

```
<a name="home">
```

```
</a>
```

```
<br />
```

```
<div style="text-align: center;">
```

```
<a href="https://muhammad202052.blogspot.com/p/modul.html">[KEMBALI KE MENU  
SEBELUMNYA]</a></div>
```

```
<br />
```

```
<center>
```

```
<div style="background-color: white; border-color: rgb(23, 128, 221); border-image: none; border-style:  
dashed; border-width: 2px; border: 2px dashed rgb(23, 128, 221); height: 240px; overflow: auto;  
padding: 10px; text-align: center; width: 330px;">
```

```
<b>DAFTAR ISI</b>
```

```
<br />
```

```
<div style="text-align: left;">
```

```
<a href="#kondisi">1. Kondisi</a></div>
```

```
<div style="text-align: left;">
```

```
<a href="#hard">2. Gambar</a> <br /></div><div style="text-align: left;">
```

```
<a href="#rangkaian">3. Video simulasi</a></div>
```

```
<div style="text-align: left;">
```

```
<a href="#flowchart">4. Prinsip kerja rangkaian</a></div>
```

```
<div style="text-align: left;">
```

```
<a href="#listing">5. Link download</a></div>
```

```
</div>
```

```
</center><p>
```

</p><div>
</div>1.

Kondisi

[Kembali]<p></p><p>Percobaan 1 kondisi 3</p><p class="MsoNormal">buatlah vehicle belok kiri
<o:p></o:p></p><div>

2.

Gambar

[Kembali]</div><div> </div><div style="text-align: center;"><div class="separator" style="clear: both; text-align: center;"><span style="font-family: "times" , "times
new roman" , serif;"><span style="font-family: "times" , "times new
roman" , serif; font-size: small;"></div></div><div
style="text-align: center;"><span style="font-family: "times" , "times new
roman" , serif;"><span style="font-family: "times" , "times new roman" ,
serif; font-size: small;">
</div><div>

<span
style="font-family: "times" , "times new roman" , serif; font-size: small;">3.
Video simulasi

[Kembali]
</div><div><span
style="font-family: "times" , "times new roman" , serif;"><br
</div><div><div class="separator" style="clear: both; text-align: center;"><object
class="BLOG_video_class" contentid="8e4e8b43477e5f6c" height="266"
id="BLOG_video-8e4e8b43477e5f6c" width="320"></object></div><div class="separator" style="clear:
both; text-align: center;">
</div></div><div>

<span
style="font-family: "times" , "times new roman" , serif; font-size: small;">4.
Prinsip kerja rangkaian

[Kembali]</div><div><div class="separator" style="clear: both;
text-align: justify;">
</div><div class="separator" style="clear: both; text-align: justify;"><!--[if gte
mso 9]><xml>

<o:OfficeDocumentSettings>

<o:AllowPNG/>

</o:OfficeDocumentSettings>

</xml><![endif]>

<p class="MsoNormal">Perintah nya yaitu buatlah vehicle belok kiri </p>

<p class="MsoNormal">Dapat dilihat pada rangkaian, disini kita menggunakan beberapa komponen diantaranya yaitu ada arduino uno, driver motor IL L293D, 2 buah motor, baterai, power dan ground. Dapat dilihat pada rangkaian pin in1, in2 pada L293D terhubung dengan pin 10,9 pada arduino, pin in3,in4 terhubung dengan pin 5 dan 6 pada arduino, dimana pin in1 – in4 ini digunakan sebagai pengatur kondisi motor, lalu pin EN1,EN2 pada L293D dihubungkan dengan power dimana pin ini berfungsi untuk mengaktifkan atau menonaktifkan motor, lalu ada pin VSS yang dihubungkan dengan power dimana pin ini berfungsi sebagai sumber bagi IC L29D. lalu ada pin VS dihubungkan dengan baterai dimana fungsi pin VS ini adalah sebagai sumber bagi motor. Selanjutnya ada pin out1,ou2 masing masing dihubungkan dengan kaki motor pertama dan pin out3,out4 dihubungkan dengan kaki motor kedua. </p>

<p class="MsoNormal">Listing program </p>

```
<div style="background-color: white; color: #4e5b61; font-family: Consolas,&quot;Courier New&quot;;monospace; font-size: 14px; font-weight: normal; line-height: 19px; white-space: pre;"><div><span style="color: #728e00;">#define</span><span style="color: #4e5b61;"> </span><span style="color: #d35400;">in1</span><span style="color: #4e5b61;"> </span><span style="color: #005c5f;">10</span><span style="color: #95a5a6;"> //Deklarasi pin 10 sebagai input 1</span></div><div><span style="color: #728e00;">#define</span><span style="color: #4e5b61;"> </span><span style="color: #d35400;">in2</span><span style="color: #4e5b61;"> </span><span style="color: #005c5f;">9</span><span style="color: #95a5a6;"> //Deklarasi pin 9 sebagai input 2</span></div><div><span style="color: #728e00;">#define</span><span style="color: #4e5b61;"> </span><span style="color: #d35400;">in3</span><span style="color: #4e5b61;"> </span><span style="color: #005c5f;">5</span><span style="color: #95a5a6;"> //Deklarasi pin 5 sebagai input 3</span></div><div><span style="color: #728e00;">#define</span><span style="color: #4e5b61;">
```

```

</span><span style="color: #d35400;">in4</span><span style="color: #4e5b61;"> </span><span
style="color: #005c5f;">6</span><span style="color: #95a5a6;"> //Deklarasi pin 6 sebagai input
4</span></div><br /><div><span style="color: #00979d;">void</span><span style="color: #4e5b61;">
</span><span style="color: #d35400;">setup</span><span style="color: #434f54;">()</span><span
style="color: #4e5b61;"> </span><span style="color: #434f54;">{</span><span style="color: #95a5a6;">
//Semua kode dalam fungsi ini di eksekusi sekali</span></div><div><span style="color:
#d35400;">pinMode</span><span style="color: #434f54;">(</span><span style="color: #4e5b61;">in1,
OUTPUT</span><span style="color: #434f54;">)</span><span style="color: #4e5b61;">;</span><span
style="color: #95a5a6;"> //Deklarasi in1 sebagai OUTPUT</span></div><div><span style="color:
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OUTPUT</span><span style="color: #434f54;">)</span><span style="color: #4e5b61;">;</span><span
style="color: #95a5a6;"> //Deklarasi in2 sebagai OUTPUT</span></div><div><span style="color:
#d35400;">pinMode</span><span style="color: #434f54;">(</span><span style="color: #4e5b61;">in3,
OUTPUT</span><span style="color: #434f54;">)</span><span style="color: #4e5b61;">;</span><span
style="color: #95a5a6;"> //Deklarasi in3 sebagai OUTPUT</span></div><div><span style="color:
#d35400;">pinMode</span><span style="color: #434f54;">(</span><span style="color: #4e5b61;">in4,
OUTPUT</span><span style="color: #434f54;">)</span><span style="color: #4e5b61;">;</span><span
style="color: #95a5a6;"> //Deklarasi in4 sebagai OUTPUT</span></div><div><span style="color:
#434f54;">}</span></div><br /><div><span style="color: #00979d;">void</span><span style="color:
#4e5b61;"> </span><span style="color: #d35400;">loop</span><span style="color:
#434f54;">()</span><span style="color: #4e5b61;"> </span><span style="color:
#434f54;">{</span><span style="color: #95a5a6;"> //Semua kode dalam fungsi ini dieksekusi
berulang</span></div><div><span style="color: #d35400;">digitalWrite</span><span style="color:
#434f54;">(</span><span style="color: #4e5b61;">in1, LOW</span><span style="color:
#434f54;">)</span><span style="color: #4e5b61;">;</span><span style="color: #95a5a6;"> //in1 diberi
logika 0</span></div><div><span style="color: #d35400;">digitalWrite</span><span style="color:
#434f54;">(</span><span style="color: #4e5b61;">in2, LOW</span><span style="color:
#434f54;">)</span><span style="color: #4e5b61;">;</span><span style="color: #95a5a6;"> //in2 diberi
logika 0</span></div><div><span style="color: #d35400;">digitalWrite</span><span style="color:
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#434f54;">)</span><span style="color: #4e5b61;">;</span><span style="color: #95a5a6;"> //in3 diberi
logika 0</span></div><div><span style="color: #d35400;">digitalWrite</span><span style="color:
#434f54;">(</span><span style="color: #4e5b61;">in4, HIGH</span><span style="color:
#434f54;">)</span><span style="color: #4e5b61;">;</span><span style="color: #95a5a6;"> //in4 diberi
logika 1</span></div><div><span style="color: #d35400;">delay</span><span style="color:
#434f54;">(</span><span style="color: #005c5f;">3000</span><span style="color:
#434f54;">)</span><span style="color: #4e5b61;">;</span><span style="color: #95a5a6;"> //Jarak
waktu 3000 ms setelah input dieksekusi</span></div><br /><div><span style="color:
#434f54;">}</span></div></div>

```

Prinsip kerja dari program ini yaitu yang pertama dideklarasikan pin 10,9,6 dan 5 pada arduino itu sebagai input pada pin in1,in2,in3, dan in4. Lalu ada fungsi void setup dimana pada fungsi ini semua kode kan dijalankan sekali. Lalu dalam fungsi void ini terdapat syntaks yang mendeklarasikan bahwa in1 sampai in4 digunakan sebagai output. Selanjutnya ada fungsi void loop dimana pada fungsi ini semua kode akan dijalankan berulang. Lalu untuk menampilkan output program ini kita perlu menuliskan syntaks digitalWrite(pin,LOGIKA) dimana syntaks ini bertujuan untuk menentukan logika dari pin L293D yang kita gunakan sebagai outputnya. Disini untuk pin in1 dan in2 kita beri logika low sehingga motor yang terhubung dengan pin tersebut tidak akan bergerak atau berputar, sedangkan pin in3 kita beri logika low dan pin in4 kita beri logika high sehingga motor yang dihubungkan dengan pin tersebut akan berbelok ke arah pin 3 atau arah kiri. Lalu ada delay 3000 menunjukkan jarak waktu 3000ms untuk mengulang program.

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</style>

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5. Link download

[Kembali]</div><div>link html

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