

KARTIK SINGHAL

kartik21259@iitd.ac.in

[Website](#)

[GitHub](#)

EDUCATION

Indraprastha Institute of Information Technology (IIIT), Delhi, India
Bachelor of Technology in Computer Science and Applied Mathematics
CGPA: 8.5/10

Aug 2021 - May 2025
(Expected)

KNOWLEDGE & SKILLS

Computer Vision, Robotics, Reinforcement Learning, Deep Learning, Machine Learning, MLOps
Python, C/C++, Java | Pytorch, NumPy, Pandas, Scikit-Learn
Previously proficient in ReactJS, NodeJS, ExpressJS, Flask, MySQL, Firebase

WORK EXPERIENCE

Research Specialist II - AiSys Lab, University of South Carolina, USA
Advisors - [Mehdi Yaghouti](#), [Pooyan Jamshidi](#)

May 2023 – July 2023
On-Site

Research Intern - VIGIL, IIT Hyderabad, India
Advisors - [C. Vishnu](#), [C. Krishna Mohan](#)

Jun 2021 – Dec 2021
Remote

ACHIEVEMENTS

 Grand-Prize [Winner](#) of [Google Code-In 2019](#) for my contribution to open-source projects.

Papers

- Multi-Sense-Rescuer: Multi-Target Audio-Visual Learning and Navigation in Search and Rescue Scenarios, **Kartik Singhal**, Mehdi Yaghouti, Pooyan Jamshidi [*IROS 2023, Learning Robot Super Autonomy workshop*] [Under Review at *ICRA 2024*] [[project website](#)]

PROJECTS

Many more. Please see [Github](#).

Sensor Fusion and Tracking

[Waymo Open Dataset]

- Track objects over time by fusing incoming Lidar and Camera data. See the Github repository for results.

3D Object Detection using Lidar

[Waymo Open Dataset]

- Detect vehicles using a pretrained SFA3D model in a bird's eye view perspective image-like input.

Object Detection and Localization

[Pytorch | Tensorflow]

- Detect and draw bounding boxes around cars in an image using the YOLO algorithm trained from **scratch**
- Draw bounding boxes around vehicles, pedestrians, and cyclists by training an SSD Resnet 50 640x640 model and achieving 70% mAP for large-sized objects.

Mini Keras

[Python, Numpy]

- Built a neural network library using only Python and Numpy with a user-friendly interface akin to Keras
- Dense layers, Optimizers: gradient descent with momentum, Adam, and Regularizers: L2 loss and Dropouts.

Behavioural Cloning for self-driving cars

[Keras]

- Collect steering data by driving car in the simulator and train a CNN-based model for autonomous driving

Chat App

[ReactJS, NodeJS, Flask, MySQL, Firebase Realtime Database]

- A web-based application allowing users to create account and share private messages in real-time.