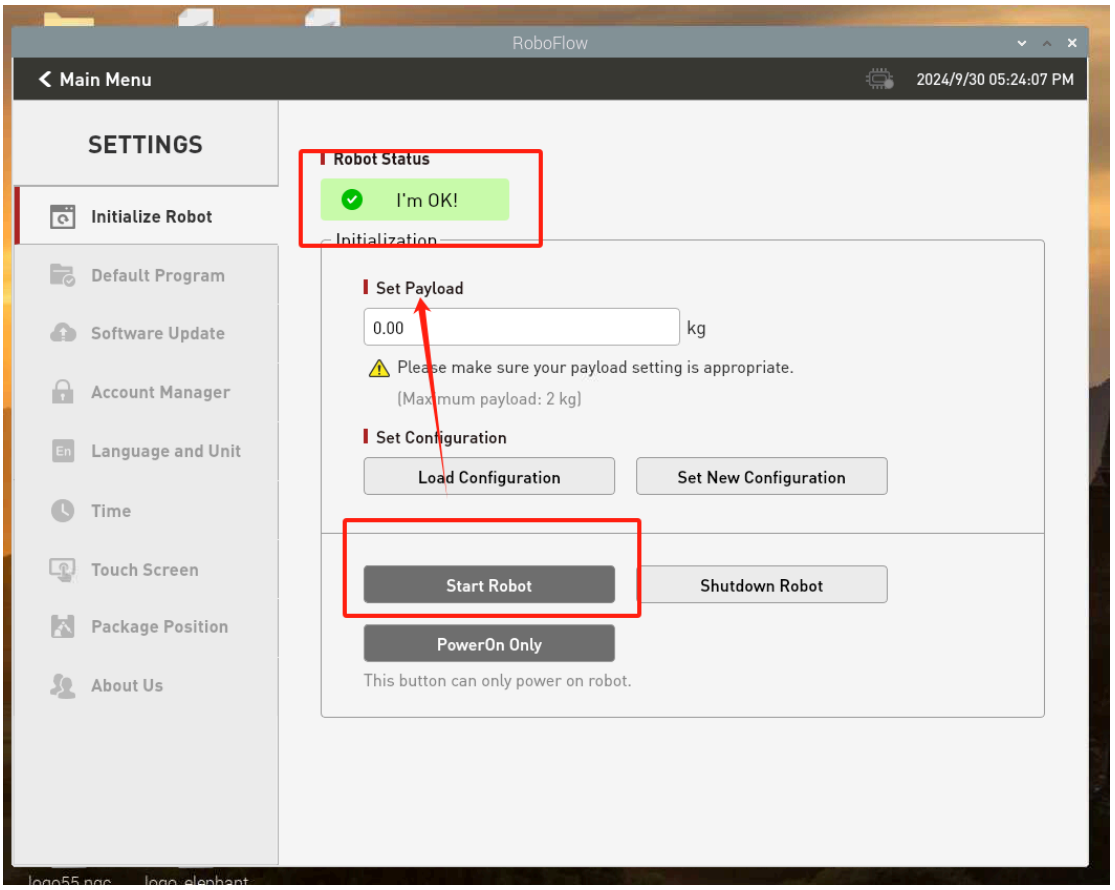
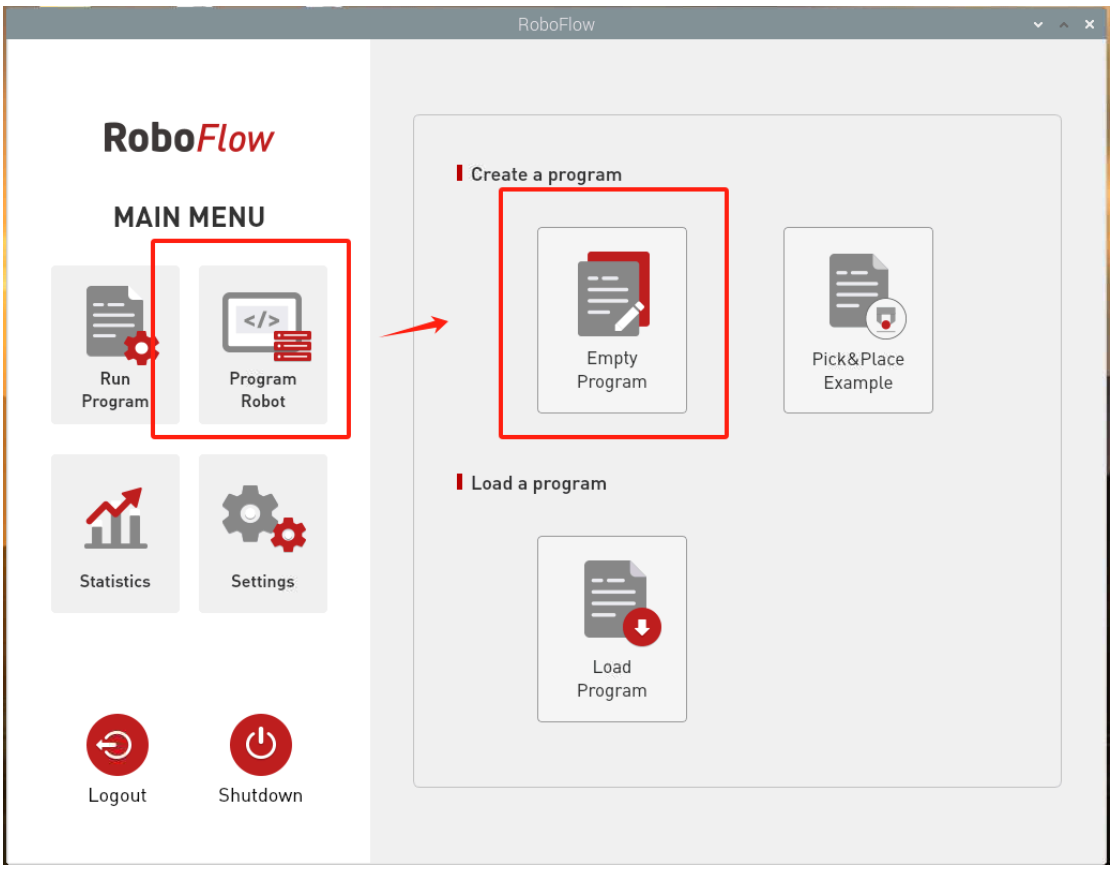
If your electric gripper cannot be used, you can refer to the following usage methods to solve your problem.
First step, first confirm whether the machine is powered on. After clicking Start Robot, check whether the robot status is "I'm OK!".

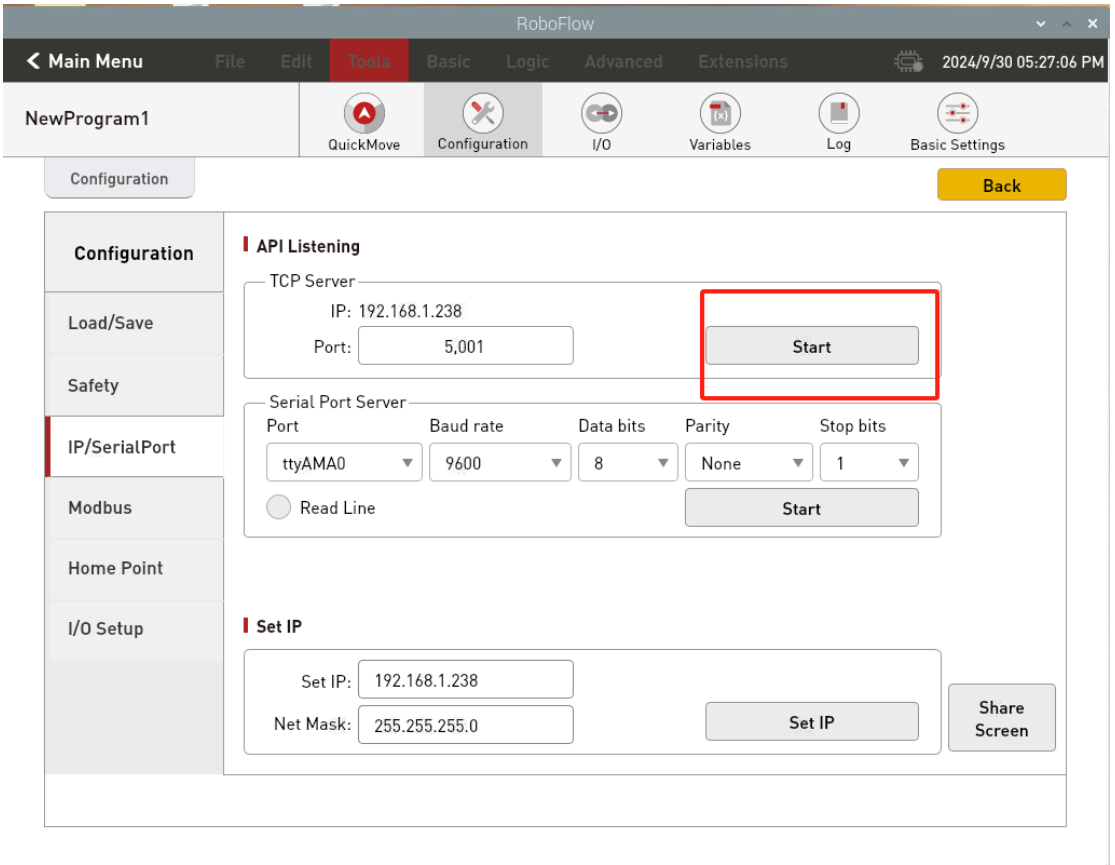


Second step:
Create a blank program.



Third step:

Check whether the configured TCP/IP is enabled. If it is enabled, just turn it off.



Fourth step: Write a program.

It should be noted in particular that if your electric gripper flashes a red light, you need to click Init Gripper under Debug Control to initialize the gripper. Otherwise, the gripper cannot be used normally. And after you click Init Gripper, the light of the electric gripper will turn blue. After the light is blue, test to see if your electric gripper is normal. For numbers 2 and 3 in the picture, you can choose to control and use according to the opening and closing of the electric gripper. Run the program after testing the electric gripper.

