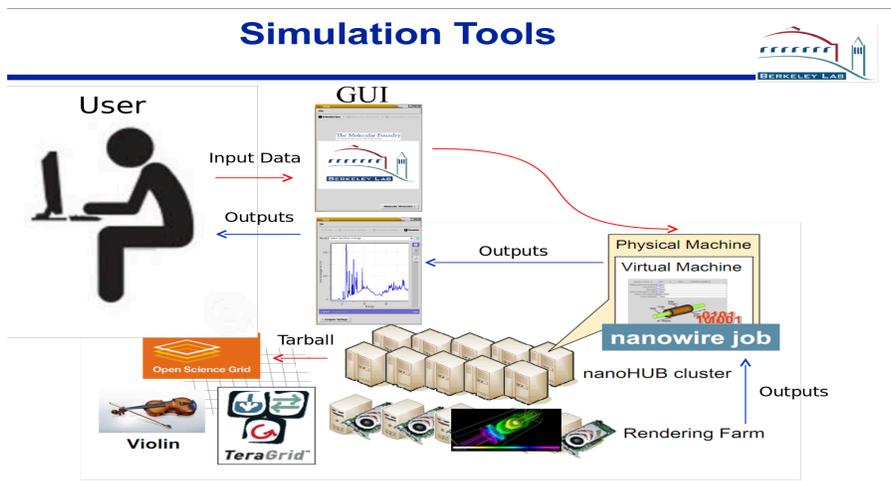


- a. The rappture toolkit: <https://nanohub.org/infrastructure/rappture/>
- b. rappture builder simplifies designing and writing the GUI. drag and drop GUI elements into a tree. The builder exports the tree into "tool.xml" which rappture interprets to draw the GUI at startup. tool.xml executes the script wrapper to interpret the inputs from the user/GUI and execute code/submit jobs. Your wrapper then gathers outputs and submit them back to the GUI and user.
- c. `cd $TOOLDIR/rappture; rappture -builder;`
  - i. In python, replace variables named "str" to avoid collision with str method. Also, booleans are given values "yes" and "no", not true/false

#### 4. Infrastructure



- a. The workspace virtual machine has limited storage space and computing power and is used mainly for input/output between the user and cluster. Calculations are performed on clusters through `submit [-i $INPUTS] $EXEC`
  - i. Submit: <http://hubzero.org/documentation/1.0.0/tooldevs/grid.submitcmd>
  - ii. Berkeley XAS found best results using <4 nodes, as wait time increases significantly with the number of nodes requested
- b. Submitted executables (\$EXEC) must be installed by nanoHUB staff. Providing explicit instructions on compiling will expedite the process. For Berkeley XAS, a phone call made this much easier and helped develop a method for submitting

multiple executables within a single script

- i. Berkeley XAS employs a brief script (written by the main wrapper) that parses inputs, and prepares directories for the simulation. The wrapper then executes a primary script which has a call "submit -i \$INPUTDAT XAS. The primary script is executed on nanoHUB clusters using \$INPUTDAT (which is tarballed and sent to the cluster). The script runs several executables using the contents of the current directory and then deletes unnecessary files. Once completed, all of the remaining contents in the working directory are transferred back to the directory from which the primary script was submitted. The wrapper then parses these outputs and interprets them for the GUI and user.
      - c. Similarly, scripts executed by the GUI must be approved and installed by nanoHUB staff. However, scripts written on the fly by the script wrapper can be executed without prior installation.
        - i. Rappture Integration with Submit:  
[http://hubzero.org/documentation/1.0.0/tooldevs/grid.rappture\\_submit](http://hubzero.org/documentation/1.0.0/tooldevs/grid.rappture_submit)
      - d. Submit lines transfer -i \$INPUTS to a new working directory on a nanoHUB cluster and begin execution. Once on the cluster, the executable will be out of contact with the user until the task is completed or fails. Finished tasks will transfer all remaining files back to the workspace. Tasks should remove unnecessary files after completion to reduce time spent transferring files (very slow otherwise).
  5. svn commit; Update tool on homepage for staff installation to latest revision
  6. Test within workspace using middleware/invoke
    - a. Invoke: <http://hubzero.org/documentation/1.0.0/tooldevs/invoke>
    - b. Invoke will demonstrate the behavior of the published tool, including the environment packages (assuming they are set identically). However, the path of the tool is dependent on the current directory, while the path of runs from the published tool runs from the root directory -- these may be inconsistent. Therefore relative paths should never be used (except for child directories created by the tool during an individual job).
      - i. cd commands within the main script wrapper (the one called by the GUI/wrapper) do not function and do not throw errors, however cd can be used from scripts that the main wrapper executes.
    - c. \$TOOLDIR/middleware/invoke -T \$TOOLNAME
    - d. Errors in the script wrapper can also be debugged by executing the script in the shell using driver\*.xml as an argument. runfiles can be generated from runs called using invoke. Running the wrapper this way will print errors and warnings that may be hidden when run using invoke.
  7. Test within published webpage version
    - a. Files for both published and workspace runs are accessible from the workspace in the ~/data directory. "run\*.xml" files contain detailed log information regarding interactions with the GUI
  8. Publish and update

## Job Submission

- Use submit *[args]*
  - Submit command:  
<http://hubzero.org/documentation/1.0.0/tooldevs/grid.submitcmd>
  - *-i \$INPUTFILE* to send files to cluster's working directory
- Submitted jobs are inaccessible until completed
  - jobs submitted in parallel will not communicate until task is completed and transferred back to user's directory
  - All existing files in cluster's working directory will be transferred back from cluster memory to user's current directory on nanoHUB server
    - User's have ~1.5 TB hard limit memory (~1 TB "soft" limit), exceeding hard limit will cause jobs to end abruptly
    - clean up at end of job to reduce transfer time and memory used
- Not all cluster environments are identical
  - Berkeley XAS uses Coates and Rossman exclusively

Links: Overview: <http://hubzero.org/documentation/1.0.0/tooldevs>

Advanced Rapture: [http://hubzero.org/resources/169/download/2.2\\_Rapture\\_Advanced.pdf](http://hubzero.org/resources/169/download/2.2_Rapture_Advanced.pdf)

Rapture FAQ: <https://nanohub.org/infrastructure/rapture/wiki/FAQ>

nanoHUB Tools: <http://nanohub.org/resources/3865/download/tools.pdf>

All of this info is relevant as of Fall 2011, however nanoHUB is frequently updated