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/*****
Module
  GameService.c

Revision
  1.0.1

Description
  This is a template file for implementing a simple service under the
  Gen2 Events and Services Framework.

Notes

History
When          Who          What/Why
-----
01/16/12 09:58 jec          began conversion from TemplateFSM.c
*****/
/*----- Include Files -----*/
/* include header files for this state machine as well as any machines at the
next lower level in the hierarchy that are sub-machines to this machine
*/
#include "ES_Configure.h"
#include "ES_Framework.h"
#include "GameService.h"
#include "Joystick.h"
#include "EC_Button.h"
#include "DM_Display.h"
#include "LEDDisplay.h"
#include <time.h>
#include <stdlib.h>
#include <stdio.h>
#include "PALmainService.h"
#include "PIC32PortHAL.h"
#include "ES_DeferRecall.h"

/*----- Module Defines -----*/
#define NUM_ROWS    24
#define NUM_COLS    32
#define DOG_WIDTH   4
#define DOG_HEIGHT  4
#define BONE_WIDTH  4
#define BONE_HEIGHT 4
#define CAT_WIDTH   4
#define CAT_HEIGHT  4

// Timer variable
#define ONE_SEC 1000

// add a deferral queue for up to 5 pending deferrals +1 to allow for overhead
static ES_Event_t DeferralQueue[5 + 1];

/*----- Module Functions -----*/
/* prototypes for private functions for this service.They should be functions
relevant to the behavior of this service
*/
static bool checkDogBounds(int8_t mvmtX, int8_t mvmtY);
static bool checkCollision(int8_t x1, int8_t y1, int8_t w1, int8_t h1, int8_t x2,
int8_t y2,int8_t w2, int8_t h2);
static void generateBone(void);

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static void genNewDogPos(void);
static void moveCat(void);
void CheckJoystick(Joystick_t current_joy);
static uint8_t MyAbs(int8_t a, int8_t b);

/*----- Module Variables -----*/
// with the introduction of Gen2, we need a module level Priority variable
static uint8_t MyPriority;
static int8_t dogXcoord;
static int8_t dogYcoord;
static int8_t boneXcoord;
static int8_t boneYcoord;
static int8_t catXcoord;
static int8_t catYcoord;
static int16_t score;

/*----- Module Code -----*/
/*****
Function
    InitGameService

Parameters
    uint8_t : the priority of this service

Returns
    bool, false if error in initialization, true otherwise

Description
    Saves away the priority, and does any
    other required initialization for this service

Notes

Author
    J. Edward Carryer, 01/16/12, 10:00
*****/
bool InitGameService(uint8_t Priority)
{
    ES_Event_t ThisEvent;

    MyPriority = Priority;
    /*****
    in here you write your initialization code
    *****/

    //initial dog coordinates
    dogXcoord = 31;
    dogYcoord = 0;
    boneXcoord = 10;
    boneYcoord = 10;
    catXcoord = 5;
    catYcoord = 19;

    // initialization of audio
    PortSetup_ConfigureDigitalOutputs(_Port_B, _Pin_5); // set pin as digital output
    CHOMP = 1; // high means off, ground triggers audio

    PortSetup_ConfigureDigitalOutputs(_Port_B, _Pin_8); // set pin as digital output
    MEOW = 1; // high means off, ground triggers audio

    InitJoystickStatus(); //setup joystick -originally in ES_IN_GAME in

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// post the initial transition event
ThisEvent.EventType = ES_INIT;
if (ES_PostToService(MyPriority, ThisEvent) == true)
{
    return true;
}
else
{
    return false;
}
}

/*****
Function
    PostGameService

Parameters
    EF_Event_t ThisEvent ,the event to post to the queue

Returns
    bool false if the Enqueue operation failed, true otherwise

Description
    Posts an event to this state machine's queue
Notes

Author
    J. Edward Carryer, 10/23/11, 19:25
*****/
bool PostGameService(ES_Event_t ThisEvent)
{
    return ES_PostToService(MyPriority, ThisEvent);
}

/*****
Function
    RunGameService

Parameters
    ES_Event_t : the event to process

Returns
    ES_Event, ES_NO_EVENT if no error ES_ERROR otherwise

Description
    add your description here
Notes

Author
    J. Edward Carryer, 01/15/12, 15:23
*****/
ES_Event_t RunGameService(ES_Event_t ThisEvent)
{
    ES_Event_t ReturnEvent;
    ReturnEvent.EventType = ES_NO_EVENT; // assume no errors
    /*****
    in here you write your service code
    *****/
}

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switch (ThisEvent.EventType)
{
    case ES_INIT:
    {

    }
    break;

    case ES_DRAW_INIT_GAME:
    {
        //draw dog, bone, and cat
        DM_DrawDogAndBone(dogXcoord,dogYcoord,boneXcoord,boneYcoord);
        DM_DrawCat(catXcoord,catYcoord);

        //display buffer updated, send new frame event to display
        ES_Event_t NewEvent;
        NewEvent.EventType = ES_UPDATED_FRAME;
        PostLEDDisplay(NewEvent);
    }

    case ES_TIMEOUT:
    {
        if (GameMode == QueryPALmainService())//only do things if we are in game mode
        {
            if(GAME_UPDATE_TIMER == ThisEvent.EventParam){ //refresh the game

                //check collision with dog and bone
                if (true ==
checkCollision(dogXcoord,dogYcoord,DOG_WIDTH,DOG_HEIGHT,boneXcoord,boneYcoord,BONE_WIDT
H,BONE_HEIGHT)){
                    CHOMP = 0; //play chomp sound
                    ES_Timer_InitTimer(CHOMP_DELAY_TIMER, 0.2*ONE_SEC);//init timer
before sound can be played again
                    score++;//increment score
                    generateBone();//generate a new bone
                }

                //check collision with dog and cat
                if (true ==
checkCollision(dogXcoord,dogYcoord,DOG_WIDTH,DOG_HEIGHT,catXcoord,catYcoord,CAT_WIDTH,C
AT_HEIGHT)){
                    MEOW = 0; //play meow sound
                    ES_Timer_InitTimer(MEOW_DELAY_TIMER, 0.2*ONE_SEC); //init timer
before sound can be played again
                    score--; //decrement score
                    genNewDogPos(); //move dog to a new position
                }

                Joystick_t JoystickValues = Check4Joystick();
                int8_t mvmtX = JoystickValues.X;
                int8_t mvmtY = JoystickValues.Y;

                if (mvmtX != 0 || mvmtY != 0){//if any of the joystick values are not
zero
                checkDogBounds(mvmtX,mvmtY);//if new movement puts dogs within
bounds
                moveCat();//move cat
            }
        }
    }
}

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        DM_DrawDogAndBone(dogXcoord, dogYcoord, boneXcoord, boneYcoord);
//draw dog+bone position
        DM_DrawCat(catXcoord, catYcoord); //draw new cat position

        //display buffer updated, send new frame event to display
        ES_Event_t NewEvent;
        NewEvent.EventType = ES_UPDATED_FRAME;
        PostLEDDisplay(NewEvent);
    }
    CheckJoystick(JoystickValues); //check if the joystick is being used
    ES_Timer_InitTimer(GAME_UPDATE_TIMER, 75); //reset timer for refreshing
the game

} else if(GAME_END_TIMER == ThisEvent.EventParam){ //signals end of the game
    ES_Event_t NewEvent;
    NewEvent.EventType = ES_GAME_TIMEOUT; //post game timeout event
    NewEvent.EventParam = score;
    PostPALmainService(NewEvent);
    score = 0;
}

//timer to prevent sounds from being played too rapidly
else if(CHOMP_DELAY_TIMER == ThisEvent.EventParam){
    CHOMP = 1;
}

//timer to prevent sounds from being played too rapidly
else if(MEOW_DELAY_TIMER == ThisEvent.EventParam){
    MEOW = 1;
}
}
}
break;

default: {}
break;

}

return ReturnEvent;
}

//set the score to zero
void zeroScore(void){
    score = 0;
}

/*****
private functions
*****/
static bool checkDogBounds(int8_t mvmtX, int8_t mvmtY){
    bool returnVal = true;

    //check x bounds
    if (dogXcoord + mvmtX >= NUM_COLS){ //Out left X bounds
        returnVal = false;
        dogXcoord = NUM_COLS - 1; //set dog to leftmost position
    }
}

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}else if (dogXcoord + mvmtX -(DOG_WIDTH-1) < 0){//out right X bounds
    returnVal = false;
    dogXcoord = DOG_WIDTH-1;//set dog to rightmost position

}else{// in X bounds
    dogXcoord += mvmtX; //add movement to current dog position
}

//check y bounds
if (dogYcoord + mvmtY +(DOG_HEIGHT-1) >= NUM_ROWS){//out top Y bounds
    returnVal = false;
    dogYcoord = NUM_ROWS - DOG_HEIGHT;//set cat to topmost position
}else if (dogYcoord + mvmtY < 0){ //out bottom Y bounds
    returnVal = false;
    dogYcoord = 0;//set cat to bottommost position
}else{// in y bounds
    dogYcoord += mvmtY;//addmevment to current cat position
}

return returnVal;
}

//check if two rectangles are overlapping
//given: bottom left (X,Y) coordinate and width/height of two object you want to check
collision
static bool checkCollision(int8_t x1, int8_t y1, int8_t w1, int8_t h1, int8_t x2,
int8_t y2,int8_t w2, int8_t h2){
    bool returnVal = true;

    if (x1 - w1 > x2 || x2 - w2 > x1){//if first object is to the left or right of the
second
        returnVal = false; //not colliding
    }else if (y1 > y2 + h2 || y2 > y1+h1){ //if first object is above or below the
second
        returnVal = false;//not colliding
    }
    //otherwise they are colliding
    return returnVal;
}

//generates a new bone on the screen
static void generateBone(void){
    static uint8_t idx = 0;

    srand(idx); //random seed

    int8_t nMax = NUM_COLS - 1; //max possible value
    int8_t nMin = BONE_WIDTH; //min possible value
    boneXcoord = ( rand()%((nMax+1)-nMin) ) + nMin; //generate new x coordinate

    nMax = NUM_ROWS - BONE_HEIGHT; //max possible value
    nMin = 0;//min possible value
    boneYcoord = ( rand()%((nMax+1)-nMin) ) + nMin;//generate new y coordinate

    idx += 5; //increment seed
}

static void genNewDogPos(void){

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static uint8_t idx = 0;

srand(idx); //random seed

int8_t nMax = NUM_COLS - 1; //max possible value
int8_t nMin = DOG_WIDTH; //min possible value
dogXcoord = ( rand()%((nMax+1)-nMin) ) + nMin; //generate new x coordinate

nMax = NUM_ROWS - DOG_HEIGHT; //max possible value
nMin = 0; //min possible value
dogYcoord = ( rand()%((nMax+1)-nMin) ) + nMin; //generate new y coordinate

idx += 5; //increment seed
}

static void moveCat(void){
    static uint8_t idx = 0;

    srand(idx); //random seed

    //generates random movement in both directions
    int8_t nMax = 2;
    int8_t nMin = -2;
    int8_t mvmtX = ( rand()%((nMax+1)-nMin) ) + nMin;
    int8_t mvmtY = ( rand()%((nMax+1)-nMin) ) + nMin;

    //used to determine if cats movment is random
    nMax = 5; //chance of randomness is 1 / (nMax-nMind+1)
    nMin = 0;
    int8_t isRandom = ( rand()%((nMax+1)-nMin) ) + nMin;

    if (isRandom <= nMax-1){ //Movement is random
        //nothing to do
    } else{ //Movement is not random - moves toward player
        int8_t towardX = dogXcoord - catXcoord; //take difference in x coords
        int8_t towardY = dogYcoord - catYcoord; //take difference in y coords

        //set x movment
        if (towardX >= 0){
            mvmtX = 1;
        }else{
            mvmtX = -1;
        }
        //set y movement
        if (towardY >= 0){
            mvmtY = 1;
        }else{
            mvmtY = -1;
        }
    }

    //check if movement moves cat out of X bounds
    if (catXcoord + mvmtX >= NUM_COLS){ //Out left X bounds
        catXcoord = NUM_COLS - 1;
    }else if (catXcoord + mvmtX -(CAT_WIDTH-1) < 0){ //out right X bounds
        catXcoord = CAT_WIDTH-1;
    }else{ // in X bounds
        catXcoord += mvmtX;
    }
}

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//check if movement moves cat out of Y bounds
if (catYcoord + mvmtY +(CAT_HEIGHT-1) >= NUM_ROWS){//out top Y bounds
    catYcoord = NUM_ROWS - CAT_HEIGHT;
}else if (catYcoord + mvmtY < 0){ //out bottom Y bounds
    catYcoord = 0;
}else{// in y bounds
    catYcoord += mvmtY;
}

idx += 5;//increment seed
}

void CheckJoystick(Joystick_t current_joy)
{
    if (GameMode == QueryPALmainService()) //only does anything when in Gamemode
    {
        static Joystick_t past_joy = { .X = 0, .Y = 0};
        if (MyAbs(past_joy.X,current_joy.X) > 0)//if the x values have changed
        {
            ES_Timer_InitTimer(IDLE_TIMER, 30*ONE_SEC);//reset idle timer
        }
        else if (MyAbs(past_joy.Y,current_joy.Y) > 0)//if the y values have changed
        {
            ES_Timer_InitTimer(IDLE_TIMER, 30*ONE_SEC);//reset idle timer
        }
        past_joy = current_joy;
    }
}

//always returns the positive difference between two values
static uint8_t MyAbs(int8_t a, int8_t b)
{
    if (a > b)
    {
        return a - b;
    }
    else
    {
        return b - a;
    }
}

/*----- Footnotes -----*/
/*----- End of file -----*/

```