

## राष्ट्रीय प्रौद्योगिकी संस्थान पटना / NATIONAL INSTITUE OF TECHNOLOGY PATNA

संगणक विज्ञान एंव अभियांत्रिकी विभाग / DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING अशोक राजपथ, पटना-८०००५, बिहार / ASHOK RAJPATH, PATNA-800005, BIHAR

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No:-

CSXX2812 Computer Vision

L-T-P-Cr: 3-0-0-3

**Pre-requisites:** Linear algebra, Probability theory

**Objectives/Overview:** 

• To introduce various topics of computer vision with their applications.

#### **Course Outcomes:**

At the end of the course, a student will be able to understand:

| Sl.<br>No | Course Outcome (CO)  | Mapping to PO              |
|-----------|--|----------------------------|
| 1.        | Basic concepts of computer vision                                    | PO1, PO2                   |
| 2.        | Image formation and camera calibration                               | PO1, PO3                   |
| 3.        | Concepts of feature detection and matching                           | PO1, PO2,PO3               |
| 4.        | Concepts of signal processing and pattern recognition                | PO1, PO2,PO3,<br>PO4       |
| 5.        | Application of machine learning and deep learning in computer vision | PO1, PO2, PO3,<br>PO4, PO5 |
| 6.        | Application of medical imaging in computer vision.                   | PO1, PO2, PO3,<br>PO4, PO5 |

### **UNIT I: Image formation and camera calibration**

Introduction to computer vision, image basics, geometric camera models, orthographic and perspective projections, weak perspective projection, intrinsic and extrinsic camera parameters, linear and nonlinear approaches of camera calibration.

Lectures: 08

Lectures: 06

### **UNIT II: Feature detection and matching**

Edge detection, interest points and corners, local image features, feature matching and Hough transform, model fitting and RANSAC, scale invariant feature matching

### UNIT III: Signal Processing and Pattern Recognition Lectures: 10

Representation of multidimensional signals: Continuous signals, discrete signals, relation between continuous and discrete signals, Vector spaces and unitary transforms, Scale of signals, Scale space and diffusion, Multigrid representations; Motion: flow and correspondence, Optical flow-based motion estimation, Correlation and matching, Modeling of flow fields.

# UNIT IV: Machine learning and Deep learning in Computer Vision Lectures: 06

Image classification: CNN; Object detection: Fast RCNN, Faster RCNN, YOLO.

## **UNIT V: Medical Imaging**

Radiography—X-rays, interaction with matter, X-ray detectors, dual-energy imaging, image quality, equipment; X-ray computed tomography—X-ray detectors in CT, imaging, cardiac CT, dual-energy CT, image quality, equipment; Ultrasound imaging—Physics of acoustic waves, Generation and detection of ultrasound, Gray scale imaging, Doppler imaging, image quality, equipment; Medical image analysis—Manual analysis, Automated analysis, Computational strategies for automated medical image analysis, Geometric model matching using a transformation matrix.

Lectures: 12

#### Text/Reference Books

- 1. Forsyth, D. A. and Ponce, J., "Computer Vision: A Modern Approach", Prentice Hall, 2nd Ed.
- 2. Jahne, B., "Computer Vision and Applications", Academic press.
- 3. P. Suetens, "Fundamentals of Medical Imaging", Cambridge University Press.