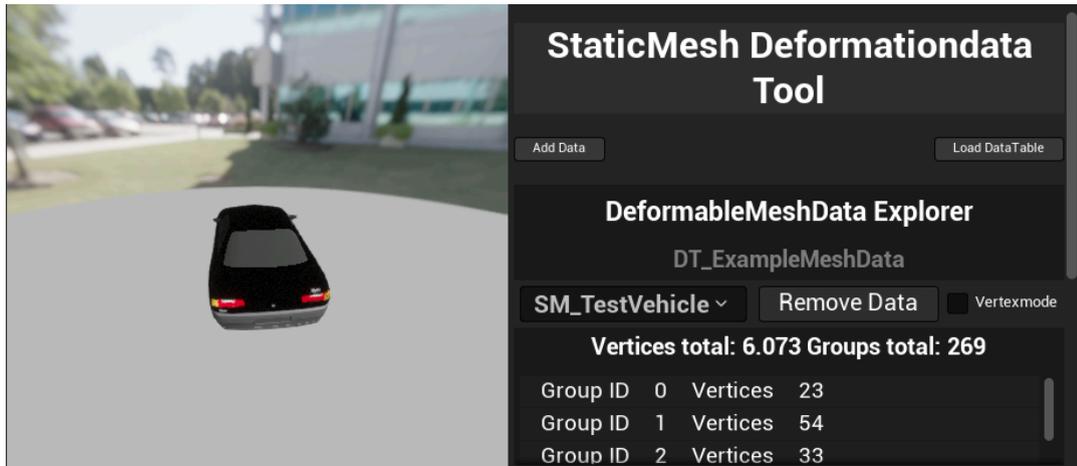


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StaticMesh Deformationdata Tool



Structure

New data can be created and existing data can be loaded using the top two buttons "Add Data" and "Load Datatable". In the "DeformableMeshData Explorer" individual meshes can be selected, which can then be seen in the viewport on the left.

Functionality

The "StaticMesh Deformationdata Tool" is the fundamental building block of the plugin. This is where the data creation process for the "Deformation Component" starts. The tool can read static meshes and prepare them for the component. During preparation, all vertices and their associated positions are packed into a struct. Depending on the configuration, the vertices are also divided into groupings that have a positive effect on performance.

This data is then saved in a datatable and then loaded and used by the deformable mesh component in the respective actor.

You have to pay attention to this!

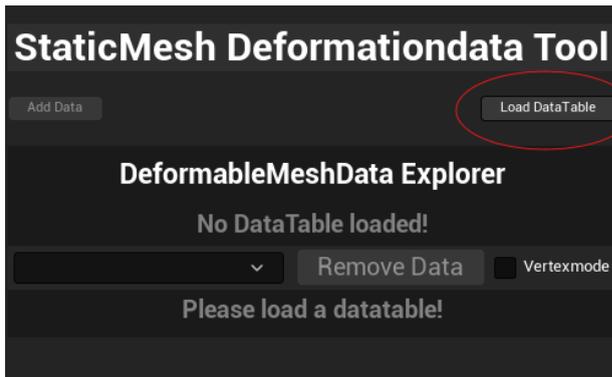
Important! The **tool** only supports static meshes! Only a static mesh can be deformed by the *deformation component*, but your vehicle itself can be a skeletal or static mesh based vehicle. What you also have to consider: your vehicle mesh must be separate from the wheels! If you have a Skeletal Mesh based vehicle, please note that you have to create a Static Mesh for the tool, [which you can find out how to do here!](#)

First steps

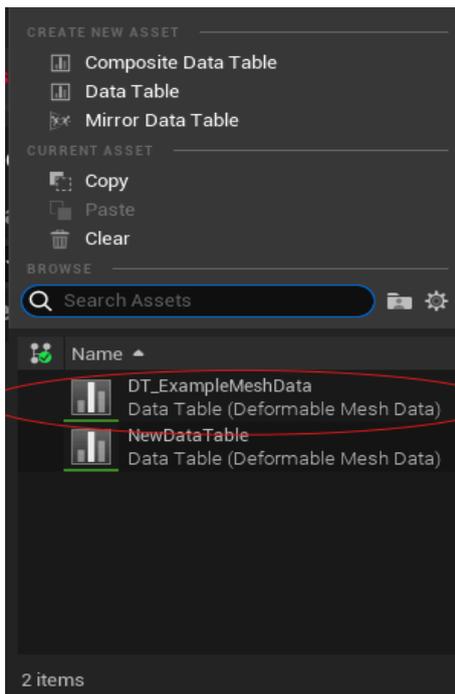
1. Install and activate our plugin. [Howto?](#)
2. Open Static Mesh Deformation Data Tool



3. Load a compatible datatable



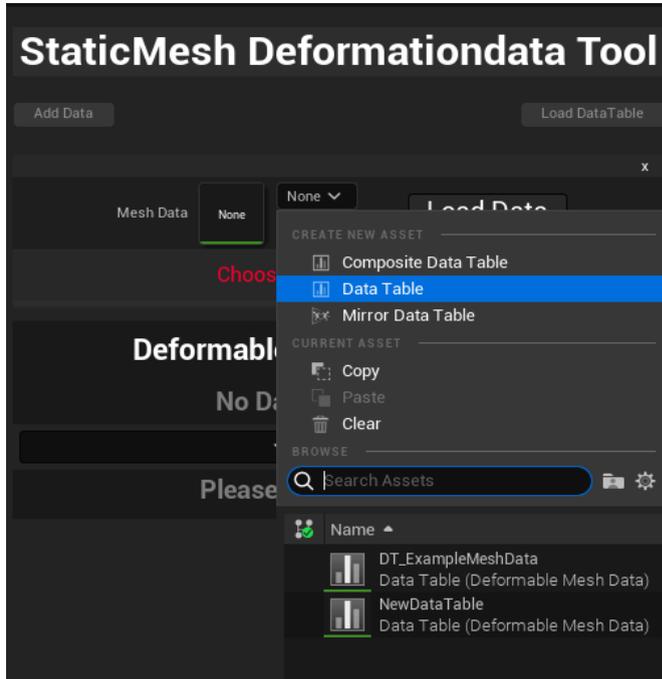
If a compatible datatable exists, it will be suggested to you in the list:



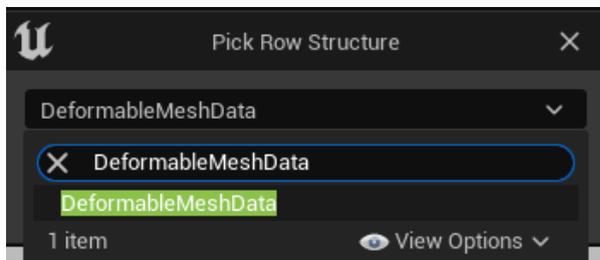
If the list is empty it means that there is no compatible datatable and you still need to create it.

4. (Optional) Create a compatible datatable

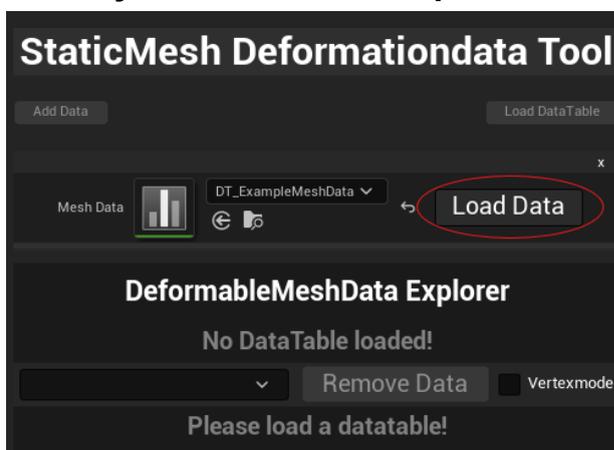
The component requires a special structure of the data table so that the data for the component is arranged in a readable manner.



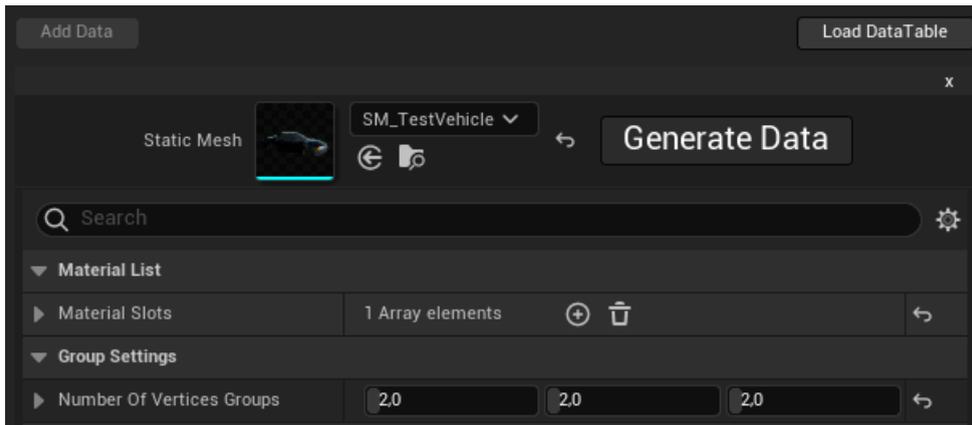
To do this, press "Data Table" under "Create new asset" and save it as you wish. Then select "**Deformable Mesh Data**" as "Data Row Structure":



5. Select your datatable and press "Load Data"



6. Create DefromableMeshData using the “Add Data” (top left).



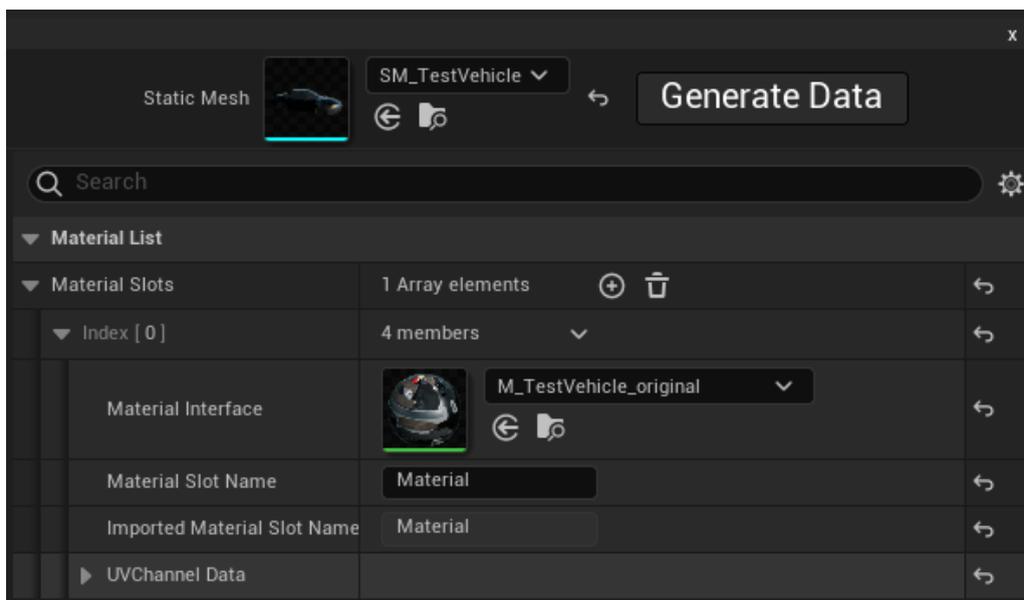
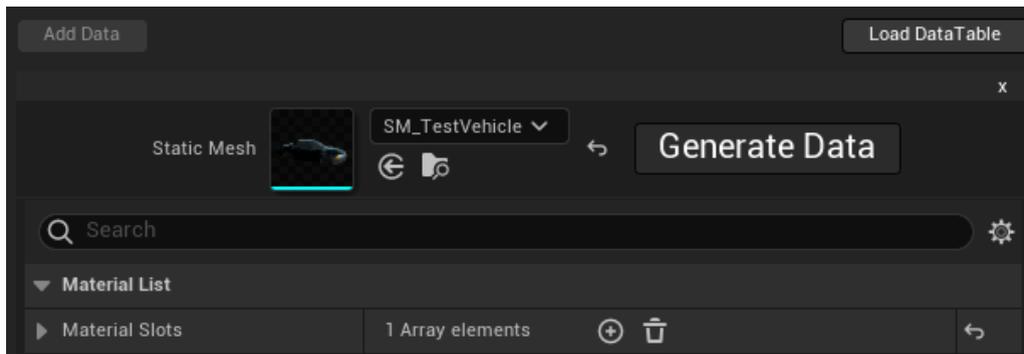
To do this, select your desired static mesh. Under ‘Number of Vertices Groups’ you can determine the number of groups of vertices on the X, Y and Z axes (see image). It makes sense to distribute the groups unevenly if the mesh is not square. The principle applies that the more detailed the model area, the more sense it makes to generate more groups on this axis. For example, if the mesh is very high (in the sense of height), it makes sense to create more groups on the Z axis than on the other axes. The more groups there are, the smaller the number of individual vertices in each group that need to be captured at once on impact.



7. (Optional) Select material

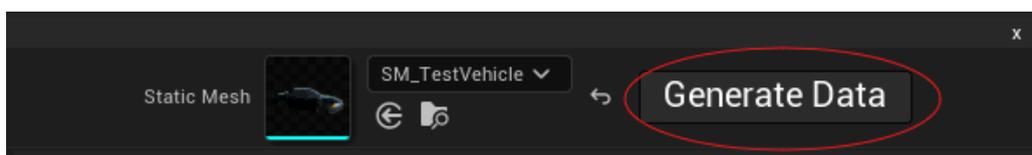
In this step, the materials of the static mesh can be changed. The source static mesh will be changed. Materials that support at least deformation should be used for this (more on [this](#) here). By default, all materials of the static mesh are already selected under "Material Slots".

Please note: In some cases, the materials of poor static meshes that do not have reasonable UVs, for example, may not be displayed correctly in the component.



8. Generate mesh data

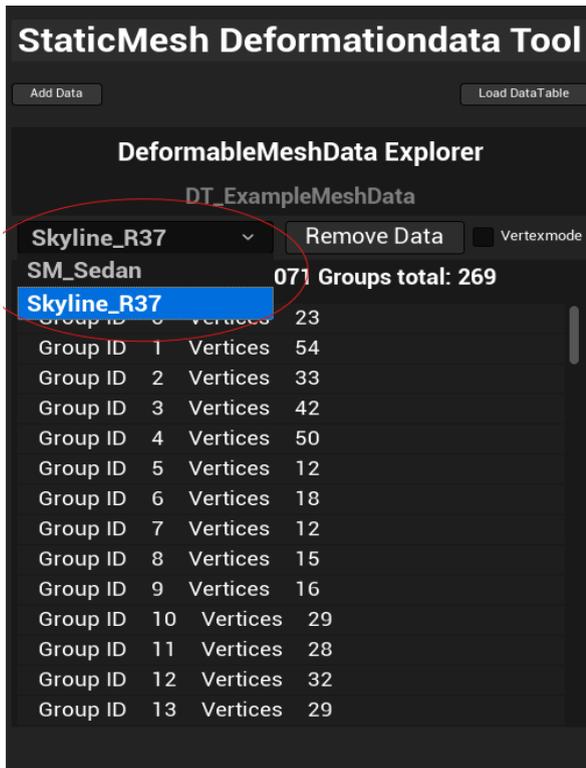
Last press on "Generate Data" to transfer the static mesh and all the settings made into the data table.



DeformableMeshData Explorer

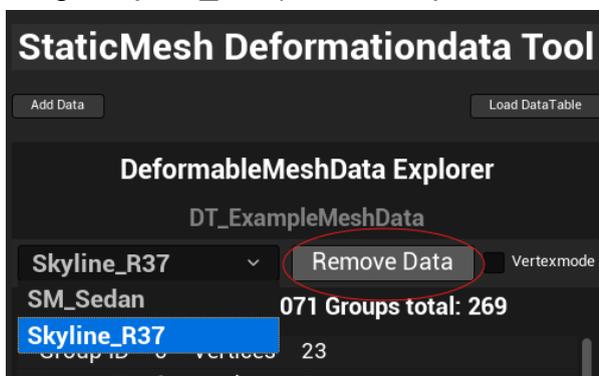
Open data

The “DeformableMeshData Explorer” gives you an insight into your created datatables and prepared meshes. First load your datatable using the function “*Load DataTable*” into the tool and then select the desired mesh in the selection box to see its groupings and the mesh itself in the viewport:



Delete datatable entries

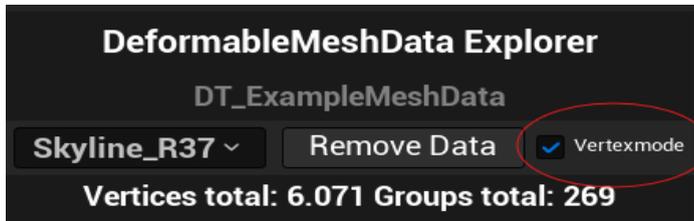
To delete data, select the corresponding mesh in the selection box (in the example image *Skyline_R37*) and then press the “Remove Data” button.



Navigation in the viewport

The mesh can be inspected using the viewport. Navigation takes place with the right mouse button pressed and W/A/S/D. The speed can be set faster or slower using the mouse wheel.

Vertexmode



The 'Vertex mode' visualises the groupings of the mesh in colour in the viewport. To do this, the mode must be activated and then groups that are to be displayed must be selected from the list below:

Group ID	Vertices
0	23
1	54
2	33
3	42
4	50
5	12
6	18
7	12
8	15
9	16
10	29
11	28
12	32
13	29

Deformation Component

 BP_DeformableMeshComp

Functionality

The *Deformable Mesh Comp* is the counterpart to the *Static Mesh Deformation Data Tool*. This is where the magic happens. Here the collected data from the datatable that we previously created in the tool is processed. The component simply works according to the plug and play system: **You simply place it below the vehicle mesh, give the component some information and the component regulates the rest independently.**

Details on how the component works

The component does this internally in the background

1. Loads the previously created datatable into memory using [Async Load](#). A [procedural mesh](#) is then created, which we will use later for the deformation. This procedural mesh is a child of the vehicle mesh.
2. The procedural mesh itself is created from the previously prepared data of the tool from the datatable.
3. The component hides the vehicle mesh (*parent component*) and switches on its “Simulate Hit Events” (important only for vehicle mesh!). The reason for this is that we now bring our procedural mesh to the foreground because that is where we will apply the deformation upon impact. **The original vehicle mesh only serves us as a hit detection mesh.** Important: The whole thing works just as well with a skeletal mesh as with a static mesh as the vehicle mesh, which is not important for the *component*. Next, the component binds the “On Component Hit” event to the vehicle mesh with our deformation logic.

This is roughly summarized in deformation logic

During an impact, an area is formed at the location of the impact, the size of which varies [Impact Radius](#) is dependent.

In this area we look at which vertices are affected by the impact. This would not be easily possible by going through each individual vertex in a for each loop, looking at its position and checking whether this is in the formed area.

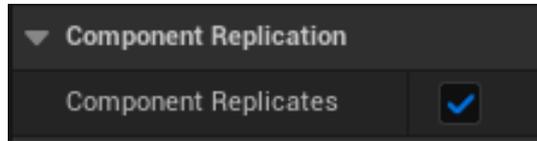
This for each loop would then be so extremely complex for the CPU while the game is running (i.e. the more detailed the mesh, the longer the loop) that it could lead to FPS drops or even application crashes.

That's why we decided to pre-sort and group all vertices with the tool before runtime so that in the event of an impact we only have to check whether a group of vertices is affected and then only check this small, relevant group of vertices in the loop whether it is affected. If relevant, these vertices are shifted in position from the opposite direction of impact and updated in the procedural mesh.

In order to make the whole thing even more realistic visually, we use this affected group in another procedure in which we change the vertex color to which a material instance can then react and then color scratches (via a mask) and dents (via the normal input) in this area.

Multiplayer / Network Replication (V1.1)

The component can be used in multiplayer. All you need to do is switch on the "Component Replicates" setting of the deformation component, which is the case by default. **If the component is used in single player, this setting can and should be deactivated in order to save performance.**



How it works

When network replication is active, all hits are recognised by the server and forwarded to all *relevant*¹ clients. Each client calculates the deformation independently based on the data received from the server. In general, the hits are always recognised by the server, with the exception of when the actor is a pawn and this pawn is controlled by a player. In this case, the hits are recognised by the controlling client and sent to the server.

Each hit is also stored in the *hit history*. This hit history is used to be able to restore the current deformation at any time. This is particularly important as a player who joins later should see the same deformation as all other players. The same concept applies to actors that only become relevant for a client later. In both cases, the hit history is replayed client side so that all players subsequently see the same deformation.

Limitations

We are currently aware of two limitations in the way our network replication works. Firstly, there is always a certain delay in deformation, as all data must first be sent to the server and then back to the client. This can be optimized in future using client-side prediction.

Secondly, the *hit history* only supports a maximum of ~300 entries. The reason for this is that Unreal Networking has a fixed maximum packet size² and this is currently reached after ~300 hits. Once the maximum number of hits has been reached, the oldest hits are always deleted from the hit history for all subsequent hits and are therefore lost.

¹ [Network Relevancy](#)

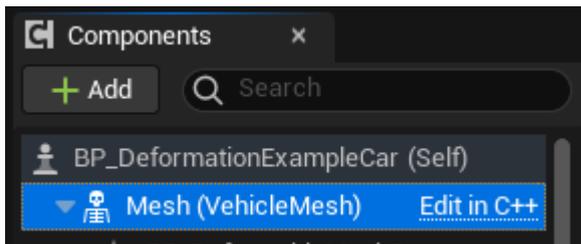
² Also called "maximum bunch size"

Component setup

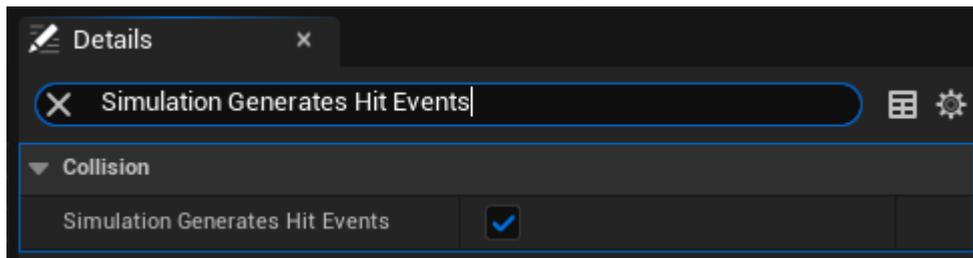
The component can be combined with many other plugins, for example the “*Chaos Vehicle*” plugin from Epic Games or the “*Advanced Vehicle System*” plugin by Overtorque Creations. For simplicity's sake, let's start with *Chaos Vehicle*.

Chaos Vehicle and AVS

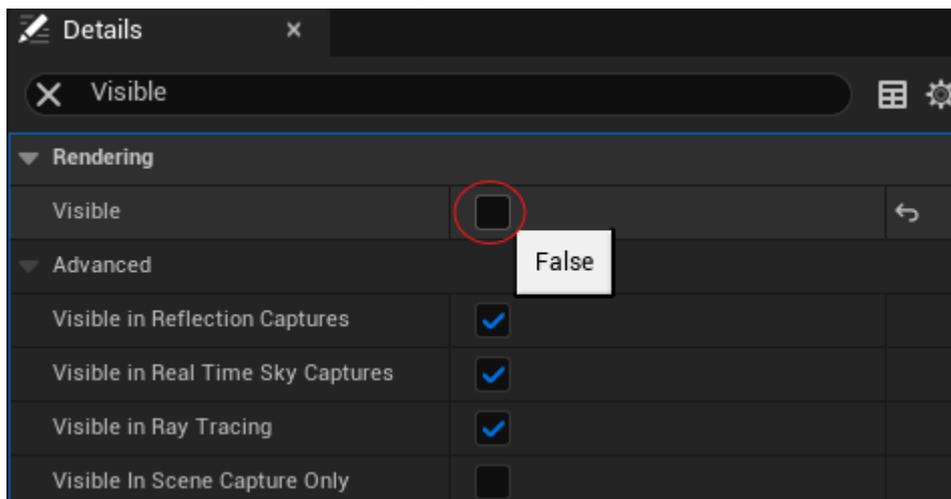
1. First create a normal chaos vehicle, for example with this [Instruction](#) or [our instructions](#).
2. The root component (“VehicleMesh”) must then be adjusted



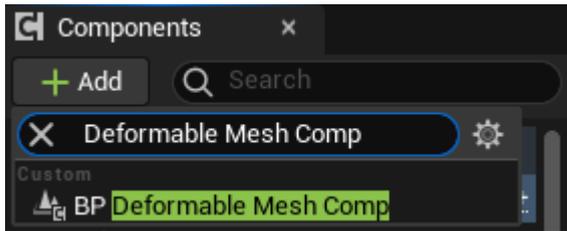
- a. Navigate in the Details panel under “*Collision*” and switch “*Simulation Generates Hit Events*” and “*Simulate Physics*” on.



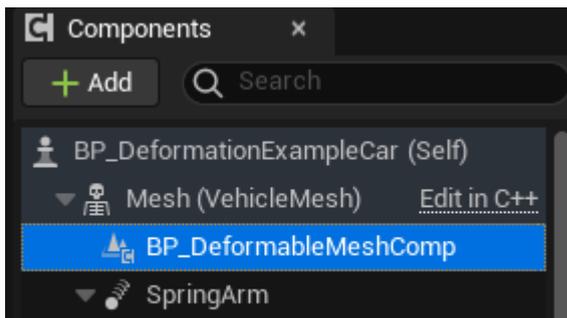
- b. Now search for “*Visible*” and put the box on *False*.



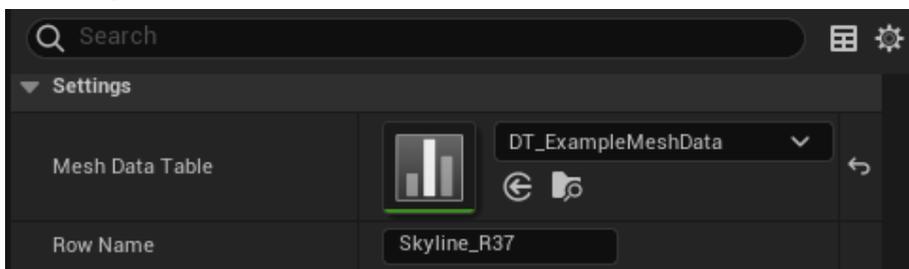
- Press that "Add" Button, search for "**Deformable Mesh Comp**" and add the component below the root component:



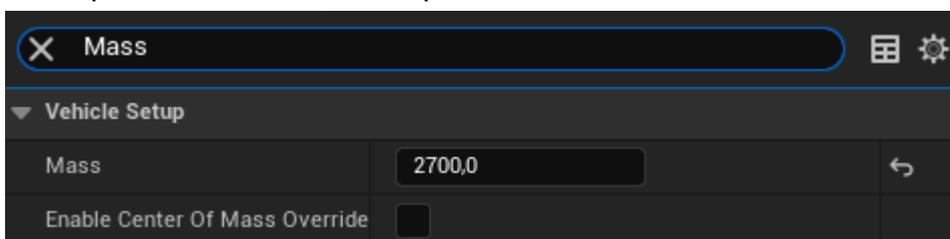
Important: The component must be a child of the static/skeletal mesh that is to deform. In our case the "VehicleMesh":



- Select the just created "BP_DeformableMeshComp" and open the Details panel. Find the "Settings" category, select your created DataTable as "Mesh Data Table" and also enter the name of the mesh in "Row Name", as shown in the image.



- Next, you define the weight of your chaos vehicle. It is strongly advised to choose a realistic weight, as the damage calculation depends on the weight. **Notice:** In case you don't use chaos vehicles and skeleton meshes, the *Mass* of the parent static mesh component is used.

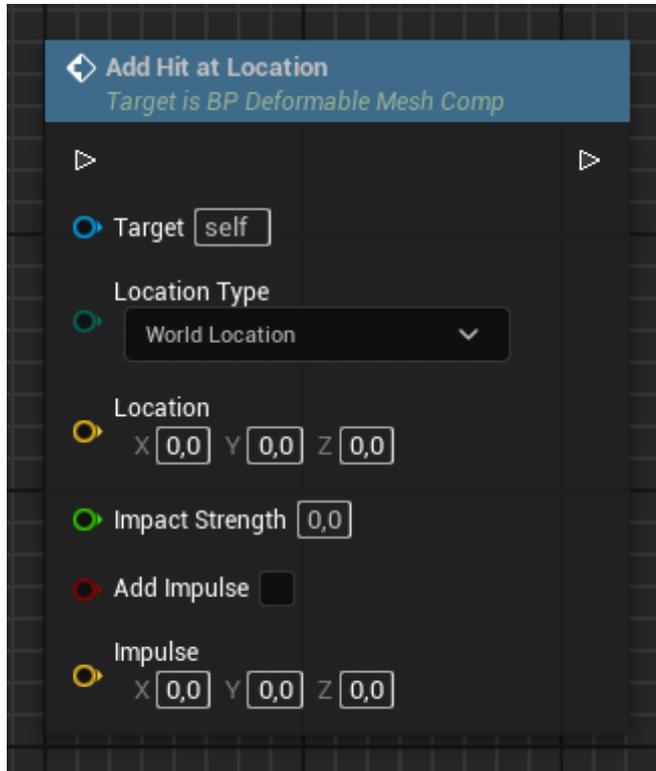


Non-Vehicle Actor

The deformation component does not necessarily have to be used in combination with a vehicle. It can also be used with normal actors. These actors do not even necessarily have to simulate physics. For non-physics-simulating actors, however, it should be noted that a mass must be specified as a [mass override](#). The calculation of the deformation requires a mass! The setup procedure differs only slightly from the procedure for [Chaos Vehicle](#). The first step is omitted and the mass (step 6) does not have to be specified in the vehicle, but if at all in the component (as a "mass override").

Component functions

Add Hit at Location (V1.1)



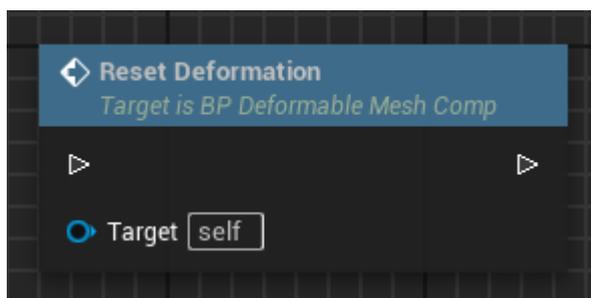
This function can be used to perform a hit (+ deformation) at a given position. The position can be a position in the world or relative to the actor.

The *impact strength* is in m/s^2 and can be determined using the [Debug impulse](#) setting.

This function can also be used to automatically add an impulse at the specified position. It internally uses the default *AddImpulseAtLocation* node.

 This function is replicated and can be called by the controlling client or the server (authority).

Reset Deformation



This function can be used to reset the deformation.

 This function is replicated, but may only be called by the server (authority).

Other useful functions (Materials V1.3)

▼ FUNCTIONS (3 OVERRIDABLE)		
▼ Mesh Data		
<i>f</i>	public	GetMeshMaterialInstancesSlots
<i>f</i>	public	SetAllMeshMaterialInstancesSlots
<i>f</i>	public	ClearAllMeshMaterialInstancesSlots
<i>f</i>	public	Get Mesh Material Instance Slot by Index
<i>f</i>	public	Add Material Instance Slot
<i>f</i>	public	SetMaterialInstanceSlotByIndex
<i>f</i>	public	RemoveMeshMaterialInstanceSlotByIndex
<i>f</i>	public	RemoveMeshMaterialInstanceSlotByItem
<i>f</i>	public	FindMeshMaterialInstanceSlotByItem
<i>f</i>	public	SetMaterialParamByIndex(Float)
<i>f</i>	public	SetMaterialParamByIndex(Vector)
<i>f</i>	public	SetMaterialParamByIndex(Texture)
<i>f</i>	public	UpdateMesh

These functions can be used to edit the materials of the default mesh.

After a change has been made, *UpdateMesh* should always be called to refresh the visible mesh.

Settings of the component

Deformation Settings

▼ Settings - Deformation	
Max Deform Percentage	0,75
Max Hit Deform Percentage	0,5
Max Hit Acceleration	60,0
▼ Radius	
Max Impact Radius	72,0
Min Impact Radius	16,0
▼ None Physics	
Mass Override	0,0

Max Deform Percentage

Maximum deformation in percent. The exact value depends on the distance of the vertex to the mesh origin, e.g. a vertex that is far out can achieve a much higher deformation than a vertex that is located directly on the origin.

Max Hit Deform Percentage

Maximum deformation in a single impact, e.g. 10%, means that at least 10 hits (10 x 10% = 100%) are required to achieve the maximum deformation.

Max Hit Acceleration

Acceleration (m/s²) required to achieve "Max Hit Deformation Percentage". Can be measured with the debug setting "[Debug Vehicle Velocity](#)".

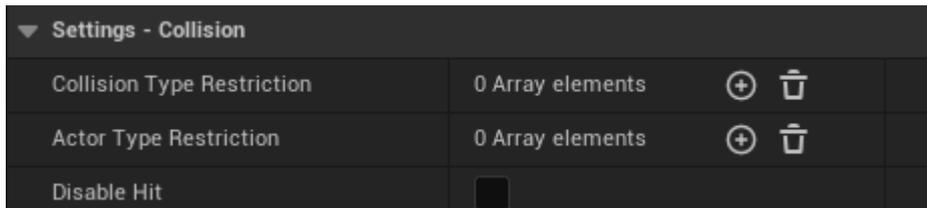
Radius Settings (Impact Radius)

The minimum/maximum size of the impact (in cm). It affects how many vertices can move in a single impact. The minimum size corresponds to a very low force impact and the maximum size corresponds to a very high force impact.

Mass Override (V1.1)

This value overrides the mass of the parent component. If specified, this mass is used to calculate the deformation. This setting is mandatory if the parent component does not simulate physics. See [Non-Vehicle Actors](#).

Collision Settings



Collision Type Restriction

(Optional) Here you can add collision types with which the component should only simulate collision. By default there is no restriction.

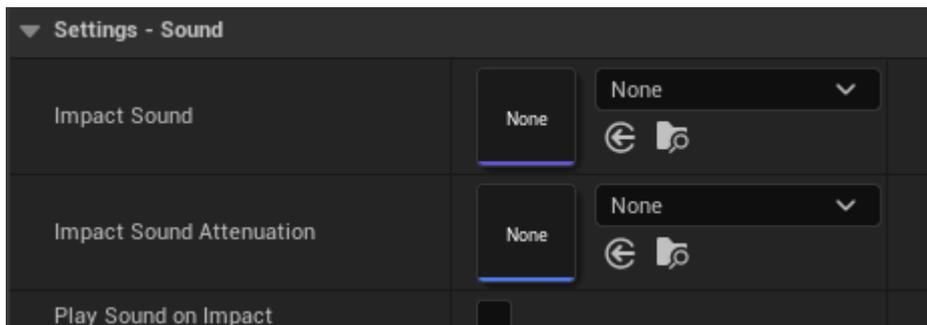
Actor Type Restriction

(Optional) Here you can add actor types with which the component should only simulate collision. By default there is no restriction.

Disable Hit

Here you can deactivate deformation.

Sound Settings



Impact Sound

Here you can insert a sound file that will be played at the point of impact.

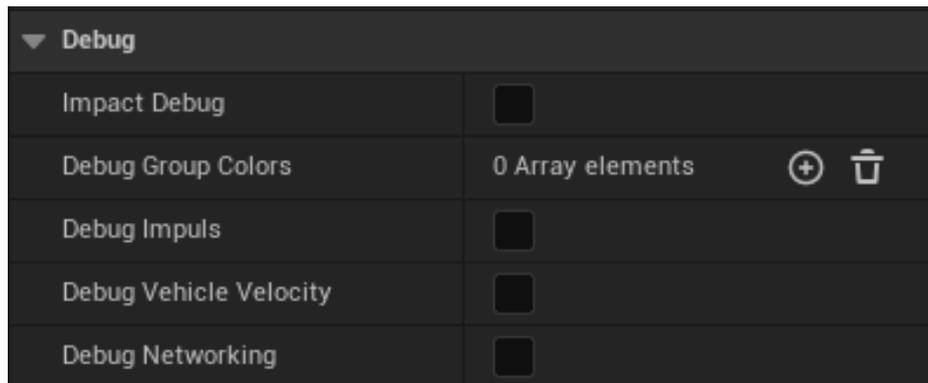
Impact Sound Attenuation

Insert a sound attenuation config file here that matches your impact sound.

Play Sound on Impact

Here you activate your selected impact sound upon impact should be played.

Debug Settings



Impact Debug

Here you can display the impact radius visually in-game for debugging purposes.

Debug Impulse

Shows impulse values that act on impact (kilonewtons and speed in m/s^2). These two values are important for the impact calculation:

$$Impact\ Strength\ [m/s^2] = Normal\ Impulse\ [N] / Mass\ [kg]$$

Debug Vehicle Velocity

Shows speed values in cm the second upon impact.

Debug Networking (V1.1)

This setting can be used to log the network relevance of an actor and the number of replicated hits that need to be replayed, for example, for a player who joins later.

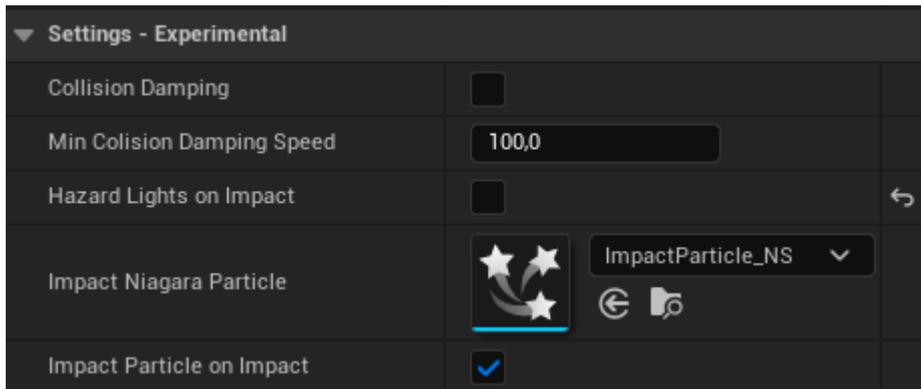
Networking Settings (V1.1)



Max Hit History (V1.1)

Maximum number of replicated hits that, for example, a player who joins later receives and replays. Limited by maximum Unreal package size, see [Limitations](#).

Experimental Settings



Collision Damping

Dampens the force that throws the vehicle back like a rubber ball after an impact.

Min Collision Damping Speed

Minimum speed at which collision damping should take effect.

Hazard Lights on Impact

Switches on the vehicle's hazard warning lights in the event of an impact (requires a vehicle material specially made for this purpose and serves only as an example of what is possible with light despite deformation).

Impact Niagara Particle

Insert a Niaga Particle System here, which should simulate particles and smoke upon impact.

Impact Particle on Impact

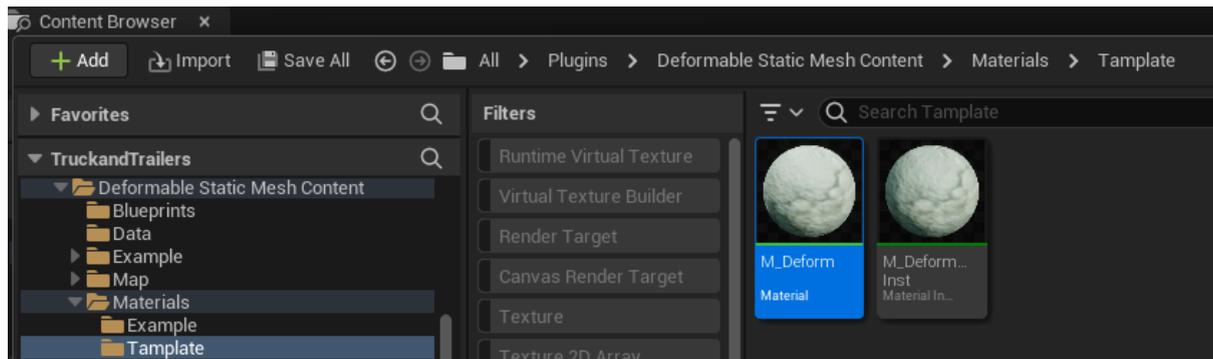
Turns on the Impact Niaga Particle System.

How to set up (Material)

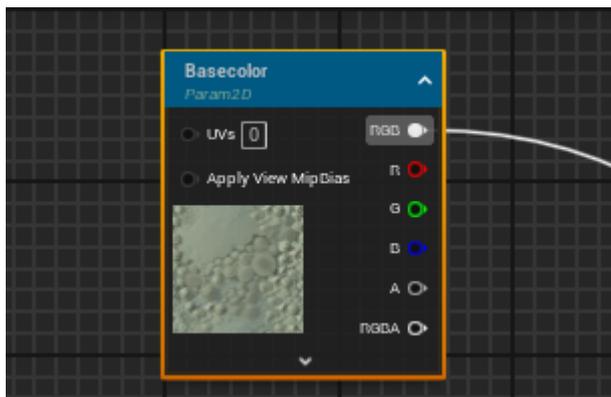
How to create a material for your vehicle/mesh

Also available as a [video tutorial](#).

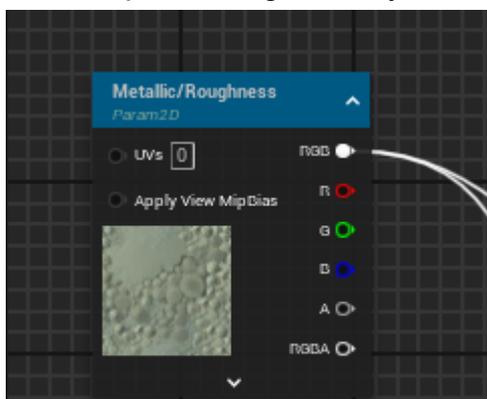
First open / create a copy of the material file *M_Deform* located in “/Plugins/DeformableStaticMeshContent/Materials/Template”:



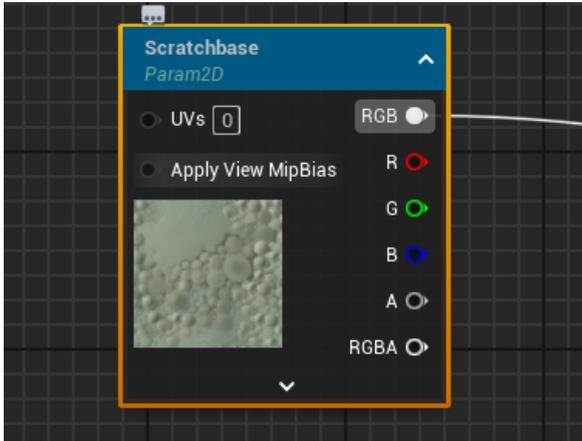
Now add your Base Color texture under *Basecolor*.



For *metallic/roughness*, your metallic roughness texture belongs in (use the correct color outputs configured in your texture and then connect them to the result node).



The *Scratchbase* Node now contains a base color texture into which you can add scratches (which you have to create with Substance Painter, for example).



It looks like this, for example.



Changelog

Version 1.0 (07-2024)

- Initial release
- Basic functionalities

Version 1.1 (08-2024)

- [Network Replication](#)
- Support for [non-physics-simulating](#) Actors and [Non-Vehicle Actors](#)
- Support for impulses through new [AddHitToLocation](#) function
- Various refactorings of the component
- Removed: "Vehicle Material" setting

Version 1.2 (09-2024)

- [12 new functions](#) have been added to influence the materials from the Procedural Mesh, for example to control the vehicle lighting.
- New getter function has been added to expose the Procedural Mesh.
- A bug that only one material slot is taken into account (the last index) is also fixed.

Version 1.3 (10-2024)

- Demo map:
 - A bug has been fixed in the demo map where the tires constantly slipped into the ground
 - Collisions in the demonstration vehicle have been reworked
- C++ optimizations have been made. Among other things, all for loops processing large data sets have been parallelized and are now executed using a multithreading process, which applies dynamic chunking depending on system performance and the size of the data set.
- Multiple UVs are now supported, up to 4 per section of the static mesh.
- The damage model has been completely revised. Among other improvements, you can now define the damage falloff via a curve. In the curve, you can determine precisely where the center of the damage is and how it should be distributed. You can also apply noise to make the damage appear more dynamic.
- An "*On Impact*" event has been added to allow binding, for example, to damage display widgets or anything that needs to be updated after an impact.
- Collision damping has been improved and now functions more effectively.
- And much more.