  |
|    | b)   | Ammeter  |  |
|    | c)   | Wattmeter  |  |
|    | d)   | Galvanometer   |  |
| 3. | The instruments which are used to measure the quantity under measurement directly. |  |  |
|    | a)   | Primary  |  |
|    | b)   | Absolute   |  |
|    | c)   | Secondary  |  |
|    | d)   | None of these  |  |
| 4. |  | condary instruments are  |  |
|    | a)   | Voltmeter  |  |
|    | b)   | Ammeter  |  |
|    | c)   | Wattmeter  |  |
|    | d)   | All of these   |  |

| 5.  | The Instruments which reads with the help of pointer and calibrated scale.                           |
|-----|--|
|     | a) Indicating  |
|     | b) Recording   |
|     | c) Integrated  |
|     | d) None of above   |
| 6.  | The Instruments which continuously record the quantity under measurement over a some period          |
|     | a) Indicating  |
|     | p) Recording   |
|     | c) Integrated  |
|     | d) None of above   |
| 7.  | The instruments are used to collect the data for specific duration of time are called as integrating |
|     | type instruments.  |
|     | a) Indicating  |
|     | p) Recording   |
|     | c) Integrated  |
|     | d) None of above   |
| 8.  | The integrating type of instrument is  |
|     | a) Voltmeter   |
|     | o) Ammeter   |
|     | c) Wattmeter   |
|     | d) Energymeter   |
| 9.  | The indicating type of instrument is   |
|     | a) Voltmeter   |
|     | b) Energymeter   |
|     | c) None of above   |
|     | d) Both a) and b)  |
| 10. | The Degree Closeness with which an instrument reading approaches the true value.                     |
|     | a) Accuracy  |
|     | p) Precision   |
|     | c) Resolution  |
|     | d) Drift   |
| 11. | The degree of Measure of Consistency or Repeatability of Measurement under a successive set of       |
|     | readings.  |
|     | a) Accuracy  |
|     | p) Precision   |
|     | c) Resolution  |
|     | d) Reproducibility   |
| 12  | The closeness of output readings when the same input is applied repetitively over a short period of  |
| 12. | time.  |
|     | unic.  |
|     | a) Repeatability   |
|     | p) Reproducibility   |
|     | c) Resolution  |

d) Drift

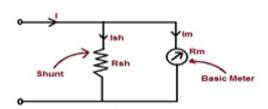
- 13. It describes the closeness of output reading for same input when there are changes in method of measurement, observer, measuring instrument, location etc.
  a) Repeatability
  b) Reproducibility
  c) Resolution
  d) Drift
  14. It is smallest measurable I/P changes which can be detected by the instrument.
  - a) Accuracy
    - b) Precision
  - c) Resolution
  - d) Drift
- 15. The errors that are caused by deviations in the performance of the measuring instrument that occur after calibration.
  - a) Error
  - b) Drift
  - c) Dead zone
  - d) None of above
- 16. It is defined as the largest change of input quantity for which there is no output of the instrument.
  - a) Error
  - b) Drift
  - c) Dead zone
  - d) Resolution
- 17. It is defined as the difference between True value and Measured value
  - a) Error
  - b) Drift
  - c) Dead zone
  - d) Resolution
- 18. The time required for Instrument to change its output if an input is applied.
  - a) Speed of response
  - b) Dynamic error
  - c) Lag
  - d) Fidelity
- 19. The difference between the true value and measured value with zero static error.
  - a) Speed of response
  - b) Dynamic error
  - c) Lag
  - d) Fidelity
- 20. It is defined as a time difference between input and output of instrument.
  - a) Speed of response
  - b) Dynamic error
  - c) Lag
  - d) Fidelity
- 21. The degree to which an instrument indicates the changes in the measured variable without dynamic error (faithful reproduction).

- a) Speed of response
- b) Dynamic error
- c) Lag
- d) Fidelity
- 22. The type of systematic error is
  - a) Instrumental
  - b) Observational
  - c) Environmental
  - d) All above
- 23. The error that occurs due to friction in bearings of various moving components irregular spring tensions stretching of the spring or redaction in tension due to improper handling or overloading of the instrument.
  - a) Instrumental
  - b) Observational
  - c) Environmental
  - d) None of above
- 24. The error that occurs due to the effects of change in temperature humidity barometric pressure or of magnetic or electrostatic fields.
  - a) Instrumental
  - b) Observational
  - c) Environmental
  - d) None of above
- 25. The errors that may be introduced due to parallax error while reading a meter improper scale selection.
  - a) Instrumental
  - b) Observational
  - c) Environmental
  - d) None of above
- 26. These errors are due to unknown causes & occur invariably.
  - a) Instrumental
  - b) Gross errors
  - c) Systematic errors
  - d) Random errors
- 27. The process of estimating the value of a quantity by comparing it with a standard quantity.
  - a) Measurement
  - b) Measuring instrument
  - c) Calibration
  - d) Standards
- 28. The need for Calibration is
  - a) To ensure readings from an instrument are consistent with other measurements.
  - b) To determine the accuracy of the instrument readings.

- c) To establish the reliability of the instrument i.e. that it can be trusted.
- d) All of above
- 29. Operating torques in analogue instruments are
  - a) deflecting and control
  - b) deflecting and damping
  - c) deflecting, control and damping
  - d) vibration and balancing
- 30. A \_\_\_\_\_ device prevents the oscillation of the moving system and enables the latter to reach its final position quickly
  - a) Deflecting
  - b) Controlling
  - c) Damping
  - d) any of the above
- 31. The torque that is required to move the pointer on calibrated scale is
  - a) Deflecting
  - b) Controlling
  - c) Damping
  - d) any of the above
- 32. The torque that is required to control the pointer on calibrated scale
  - a) Deflecting
  - b) Controlling
  - c) Damping
  - d) any of the above
- 33. An ammeter is a
  - a) Secondary Instrument
  - b) Absolute Instrument
  - c) Recording Instrument
  - d) Integrating Instrument
- 34. The controlling torque is
  - a) Equal and in same direction as of deflecting torque
  - b) Equal and in opposite direction of deflecting torque
  - c) Equal and in same direction as of damping torque
  - d) Equal and in opposite direction of damping torque
- **35. PMMC is** 
  - a) Permanent magnet moving core
  - b) Permanent magnet moving coil
  - c) Pole magnet moving coil
  - d) Permanent magnet coil
- 36. In PMMC instrument, the magnet field is developed by using

| a) Permanent Magnets  |   |
|---|---|
| b) Electromagnets   |   |
| c) Both a) and b)   |   |
| d) None of above  |   |
| 37. In PMMC instrument, the deflecting torque is given by   |   |
| a) Td=NBIL * 2r   |   |
| b) Td=NBI * 2r  |   |
| c) Td=NBIL * r  |   |
| d) Td=NBI * R   |   |
| 38. In PMMC instrument, the controlling Torque is given by  |   |
| a) Kc * θ   |   |
| b) Kc * $\theta^2$  |   |
| c) Kd * $\theta$  |   |
| d) Kd * $\theta^2$  |   |
| 39. In any instrument, the pointer shows steady reading when  |   |
| a) Td > Tc  |   |
| b) Td < Tc  |   |
| c) Td = Tc  |   |
| d) None of Above  |   |
| 40. The scale of PMMC instrument is   |   |
| a) Uniform<br>b) Non-Uniform  |   |
| c) Cramped at the lower ends  |   |
| •   |   |
| <ul><li>d) Crowded in the middle</li><li>41. The basic PMMC movement is often called D'Arsonval movement is used to measure</li></ul> |   |
|   | • |
| a) DC only  |   |
| b) AC only  |   |
| c) Both DC & AC   |   |
| d) None of the above  |   |
| 42. In measuring instruments, spiral springs are provided to  |   |
| a) Lead current   |   |
| b) Produce controlling torque   |   |
| c) Produce damping torque   |   |
| d) Lead current and produce controlling torque  |   |
| 43. In Moving iron instrument, the basic principle of is used.  |   |
| <ul><li>a) Faradays Law of Electromagnetic Induction</li><li>b) Principle of Force of Attraction or Force of Repulsion</li></ul>      |   |
| c) Induction Principle  |   |
| d) Electrostatic Principle  |   |
| 44. In Repulsion Type MI instrument, the number of Iron Pieces used is  |   |
| a) One  |   |

- b) Two
- c) Three
- d) Zero
- 45. In Attraction Type MI instrument, the number of Iron Pieces used is
  - a) One
  - b) Two
  - c) Three
  - d) Zero
- 46. MI instrument can be used for the measurement of
  - a) AC Only
  - b) DC Only
  - c) AC and DC
  - d) None of Above
- 47. The scale of MI Instrument is
  - a) Uniform
  - b) Non-Uniform
  - c) Cramped at the lower ends
  - d) Crowded in the middle
- 48. The circuit shown below is a



- a) Basic Voltmeter
- b) Basic Wattmeter
- c) Basic Ammeter
- d) All of Above
- 49. The equation for Shunt Resistance is

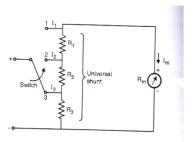
a) Rsh= 
$$\frac{Rm}{\frac{I}{Im}-I}$$

b) Rsh= 
$$\frac{Rm}{\frac{Im}{I}-I}$$

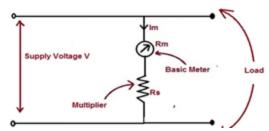
c) Rsh= 
$$\frac{Rm}{\frac{l}{lm}-1}$$

d) Rsh= 
$$\frac{Rm}{\frac{Im}{I}-1}$$

50. The circuit shown below is a



- a) Practical Voltmeter
- b) Practical Ammeter
- c) Practical Wattmeter
- d) None of Above
- 51. The circuit shown below is a



- a) Basic Voltmeter
- b) Multirange Voltmeter
- c) Basic Ammeter
- d) Multirange Ammeter
- 52. The equation for Series resistance is

a) 
$$\frac{V}{i} - 1$$

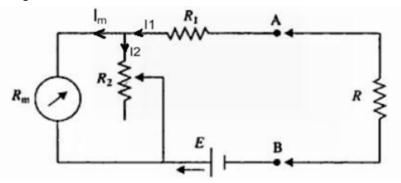
b) 
$$\frac{i}{V} - 1$$

c) 
$$\frac{V}{i}$$
 - Rm

d) 
$$\frac{i}{V}$$
 - Rm

- 53. In which Ohmmeter the meter is connected in parallel to the resistance which is to be measured.
  - a) Series type Ohmmeter
  - b) Shunt Type Ohmmeter
  - c) Both
  - d) None of Above
- 54. In which Ohmmeter the meter is connected in series to the resistance which is to be measured.
  - a) Series type Ohmmeter
  - b) Shunt Type Ohmmeter

- c) Both
- d) None of Above
- 55. The given circuit is a



- a) Series type Ohmmeter
- b) Shunt Type Ohmmeter
- c) Both
- d) None of Above
- 56. The type of Moving Iron Instrument is
  - a) Attraction Type
  - b) Repulsion Type
  - c) Both a) and b)
  - d) None of Above
- 57. A moving coil instrument has an internal resistance of 10  $\Omega$  and full scale deflection of 40 mA. The shunt resistance required to convert this instrument for use as an ammeter of range of 0 to 2A is:
  - a)  $0.1021 \Omega$
  - b) 0.2041 Ω
  - c) 0.2561 Ω
  - d) 0.4210 Ω
- 58. A moving coil instrument has a internal resistance of 20  $\Omega$  and a full scale deflection of 100mA. The value of series resistor required to measure a voltage of 400V is,
  - a) 3980m Ω
  - b)  $3.980M \Omega$
  - c) 3890 Ω
  - d) 3980 Ω
- 59. Clamp meter is used for the measurement of
  - a) Large Alternating current
  - b) Small Alternating Current
  - c) Small Direct Current
  - d) Large Direct current
- 60. Clamp meter uses a \_\_\_\_\_\_ for its measurement
  - a) Potential Transformer

## b) Current Transformer

- c) Series Resistor
- d) Shunt Resistor