

[INFO] [launch]: All log files can be found below
/home/admin/.ros/log/2025-12-16-20-49-06-597659-nexcobot-4623

[INFO] [launch]: Default logging verbosity is set to INFO

[INFO] [static_planning_scene-1]: process started with pid [4626]

[INFO] [cumotion_goal_set_planner_node-2]: process started with pid [4627]

[static_planning_scene-1] [INFO] [1765889349.592913943] [static_planning_scene_server]:
Static Planning Scene Server initialized

[cumotion_goal_set_planner_node-2]
/usr/local/lib/python3.12/dist-packages/matplotlib/projections/__init__.py:63: UserWarning:
Unable to import Axes3D. This may be due to multiple versions of Matplotlib being installed (e.g.
as a system package and as a pip package). As a result, the 3D projection is not available.

[cumotion_goal_set_planner_node-2] warnings.warn("Unable to import Axes3D. This may be
due to multiple versions of "

[cumotion_goal_set_planner_node-2] [INFO] [1765889350.118333755] [cumotion_planner]:
Loading grid position and dims from grid_center_m and grid_size_m parameters.

[cumotion_goal_set_planner_node-2] [INFO] [1765889351.619200591] [cumotion_planner]:
warming up cuMotion, wait until ready

[cumotion_goal_set_planner_node-2] [INFO] [1765889354.470991454] [cumotion_planner]:
cuMotion is ready for planning queries!

[static_planning_scene-1] [INFO] [1765889354.472028703] [static_planning_scene_server]: No
static planning scene file path provided

[cumotion_goal_set_planner_node-2] [INFO] [1765889354.495786327] [cumotion_planner]:
Executing goal...

[cumotion_goal_set_planner_node-2] [WARN] [1765889354.496472103] [cumotion_planner]:
Static planning scene service failed: No static planning scene file path provided

[cumotion_goal_set_planner_node-2] [INFO] [1765889354.496707357] [cumotion_planner]:
Planning with time_dilation_factor: 0.7

[cumotion_goal_set_planner_node-2] [INFO] [1765889354.497600184] [cumotion_planner]:
PlanRequest start state was empty, reading current joint state

[cumotion_goal_set_planner_node-2] [ERROR] [1765889354.498127470] [cumotion_planner]:
joint_state was not received from /joint_states

[cumotion_goal_set_planner_node-2] [INFO] [1765889365.907811939] [cumotion_planner]:
Executing goal...

[cumotion_goal_set_planner_node-2] [INFO] [1765889365.908442610] [cumotion_planner]:
Planning with time_dilation_factor: 0.7

[cumotion_goal_set_planner_node-2] [INFO] [1765889365.909310249] [cumotion_planner]:
PlanRequest start state was empty, reading current joint state

[cumotion_goal_set_planner_node-2] [ERROR] [1765889365.910013137] [cumotion_planner]:
joint_state was not received from /joint_states