SYSTEM REPORT

SYSTEM DIAGRAM

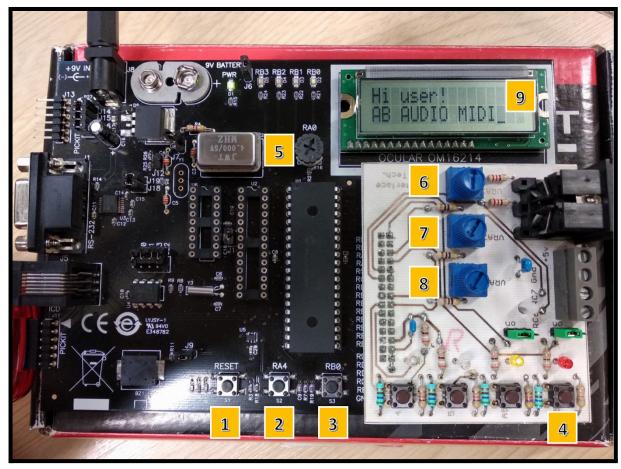


Figure 1: System

Figure 1 displays the system. Labelled are the interactive elements offered by it:

- 1 **RESET**: pressing this button will reboot the system
- 2 RA4: pressing this button allows the user to cycle through editable parameters
- 3 **RB0**: pressing this button allows the user to cycle through MIDI Channels
- 4 **RC5**: pressing this button will send a Note on MIDI message with the parameters set by the user, followed by a Note off MIDI message.
- 5 **RA0**: this potentiometer allows the user to set the Note number, from 0 to 127.
- 6 **VRA3**: this potentiometer allows the user to vary Pan.
- 7 **VRA2**: this potentiometer allows the user to vary Modulation.
- 8 **VRA1**: this potentiometer allows the user to set the Velocity value, from 1-127.
- 9 **LCD** screen: this screen provides instant feedback to the user.

SYSTEM FLOWCHART

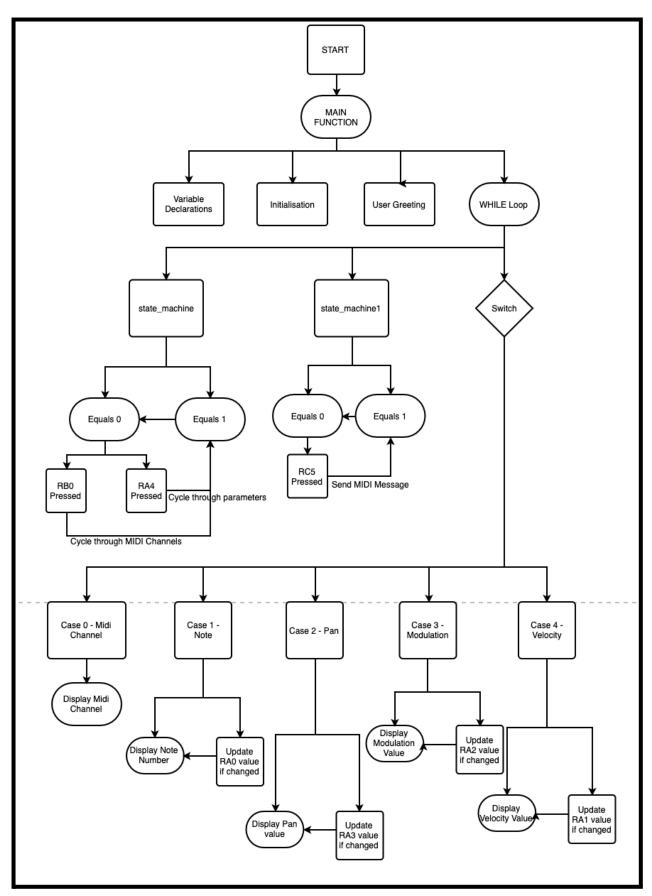


Figure 2: System Flowchart

USER GUIDE

When started, the LCD screen will light up and greet the user. After a few seconds, the screen will change to display the selected MIDI Channel, defaulting to channel 1. The user can select from channel 1 to channel 10 by pressing RB0. After channel 10 the system will cycle back to channel 1 if RB0 is pressed.

The user can cycle between 5 different parameters – MIDI Channel, Note, Pan, Modulation and Velocity – by pressing RA4.

The 4 potentiometers offered by the system allow the user to change the parameters:

- RA0 changes note value (0:127)
- VRA3 changes Pan (-64:64)
- VRA2 changes Modulation (0:127)
- VRA1 changes Velocity (1:127)

Each of these parameters can be changed even when not being displayed, ie. If the Pan potentiometer is changed whilst Velocity is being displayed on the screen, the Pan value will still change. However, in order to confirm the change, the user must display the Pan value on the screen.

If RC5 is pressed, the system will send a MIDI note on message with the set values, followed shortly by a note off message.

TECHNICAL DESCRIPTION OF CODE

```
61  #include <xc.h> // Include xc
62  #include <stdio.h> // Include stdio
63  #include "lcd.h" // Include lcd
64  #include "usart.h" // Include usart
```

Figure 3

Figure 3 shows the #include statements at the start of the code, which are necessary in order for the whole program to work correctly.

Figure 4

Figure 4 shows the declaration of the pause function, which will be used later to hold the user greeting for a few seconds.

```
void init(void){ //Initialisation
78
          // Set I/0
          TRISA = 0b00011111; // Enable RA0, RA1, RA2, RA3, RA4 an input, the rest will be outputs
79
          TRISB = 0x01; // RB0 input
80
81
          TRISC = 0b00100000; // C5 as an input
          TRISD = 0; // Port D as an output
82
83
84
          PORTB = 0;
          ADCON1 = 0b00000111; // Set analogue/digital channels
85
          ADFM = 1; // Make sure Right Justification is on
86
          ADIE = 0; // not interrupt driven
ADON = 1; // Switch on the ADC module
87
88
89
90
          USARTInit(); // Initialise USART
          lcd_init(); // Initialise LCD
91
92
```

Figure 5

Figure 5 shows the init function (initialisation). Inputs and Outputs are set on Ports A, B, C and D. Furthermore, the ADC parameters are set to work accordingly to our needs. The potentiometers are set as analogue channels whereas everything else is set as digital. Finally the USARTInit and Icd_init functions are called, initialising the USART and the Icd screen.

```
□ void main(void){
96
          unsigned char midiChannel = 0; // MIDI Channel variable
97
          unsigned char note = 0; // Selected note variable
          unsigned char pan = 0; // Pan variable
98
          unsigned char mod = 0; // Modulation variable
99
100
          unsigned char velocity = 1; // Velocity variable
          unsigned char outString[15] = ""; // OutString for writing into lcd
101
102
          unsigned char adc_left, adc_right; // ADC values
103
104
          int adc_new, last_value; // Manipulated ADC values
105
106
107
          int state_machine = 0; // Variables that will be used for menu system
           int state_machine1 = 0; // Variables that will be used for menu system
108
          int updatePan = 0; // Used to update Pan
109
          int updateMod = 0; // Used to update Mod
110
          int parameter = 0; // Variables that will be used for menu system
111
112
113
           init();
```

Figure 6

Figure 6 shows the start of the main function, where all the variables are declared. midiChannel, note, pan, mod and velocity will be used to hold the values of each parameter (MIDI Channel, Note, Pan, Modulation and Velocity). outString is used for writing into the LCD screen. adc_left and adc_right will be used to hold values read from the ADC. adc_new and last_value will be used for manipulated ADC values. The integer variables will be used on if statements for menu systems and so the system knows if to update values or not.

Finally, the init function is called, initialising the system.

Figure 7

Figure 7 shows the code responsible for greeting the user. After 3000 miliseconds, the screen is cleared.

```
125
               if((PORTBbits.RB0==0)&&(state_machine==0)){ // RBO button press, state_machine = 0
126
                   midiChannel++; // Increase MIDI Channel by 1
                   state_machine = 1; // Change state machine
128
129
               if((PORTAbits.RA4==0)&&(state machine==0)){ // RA4 button press, state machine = 0
130
131
                   lcd_clear(); // Clear screen
parameter++; // increase parameter
133
                   state_machine = 1; // Change state machine
134
               if((PORTAbits.RA4==1)&&(PORTBbits.RB0==1)&&(state_machine==1)){ // No button press, state_machine = 1
135
                   state_machine = 0; // Change state machine back to its original value
               }
137
138
               if(parameter > 4) // If parameter = 5 (5th menu element)
139
140
                   parameter = 0; // Go back to first element (cycle completed)
142
               if(midiChannel > 9) // If Midi Channel > 10
143
144
145
                    lcd_clear(); // Clear screen
146
                   lcd_puts("Midi Channel:"); // Write Midi Channel
147
148
                   midiChannel = 0; // Cycle through back to first channel
149
```

Figure 8

Figure 8 shows the start of the while loop.

When state_machine equals 0, if RB0 is pressed, the value of midiChannel will increase by 1. state_machine will then equal 1, making the if irrelevant so that one RB0 button press increases midiChannel by only 1, no matter how long it is held for. Once the user lets go of RB0 state_machine will change back to 0, allowing for another button press that will increase midiChannel.

The same system is used with RA4, which will vary parameter, a variable that will be used later in the menu system on the switch.

The two if statements at the end are used to limit the number of MIDI channels to 10, and the parameters to 5 (as there are 5 possible parameters).

```
153
               switch (parameter) // Menu System
154
                   case 0: // MIDI Channel
155
                   lcd_goto(0); // select first line
156
                   lcd_puts("Midi Channel:"); // Write Midi Channel
157
158
                   int channelNumber = 1+midiChannel; // As 0 = Channel 1, we need to equate the values
159
                   sprintf(outString,"%d",channelNumber); // Prepare to write the channel
160
                   lcd_goto(0x40); // select second line
161
162
                   lcd_puts(outString); // Write the channel
163
164
                   break:
```

Figure 9

Figure 9 shows the start of the switch code and the first and default case (MIDI Channel). As the screen was last cleared, text can be written into the LCD using Icd_puts. channelNumber is used so that the channel number displayed is the same as the channel selected, as a value of 0 is channel 1. The channel number is then written onto the second line of the LCD screen.

```
166
                   case 1: // Note
167
                   lcd_goto(0);
                                   // select first line
                   lcd_puts("Note:"); // Write Note
168
169
                   sprintf(outString,"%d",note); // Prepare to write the note
170
                   lcd_goto(0x40); // select second line
171
                   lcd_puts(outString); // Write the note
172
173
174
                   //ADC bit
                   ADCON0=0b00000011; // Read from RA0
175
                   NOP(); // Wait 4 uS NOP() as detailed in the data sheet
176
                   NOP(); //
177
178
                   NOP(); // We need to wait a minimum of 4uS between switching channels
179
                   NOP();
                   GODONE=1; // Start a conversion on channel 0
180
181
                   while(GODONE)continue;
                   ADIF=0; // Clear the end of conversion flag
182
183
                   adc_left=ADRESL; // Read the lower bits of the ADC results
184
                   adc_right = ADRESH; // Read the upper bits of the ADC results
185
186
                   adc_new = adc_right<<8;
                   adc_new = adc_left + adc_new;
187
188
                   adc_new = adc_new>>3;
189
                   note = adc_new; // set note as ADC value
190
191
                   if(adc_new!=last_value){
                                     // Clear screen if the value is different
192
                       lcd_clear();
193
                   last_value=adc_new;
194
195
                   break;
```

Figure 10

Figure 10 shows the code for case 1 (Note). The first set of lines are basically the same as those in case 0, handling the writing onto the LCD screen. Starting on line 175 is code used for ADC handling. The comments describe what each line does. Starting on line 186 is code that manipulates the ADC values to get a value that can be usable by MIDI. The if statement on line 191 will clear the lcd screen if the note value has been changed.

```
197
                   case 2: // Pan
                   lcd_goto(0);
198
                                   // select first line
                   lcd_puts("Pan:"); // Write pan
199
200
                   int panValue = pan - 64; // Change how pan value is displayed
201
                   sprintf(outString,"%d",panValue); // Prepare to write pan
202
                   lcd goto(0x40); // select second line
203
204
                   lcd_puts(outString); // Write the pan value
205
206
                   //ADC bit
                   ADCON0=0b00001111; // Read from VRA3
207
208
                   NOP(); // Wait 4 uS NOP() as detailed in the data sheet
                   NOP(); //
209
                   NOP(); // We need to wait a minimum of 4uS between switching channels
210
211
                   NOP();
                   GODONE=1; // Start a conversion on channel 0
212
213
                   while(GODONE)continue;
                   ADIF=0; // Clear the end of conversion flag
214
215
                   adc_left=ADRESL; // Read the lower bits of the ADC results
                   adc_right = ADRESH; // Read the upper bits of the ADC results
216
217
218
                   adc_new = adc_right<<8;
219
                   adc_new = adc_left + adc_new;
220
                   adc_new = adc_new>>3;
221
                   pan = adc_new; // set pan as ADC value
222
                   if((updatePan == 0)&&(pan==last_value)){
223
                       USARTWriteByte(176 + midiChannel); // Control Value on Channel 1
224
                       USARTWriteByte(0x0A); // Control Pan
225
226
                       USARTWriteByte(pan); // pan value
227
                       updatePan = 1;
228
229
                   if(adc_new!=last_value){
                       lcd_clear();
230
                                       // Clear screen if the value is different
231
                       updatePan = 0;
232
                   last_value=adc_new;
233
234
                   break;
235
```

Figure 11

Figure 11 shows the code for case 2 (Pan). It's basically the same as that for case 1, except for the if statement on line 223. This if statement will send MIDI messages updating the pan value if it has been changed.

```
236
                   case 3: // Modulation
237
                   lcd_goto(0);
                                   // select first line
                   lcd_puts("Mod Value:"); // Write Mod Value
238
239
                   sprintf(outString,"%d",mod); // Prepare to write mod value
240
                   lcd_goto(0x40); // select second line
241
                   lcd_puts(outString); // Write the mod value
242
243
244
                   //ADC bit
                   ADCON0=0b00001011; // Read from VRA2
245
246
                   NOP(); // Wait 4 uS NOP() as detailed in the data sheet
                   NOP(); //
247
248
                   NOP(); // We need to wait a minimum of 4uS between switching channels
249
                   NOP();
                   GODONE=1; // Start a conversion on channel 0
250
                   while(GODONE)continue;
251
252
                   ADIF=0; // Clear the end of conversion flag
253
                   adc_left=ADRESL; // Read the lower bits of the ADC results
                   adc_right = ADRESH; // Read the upper bits of the ADC results
254
255
                   adc_new = adc_right<<8;
256
257
                   adc_new = adc_left + adc_new;
                   adc_new = adc_new>>3;
258
259
                   mod = adc_new; // set mod as ADC value
260
                   if((updateMod == 0)&&(mod==last_value)){
261
                       USARTWriteByte(176 + midiChannel); // Control Value on Channel 1
262
263
                       USARTWriteByte(0x01); // Control Mod
                       USARTWriteByte(pan); // mod value
264
                       updateMod = 1;
265
266
267
                   if(adc_new!=last_value){
268
                       lcd_clear();
                                       // Clear screen if the value is different
269
270
                       updateMod = 0;
271
                   last_value=adc_new;
272
                   break;
273
```

Figure 12

Figure 12 shows the code for case 3 (modulation). It's basically the same as that for case 2 but using different variables.

```
lcd_goto(0);
276
                                   // select first line
                   lcd_puts("Velocity:"); // Write velocity
277
278
                   sprintf(outString,"%d",velocity); // Prepare to write velocity value
279
                   lcd_goto(0x40); // select second line
280
281
                   lcd_puts(outString); // Write the velocity value
282
283
                   //ADC hit
284
                   ADCON0=0b00000111; // Read from VRA1
285
                   NOP(); // Wait 4 uS NOP() as detailed in the data sheet
286
                   NOP(); //
                   NOP(); // We need to wait a minimum of 4uS between switching channels
287
288
                   NOP();
                   GODONE=1; // Start a conversion on channel 0
289
                   while(GODONE)continue;
290
                   ADIF=0; // Clear the end of conversion flag
291
292
                   adc_left=ADRESL; // Read the lower bits of the ADC results
                   adc_right = ADRESH; // Read the upper bits of the ADC results
293
294
295
                   adc_new = adc_right<<8;
296
                   adc_new = adc_left + adc_new;
                   adc_new = adc_new>>3;
297
                   velocity = adc_new + 1; // Set velocity as ADC value + 1 in order to not get velocity = 0
298
299
                   if(velocity>127){ // If velocity = 128
300
                       velocity=127; // set velocity as 127
301
302
                   if(adc_new!=last_value){
303
                                        // Clear screen if the value is different
304
                       lcd clear();
305
306
                   last_value=adc_new;
307
                   break:
308
               }
309
```

Figure 13

Figure 13 shows the code for case 4 (Velocity). It's basically the same as that of case 1 except for the if statement on line 300. On line 298 the minimum velocity is set to 1 as if the user sets it to 0 using the potentiometer it will be 1 as 1 has been added to it. The if statement limits the maximum to 127, as due to the previous addition it could now be 128.

```
312
               if((PORTCbits.RC5==0)&&(state_machine1==0)){ // RC5 putton press, state_machine1 = 0
313
               state_machine1=1; // Set state_machine1 as 1
314
315
316
               if ((PORTCbits.RC5==1)&&(state_machine1==1)){ // No RC5 press, state_machine1 = 1
317
                   state_machine1=0; // set state_machine1 back to its original value
318
319
                   USARTWriteByte(144 + midiChannel); // NoteOn on selected channel
                   USARTWriteByte(note); // Note
320
                   USARTWriteByte(velocity); // Velocity
321
                   pause(1000);
322
323
                   USARTWriteByte(128 + midiChannel); // NoteOff on selected channel
324
                   USARTWriteByte(note); // Note
325
                   USARTWriteByte(velocity); // Velocity
326
327
328
329
330
331
          }
      }
332
333
```

Figure 14

Figure 14 shows the final code of the program, which handles MIDI message sending. If RC5 is pressed, a MIDI note on message will be sent using the variables

declared, which will have values set by the user. After a second, a MIDI note off message is sent.

CHECKLIST

CRITERIA	MET?
Multiplexing of 3 or more inputs	Yes.
Two or more analogue inputs	Yes.
One external control	Yes.
1 or more forms of feedback	Yes.
Effective programming of ADCs	Yes.
Signal conditioning on controls	Yes.
MIDI routines functional and	Yes.
demonstratable	
Dynamic control	Yes.
Selection of a different MIDI channel	Yes.
under user control	
Appropriate MIDI message depending	Yes.
on controller types required to control	
an external source	
Effective programming of the PIC using	No interrupts.
interrupts where applicable	
Control Pitch, Amplitude of one or more	Yes.
audio inputs	