

Adaptation to MQ 135 sensor

```
#define      MQ_PIN                (1)  //define which analog input channel you are going
to use
#define      RL_VALUE              (5)  //define the load resistance on the board, in kilo
ohms
#define      RO_CLEAN_AIR_FACTOR   (9.83) //RO_CLEAN_AIR_FACTOR=(Sensor
resistance in clean air)/RO,
//which is derived from the chart in datasheet
```

```
/******Software Related Macros******/
```

```
#define      CALIBRATION_SAMPLE_TIMES  (50) //define how many samples you are
going to take in the calibration phase
#define      CALIBRATION_SAMPLE_INTERVAL  (500) //define the time interval(in
milisecond) between each samples in the
//calibration phase
#define      READ_SAMPLE_INTERVAL      (50) //define how many samples you are
going to take in normal operation
#define      READ_SAMPLE_TIMES         (5)  //define the time interval(in milisecond)
between each samples in
//normal operation
```

```
/******Application Related Macros******/
```

```
#define      GAS_LPG                (0)
#define      GAS_CO                  (1)
#define      GAS_SMOKE               (2)
```

```
/******Globals******/
```

```
float      LPGCurve[3] = {2.3,0.21,-0.47}; //two points are taken from the curve.
//with these two points, a line is formed which is
"approximately equivalent"
//to the original curve.
//data format:{ x, y, slope}; point1: (lg200, 0.21), point2:
(lg10000, -0.59)
float      COCurve[3] = {1.0,0.462,-0.268}; //two points are taken from the curve.
//with these two points, a line is formed which is
"approximately equivalent"
//to the original curve.
//data format:{ x, y, slope}; point1: (lg200, 0.72), point2:
(lg10000, 0.15)
float      SmokeCurve[3] = {2.3,0.53,-0.44}; //two points are taken from the curve.
//with these two points, a line is formed which is
"approximately equivalent"
//to the original curve.
```

```

//data format:{ x, y, slope}; point1: (lg200, 0.53), point2:
(lg10000, -0.22)
float      Ro      = 10;          //Ro is initialized to 10 kilo ohms

void setup()
{
  Serial.begin(9600);              //UART setup, baudrate = 9600bps
  Serial.print("Calibrating...\n");
  Ro = MQCalibration(MQ_PIN);      //Calibrating the sensor. Please make sure the
  sensor is in clean air

                                   //when you perform the calibration
  Serial.print("Calibration is done...\n");
  Serial.print("Ro=");
  Serial.print(Ro);
  Serial.print("kohm");
  Serial.print("\n");
}

void loop()
{
  Serial.print("LPG:");
  Serial.print(MQGetGasPercentage(MQRead(MQ_PIN)/Ro,GAS_LPG) );
  Serial.print( "ppm" );
  Serial.print(" ");
  Serial.print("CO:");
  Serial.print(MQGetGasPercentage(MQRead(MQ_PIN)/Ro,GAS_CO) );
  Serial.print( "ppm" );
  Serial.print(" ");
  Serial.print("SMOKE:");
  Serial.print(MQGetGasPercentage(MQRead(MQ_PIN)/Ro,GAS_SMOKE) );
  Serial.print( "ppm" );
  Serial.print("\n");
  delay(200);
}

/***** MQResistanceCalculation *****/
Input:  raw_adc - raw value read from adc, which represents the voltage
Output: the calculated sensor resistance
Remarks: The sensor and the load resistor forms a voltage divider. Given the voltage
         across the load resistor and its resistance, the resistance of the sensor
         could be derived.
*****/
float MQResistanceCalculation(int raw_adc)
{
  return ( ((float)RL_VALUE*(1023-raw_adc)/raw_adc));
}

```

/****** MQCalibration *****/

Input: mq_pin - analog channel

Output: Ro of the sensor

Remarks: This function assumes that the sensor is in clean air. It use

MQResistanceCalculation to calculates the sensor resistance in clean air
and then divides it with RO_CLEAN_AIR_FACTOR. RO_CLEAN_AIR_FACTOR is
about

10, which differs slightly between different sensors.

*****/

float MQCalibration(int mq_pin)

{

int i;

float val=0;

for (i=0;i<CALIBARAION_SAMPLE_TIMES;i++) { //take multiple samples

val += MQResistanceCalculation(analogRead(mq_pin));

delay(CALIBRATION_SAMPLE_INTERVAL);

}

val = val/CALIBARAION_SAMPLE_TIMES; //calculate the average value

val = val/RO_CLEAN_AIR_FACTOR; //divided by

RO_CLEAN_AIR_FACTOR yields the Ro

//according to the chart in the datasheet

return val;

}

/****** MQRead *****/

Input: mq_pin - analog channel

Output: Rs of the sensor

Remarks: This function use MQResistanceCalculation to caculate the sensor resistenc (Rs).

The Rs changes as the sensor is in the different consentration of the target

gas. The sample times and the time interval between samples could be configured

by changing the definition of the macros.

*****/

float MQRead(int mq_pin)

{

int i;

float rs=0;

for (i=0;i<READ_SAMPLE_TIMES;i++) {

rs += MQResistanceCalculation(analogRead(mq_pin));

delay(READ_SAMPLE_INTERVAL);

}

rs = rs/READ_SAMPLE_TIMES;

```

return rs;
}

```

```

/***** MQGetGasPercentage *****/

```

Input: rs_ro_ratio - Rs divided by Ro

gas_id - target gas type

Output: ppm of the target gas

Remarks: This function passes different curves to the MQGetPercentage function which calculates the ppm (parts per million) of the target gas.

```

*****/

```

```

int MQGetGasPercentage(float rs_ro_ratio, int gas_id)

```

```

{
    if ( gas_id == GAS_LPG ) {
        return MQGetPercentage(rs_ro_ratio,LPGCurve);
    } else if ( gas_id == GAS_CO ) {
        return MQGetPercentage(rs_ro_ratio,COCurve);
    } else if ( gas_id == GAS_SMOKE ) {
        return MQGetPercentage(rs_ro_ratio,SmokeCurve);
    }
}

```

```

return 0;
}

```

```

/***** MQGetPercentage *****/

```

Input: rs_ro_ratio - Rs divided by Ro

pcurve - pointer to the curve of the target gas

Output: ppm of the target gas

Remarks: By using the slope and a point of the line. The x(logarithmic value of ppm) of the line could be derived if y(rs_ro_ratio) is provided. As it is a logarithmic coordinate, power of 10 is used to convert the result to non-logarithmic value.

```

*****/

```

```

int MQGetPercentage(float rs_ro_ratio, float *pcurve)

```

```

{
    return (pow(10,((log(rs_ro_ratio)-pcurve[1])/pcurve[2]) + pcurve[0]]));
}

```