



```
1. package org.firstinspires.ftc.teamcode;
2.
3. import com.qualcomm.robotcore.eventloop.opmode.LinearOpMode;
4. import com.qualcomm.robotcore.eventloop.opmode.TeleOp;
5. import com.qualcomm.robotcore.hardware.DcMotor;
6.
7. @TeleOp(name = "Testcodeonbot", group = "")
8. public class Testcodeonbot extends LinearOpMode {
9.
10.     private DcMotor frontLeft;
11.     private DcMotor frontRight;
12.
13.     /**
14.      * This function is executed when this Op Mode is selected from the Driver Station.
15.      */
16.     @Override
17.     public void runOpMode() {
18.         frontLeft = hardwareMap.get(DcMotor.class, "frontLeft");
19.         frontRight = hardwareMap.get(DcMotor.class, "frontRight");
20.
21.         // Put initialization blocks here.
22.         waitForStart();
23.         if (opModeIsActive()) {
24.             // Put run blocks here.
25.             frontLeft.setPower(1);
26.             frontRight.setPower(1);
27.             sleep(1500);
28.             // go backward
29.             frontLeft.setPower(-1);
30.             frontRight.setPower(-1);
31.             sleep(500);
32.             frontLeft.setPower(0);
33.             frontRight.setPower(0);
34.         }
35.     }
36. }
```