

SYSTEM REPORT

SYSTEM DIAGRAM

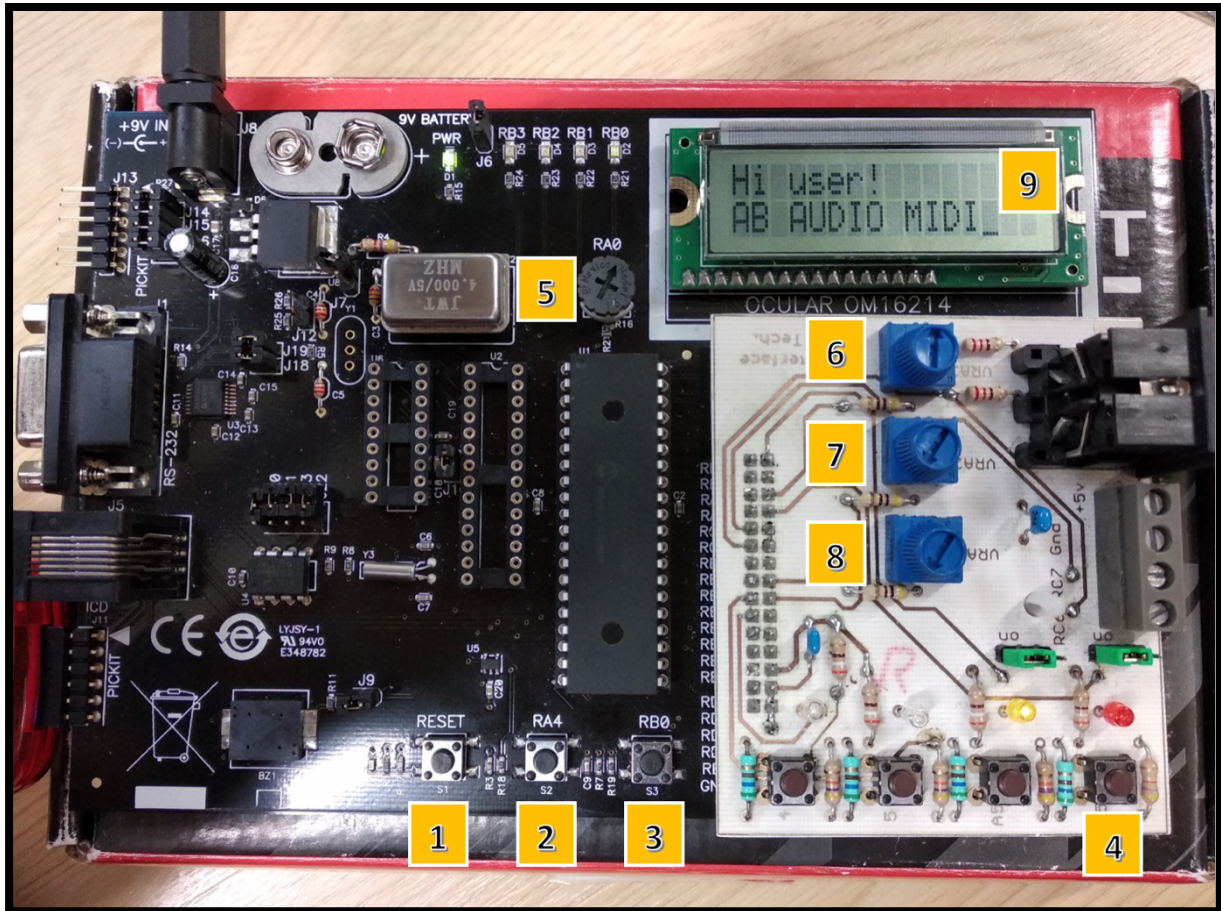


Figure 1: System

Figure 1 displays the system. Labelled are the interactive elements offered by it:

- 1 - **RESET**: pressing this button will reboot the system
- 2 - **RA4**: pressing this button allows the user to cycle through editable parameters
- 3 - **RB0**: pressing this button allows the user to cycle through MIDI Channels
- 4 - **RC5**: pressing this button will send a Note on MIDI message with the parameters set by the user, followed by a Note off MIDI message.
- 5 - **RA0**: this potentiometer allows the user to set the Note number, from 0 to 127.
- 6 - **VRA3**: this potentiometer allows the user to vary Pan.
- 7 - **VRA2**: this potentiometer allows the user to vary Modulation.
- 8 - **VRA1**: this potentiometer allows the user to set the Velocity value, from 1-127.
- 9 - **LCD** screen: this screen provides instant feedback to the user.

SYSTEM FLOWCHART

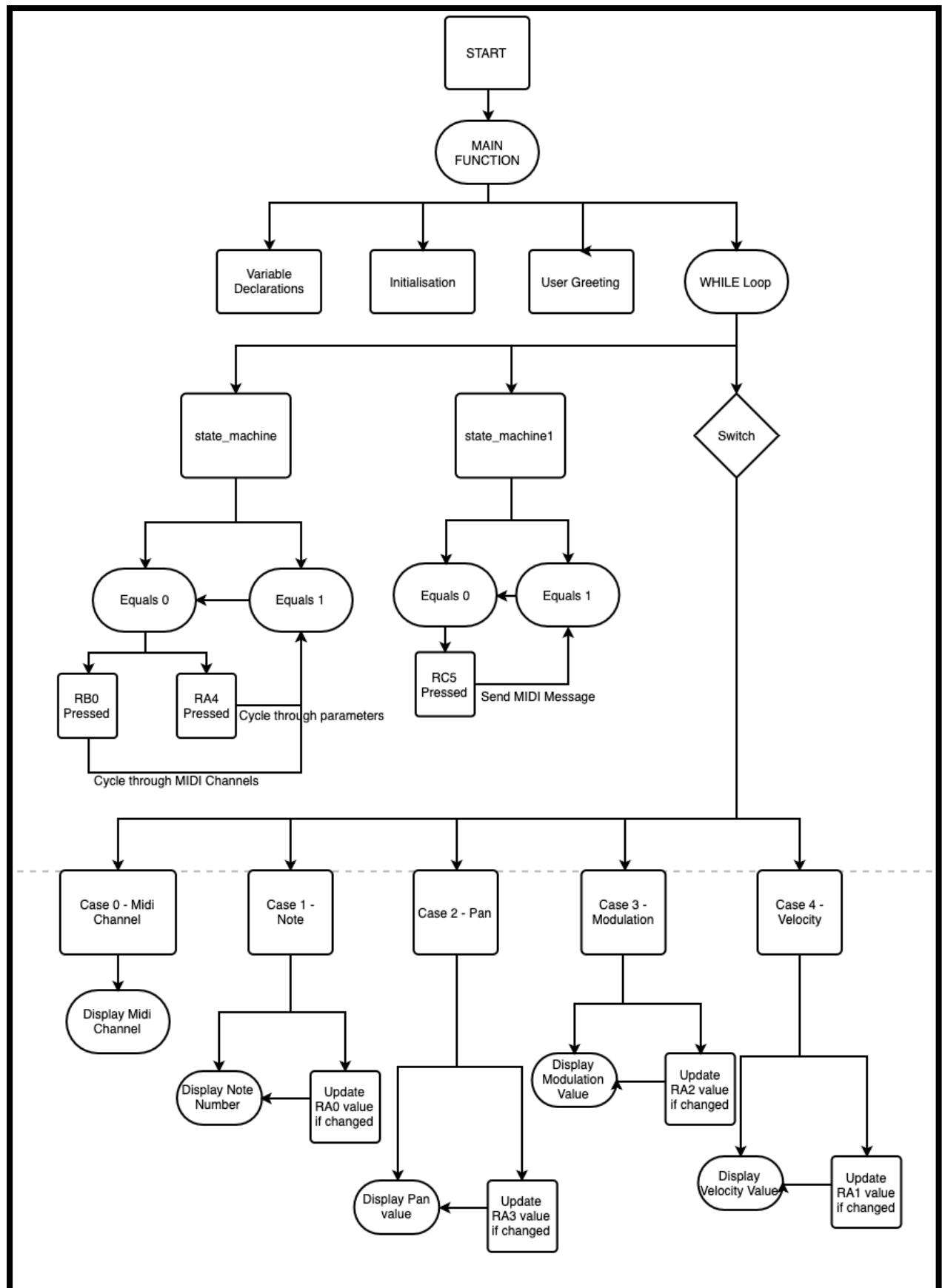


Figure 2: System Flowchart

USER GUIDE

When started, the LCD screen will light up and greet the user. After a few seconds, the screen will change to display the selected MIDI Channel, defaulting to channel 1. The user can select from channel 1 to channel 10 by pressing RB0. After channel 10 the system will cycle back to channel 1 if RB0 is pressed.

The user can cycle between 5 different parameters – MIDI Channel, Note, Pan, Modulation and Velocity – by pressing RA4.

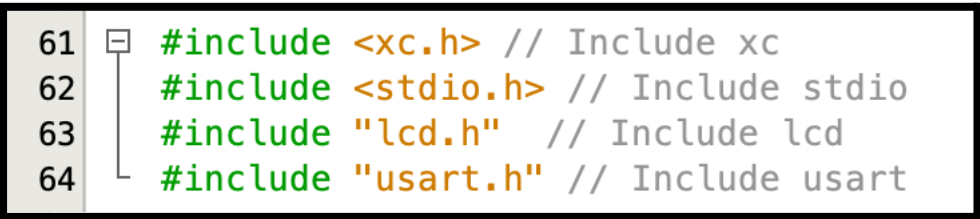
The 4 potentiometers offered by the system allow the user to change the parameters:

- RA0 changes note value (0:127)
- VRA3 changes Pan (-64:64)
- VRA2 changes Modulation (0:127)
- VRA1 changes Velocity (1:127)

Each of these parameters can be changed even when not being displayed, ie. If the Pan potentiometer is changed whilst Velocity is being displayed on the screen, the Pan value will still change. However, in order to confirm the change, the user must display the Pan value on the screen.

If RC5 is pressed, the system will send a MIDI note on message with the set values, followed shortly by a note off message.

TECHNICAL DESCRIPTION OF CODE



```
61 #include <xc.h> // Include xc
62 #include <stdio.h> // Include stdio
63 #include "lcd.h" // Include lcd
64 #include "usart.h" // Include usart
```

Figure 3

Figure 3 shows the #include statements at the start of the code, which are necessary in order for the whole program to work correctly.

```
67 void pause (int j) //Pause
68 {
69     int i;
70     for(i=0;i<=j;++i)
71     {
72         __delay_ms(1);
73     }
74 }
```

Figure 4

Figure 4 shows the declaration of the pause function, which will be used later to hold the user greeting for a few seconds.

```
77 void init(void){ //Initialisation
78     // Set I/O
79     TRISA = 0b00011111; // Enable RA0, RA1, RA2, RA3, RA4 as input, the rest will be outputs
80     TRISB = 0x01; // RB0 input
81     TRISC = 0b00100000; // C5 as an input
82     TRISD = 0; // Port D as an output
83
84     PORTB = 0;
85     ADCON1 = 0b00000111; // Set analogue/digital channels
86     ADFM = 1; // Make sure Right Justification is on
87     ADIE = 0; // not interrupt driven
88     ADON = 1; // Switch on the ADC module
89
90     USARTInit(); // Initialise USART
91     lcd_init(); // Initialise LCD
92 }
93
```

Figure 5

Figure 5 shows the init function (initialisation). Inputs and Outputs are set on Ports A, B, C and D. Furthermore, the ADC parameters are set to work accordingly to our needs. The potentiometers are set as analogue channels whereas everything else is set as digital. Finally the USARTInit and lcd_init functions are called, initialising the USART and the lcd screen.

```
95 void main(void){
96     unsigned char midiChannel = 0; // MIDI Channel variable
97     unsigned char note = 0; // Selected note variable
98     unsigned char pan = 0; // Pan variable
99     unsigned char mod = 0; // Modulation variable
100    unsigned char velocity = 1; // Velocity variable
101    unsigned char outString[15] = ""; // OutString for writing into lcd
102
103    unsigned char adc_left, adc_right; // ADC values
104
105    int adc_new, last_value; // Manipulated ADC values
106
107    int state_machine = 0; // Variables that will be used for menu system
108    int state_machine1 = 0; // Variables that will be used for menu system
109    int updatePan = 0; // Used to update Pan
110    int updateMod = 0; // Used to update Mod
111    int parameter = 0; // Variables that will be used for menu system
112
113    init();
114}
```

Figure 6

Figure 6 shows the start of the main function, where all the variables are declared. midiChannel, note, pan, mod and velocity will be used to hold the values of each parameter (MIDI Channel, Note, Pan, Modulation and Velocity). outString is used for writing into the LCD screen. adc_left and adc_right will be used to hold values read from the ADC. adc_new and last_value will be used for manipulated ADC values. The integer variables will be used on if statements for menu systems and so the system knows if to update values or not. Finally, the init function is called, initialising the system.

```
115    lcd_goto(0); // select first line
116    lcd_puts("Hi user!"); // Greet user
117    lcd_goto(0x40); // select second line
118    lcd_puts("AB AUDIO MIDI"); // Device name
119
120    pause(3000); // Pause for a bit
121    lcd_clear(); // Clear screen
122
```

Figure 7

Figure 7 shows the code responsible for greeting the user. After 3000 milliseconds, the screen is cleared.

```

124     while(1){ // While system is running
125
126         if((PORTBbits.RB0==0)&&(state_machine==0)){ // RB0 button press, state_machine = 0
127             midiChannel++; // Increase MIDI Channel by 1
128             state_machine = 1; // Change state machine
129         }
130         if((PORTAbits.RA4==0)&&(state_machine==0)){ // RA4 button press, state_machine = 0
131             lcd_clear(); // Clear screen
132             parameter++; // increase parameter
133             state_machine = 1; // Change state machine
134         }
135         if((PORTAbits.RA4==1)&&(PORTBbits.RB0==1)&&(state_machine==1)){ // No button press, state_machine = 1
136             state_machine = 0; // Change state machine back to its original value
137         }
138
139         if(parameter > 4) // If parameter = 5 (5th menu element)
140         {
141             parameter = 0; // Go back to first element (cycle completed)
142         }
143         if(midiChannel > 9) // If Midi Channel > 10
144         {
145             lcd_clear(); // Clear screen
146             lcd_goto(0); // select first line
147             lcd_puts("Midi Channel:"); // Write Midi Channel
148             midiChannel = 0; // Cycle through back to first channel
149         }
150     }

```

Figure 8

Figure 8 shows the start of the while loop.

When state_machine equals 0, if RB0 is pressed, the value of midiChannel will increase by 1. state_machine will then equal 1, making the if irrelevant so that one RB0 button press increases midiChannel by only 1, no matter how long it is held for. Once the user lets go of RB0 state_machine will change back to 0, allowing for another button press that will increase midiChannel.

The same system is used with RA4, which will vary parameter, a variable that will be used later in the menu system on the switch.

The two if statements at the end are used to limit the number of MIDI channels to 10, and the parameters to 5 (as there are 5 possible parameters).

```

152     //Menu System
153     switch (parameter) // Menu System
154     {
155         case 0: // MIDI Channel
156             lcd_goto(0); // select first line
157             lcd_puts("Midi Channel:"); // Write Midi Channel
158
159             int channelNumber = 1+midiChannel; // As 0 = Channel 1, we need to equate the values
160             sprintf(outString, "%d", channelNumber); // Prepare to write the channel
161             lcd_goto(0x40); // select second line
162             lcd_puts(outString); // Write the channel
163
164             break;

```

Figure 9

Figure 9 shows the start of the switch code and the first and default case (MIDI Channel). As the screen was last cleared, text can be written into the LCD using lcd_puts. channelNumber is used so that the channel number displayed is the same as the channel selected, as a value of 0 is channel 1. The channel number is then written onto the second line of the LCD screen.

```
166 case 1: // Note
167     lcd_goto(0); // select first line
168     lcd_puts("Note:"); // Write Note
169
170     sprintf(outString,"%d",note); // Prepare to write the note
171     lcd_goto(0x40); // select second line
172     lcd_puts(outString); // Write the note
173
174     //ADC bit
175     ADCON0=0b00000011; // Read from RA0
176     NOP(); // Wait 4 uS NOP() as detailed in the data sheet
177     NOP(); //
178     NOP(); // We need to wait a minimum of 4uS between switching channels
179     NOP();
180     GODONE=1; // Start a conversion on channel 0
181     while(GODONE)continue;
182     ADIF=0; // Clear the end of conversion flag
183     adc_left=ADRESL; // Read the lower bits of the ADC results
184     adc_right = ADRESH; // Read the upper bits of the ADC results
185
186     adc_new = adc_right<<8;
187     adc_new = adc_left + adc_new;
188     adc_new = adc_new>>3;
189     note = adc_new; // set note as ADC value
190
191     if(adc_new!=last_value){
192         lcd_clear(); // Clear screen if the value is different
193     }
194     last_value=adc_new;
195     break;
196
```

Figure 10

Figure 10 shows the code for case 1 (Note). The first set of lines are basically the same as those in case 0, handling the writing onto the LCD screen. Starting on line 175 is code used for ADC handling. The comments describe what each line does. Starting on line 186 is code that manipulates the ADC values to get a value that can be usable by MIDI. The if statement on line 191 will clear the lcd screen if the note value has been changed.

```
197 case 2: // Pan
198     lcd_goto(0); // select first line
199     lcd_puts("Pan:"); // Write pan
200
201     int panValue = pan - 64; // Change how pan value is displayed
202     sprintf(outString,"%d",panValue); // Prepare to write pan
203     lcd_goto(0x40); // select second line
204     lcd_puts(outString); // Write the pan value
205
206     //ADC bit
207     ADCON0=0b00001111; // Read from VRA3
208     NOP(); // Wait 4 uS NOP() as detailed in the data sheet
209     NOP(); //
210     NOP(); // We need to wait a minimum of 4uS between switching channels
211     NOP();
212     GODONE=1; // Start a conversion on channel 0
213     while(GODONE)continue;
214     ADIF=0; // Clear the end of conversion flag
215     adc_left=ADRESL; // Read the lower bits of the ADC results
216     adc_right = ADRESH; // Read the upper bits of the ADC results
217
218     adc_new = adc_right<<8;
219     adc_new = adc_left + adc_new;
220     adc_new = adc_new>>3;
221     pan = adc_new; // set pan as ADC value
222
223     if((updatePan == 0)&&(pan==last_value)){
224         USARTWriteByte(176 + midiChannel); // Control Value on Channel 1
225         USARTWriteByte(0x0A); // Control Pan
226         USARTWriteByte(pan); // pan value
227         updatePan = 1;
228     }
229     if(adc_new!=last_value){
230         lcd_clear(); // Clear screen if the value is different
231         updatePan = 0;
232     }
233     last_value=adc_new;
234     break;
235
```

Figure 11

Figure 11 shows the code for case 2 (Pan). It's basically the same as that for case 1, except for the if statement on line 223. This if statement will send MIDI messages updating the pan value if it has been changed.

```
236 case 3: // Modulation
237     lcd_goto(0); // select first line
238     lcd_puts("Mod Value:"); // Write Mod Value
239
240     sprintf(outString,"%d",mod); // Prepare to write mod value
241     lcd_goto(0x40); // select second line
242     lcd_puts(outString); // Write the mod value
243
244     //ADC bit
245     ADCON0=0b00001011; // Read from VRA2
246     NOP(); // Wait 4 uS NOP() as detailed in the data sheet
247     NOP(); //
248     NOP(); // We need to wait a minimum of 4uS between switching channels
249     NOP();
250     GODONE=1; // Start a conversion on channel 0
251     while(GODONE)continue;
252     ADIF=0; // Clear the end of conversion flag
253     adc_left=ADRESL; // Read the lower bits of the ADC results
254     adc_right = ADRESH; // Read the upper bits of the ADC results
255
256     adc_new = adc_right<<8;
257     adc_new = adc_left + adc_new;
258     adc_new = adc_new>>3;
259     mod = adc_new; // set mod as ADC value
260
261     if((updateMod == 0)&&(mod==last_value)){
262         USARTWriteByte(176 + midiChannel); // Control Value on Channel 1
263         USARTWriteByte(0x01); // Control Mod
264         USARTWriteByte(pan); // mod value
265         updateMod = 1;
266     }
267
268     if(adc_new!=last_value){
269         lcd_clear(); // Clear screen if the value is different
270         updateMod = 0;
271     }
272     last_value=adc_new;
273     break;
274
```

Figure 12

Figure 12 shows the code for case 3 (modulation). It's basically the same as that for case 2 but using different variables.

```

275     case 4: // Velocity
276         lcd_goto(0); // select first line
277         lcd_puts("Velocity:"); // Write velocity
278
279         sprintf(outString,"%d",velocity); // Prepare to write velocity value
280         lcd_goto(0x40); // select second line
281         lcd_puts(outString); // Write the velocity value
282
283         //ADC bit
284         ADCON0=0b00000111; // Read from VRA1
285         NOP(); // Wait 4 uS NOP() as detailed in the data sheet
286         NOP(); //
287         NOP(); // We need to wait a minimum of 4uS between switching channels
288         NOP();
289         GODONE=1; // Start a conversion on channel 0
290         while(GODONE)continue;
291         ADIF=0; // Clear the end of conversion flag
292         adc_left=ADRESL; // Read the lower bits of the ADC results
293         adc_right = ADRESH; // Read the upper bits of the ADC results
294
295         adc_new = adc_right<<8;
296         adc_new = adc_left + adc_new;
297         adc_new = adc_new>>3;
298         velocity = adc_new + 1; // Set velocity as ADC value + 1 in order to not get velocity = 0
299
300         if(velocity>127){ // If velocity = 128
301             velocity=127; // set velocity as 127
302         }
303         if(adc_new!=last_value){
304             lcd_clear(); // Clear screen if the value is different
305         }
306         last_value=adc_new;
307         break;
308     }
309 }
310

```

Figure 13

Figure 13 shows the code for case 4 (Velocity). It's basically the same as that of case 1 except for the if statement on line 300. On line 298 the minimum velocity is set to 1 as if the user sets it to 0 using the potentiometer it will be 1 as 1 has been added to it. The if statement limits the maximum to 127, as due to the previous addition it could now be 128.

```

311 //Send MIDI Message
312 if((PORTCbits.RC5==0)&&(state_machine1==0)){ // RC5 button press, state_machine1 = 0
313     state_machine1=1; // Set state_machine1 as 1
314 }
315
316 if ((PORTCbits.RC5==1)&&(state_machine1==1)){ // No RC5 press, state_machine1 = 1
317     state_machine1=0; // set state_machine1 back to its original value
318
319     USARTWriteByte(144 + midiChannel); // NoteOn on selected channel
320     USARTWriteByte(note); // Note
321     USARTWriteByte(velocity); // Velocity
322     pause(1000);
323     USARTWriteByte(128 + midiChannel); // NoteOff on selected channel
324     USARTWriteByte(note); // Note
325     USARTWriteByte(velocity); // Velocity
326
327 }
328
329
330 }
331 }
332 }
333

```

Figure 14

Figure 14 shows the final code of the program, which handles MIDI message sending. If RC5 is pressed, a MIDI note on message will be sent using the variables

declared, which will have values set by the user. After a second, a MIDI note off message is sent.

CHECKLIST

CRITERIA	MET?
Multiplexing of 3 or more inputs	Yes.
Two or more analogue inputs	Yes.
One external control	Yes.
1 or more forms of feedback	Yes.
Effective programming of ADCs	Yes.
Signal conditioning on controls	Yes.
MIDI routines functional and demonstratable	Yes.
Dynamic control	Yes.
Selection of a different MIDI channel under user control	Yes.
Appropriate MIDI message depending on controller types required to control an external source	Yes.
Effective programming of the PIC using interrupts where applicable	No interrupts.
Control Pitch, Amplitude of one or more audio inputs	Yes.