Module 03.01a Parts & Purpose Student Guided Notes

At the end of this unit, s	students will be able to:	
Describe	and	
Describe	and their	or
What is the	e basic equipment that all o	drone pilots will utilize?
The Drone		
The drone is a	and we will b	e referencing its parts as basic
equipment to We will focus our attention		
		amiliar to our group, used
, and	available "off the shelf".	are available and
historically have been t	he precursor to the technolog	gies in use today but our focus wil
be on the		
We're reviewing hardw	are that is:	
off-the-shelf		
 commonly used 	in mapping	
 familiar to indust 	ry and practitioners	

Equipment- Drone Parts

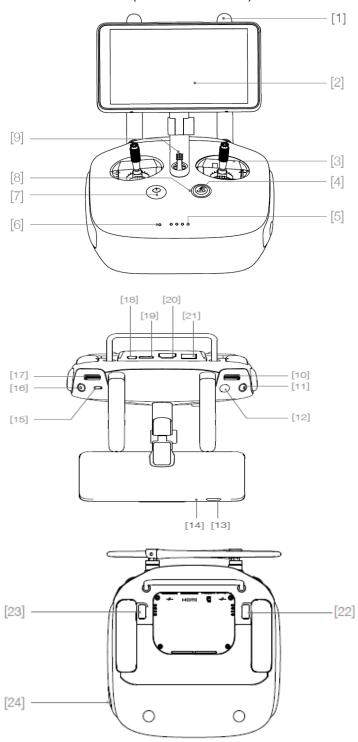
(Label the following using the link provided https://www.dronefly.com/the-anatomy-of-a-drone)



providing enough	
The top materials used in drones today are	(CRFCs)
especially in the frames, and	
-These flash various colors to	show the user what direction the drone
is facing. The two flashing red lights show the fr	
lights are the back of the droneals	
aircraft of the presence. The safety lig	
all craft of the presence. The safety lig	grits riave long range visibility.
Gimbal; 3-axis - A motor is placed on the 3 diffe	erent axes around the camera or sensor.
When the sensors detect	
cancel it. This happens almost instantly as thou	
provide smooth footage and	
Landing Gear for drones	
This can help	They can widen the drones
"stance", allowing for a more	and landing
Mini CD Diale Clat While you can fly a drawn wi	ith aut a mini CD and
Mini SD Disk Slot - While you can fly a drone wi	
commonly used to collect image data.	32GB or 64GB are
commonly used to collect image data.	
- The port used to cor	nnect the to other equipment.
While this port can be used to connect to the dr	
primary use is to	
	· · · · · · · · · · · · · · · · · · ·
Mataus Dilluses (DI DO))
Motors - DJI uses (BLDC)	
are industrial motors designed for multirotor sys	
rotating and	rotating).
- Front	t, rear, and bottom sensors are the main
components of a drones These	are used to maintain position, hover
indoors, and operate in areas where	
Propellers - Propellers have specific design con	sideration for each drone.
Considerations include rotational,	of blade, of blades, and of
blades. Propellers may have 2, 3, 4, and even	
the motors, push air in a specific direction creat	ing the propulsion needed for the aircraft
to fly and maneuver.	

Real Time Kinematic positioning using Global Navigation Satellite
System. GPS drones are equipped with a GPS module that allows them to know their
location relative to a RTK follows the same general
concept, but RTK station and a rover to reduce The
base station transmits correction data to the rover on a continuous basis allowing for the
most accurate of dronedata.
The controller
The controller is with the drone and works by sending from the remote
control to The signal tells the drone what operation to perform
(). Radio signals are sent from the radio
in the drone controller and received by the drone's via that
are either visible or embedded within the drone and the controller let's look at a DJI
Phantom 4 Controller to
Identify its parts
Describe basic components
While controllers may vary to some degree, operationally, a drone is piloted by a pilot on
this piece of equipment as it
Controller (DJI P4 Pro & Pro+ picture)
Pilot's Controls
Each will have its own controller and will be to it for pilot
Models vary by make and model of drone but all have some basic features needed for flight operations.
Using the Powerpoint of DJI Pro Manual PRovided list the parts and provide their description for the Sample Controller pictured below (1 to 24):

Phantom 4 Pro+ (Model: GL300E)



1.

2.

3.

4.

5.

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24.

The Camera and/or Sensors

Sensors and sensor technology is a	in Unmanned Aerial Vehicle
(UAV). It is for a drone to have many of the	
embedded within. A 3 axis accelerometer sensor to h	elp the drone.
A.gyroscope sensor is used to provide	_motion to the drone. A
Magnetometer sensor present in the drone that has $_$	A Barometer
sensor (or) to determine the o	of the UAV. A GPS sensor that
uses satellites that have been launched around the ea	arth to determine specific
geographic locations. A Distance sensor used to help	detect obstacles in the path of the
UAV. There are more and the list is quite extensive. (
are what have enabled UAVs to	take flight and be utilized in the
fashion that we rely on today. Our focus in this unit, h	
we mount on our UAV to enal	ble data needed
for in the field.	
The Camera is a	
Cameras or Sensors mounted on our UAVs rely on sp	•
and convert (EMS) waves	into digital images that we can use
to problems oruseful artifacts. For bet	
term "sensor" (and oftentimes the type of sensor, like	
we mount on our UAV () to capture	data.
To better understand the equipment and the work we	
important to share a basic introductory knowledge of t	
(EMS), both visible light rays and non-visible light wav	ves provides a
nice introduction for us to follow:	
https://youtu.be/lwfJPc-rSXw	
UAV Image sensors	
One primary usage of UAVs, especially as it relates to	
high quality images, from both	portions of the
, in order to obtain a high le	
be This data can then be fu	
good, detect trends and	cnanges or potential
that might arise.	

The cameras and sensors used in UAV field can be categorized by the portion of the electromagnetic spectrum they utilize:

• V	= RGB – Visible To The Human Eye				
	= NIR – Mostly Invisible to the Human Eye				
	= IR - Invisible To The Human Eye				
	Mixed Visible and Invisible wavelength				
channels					
RGB sensors					
	(like the camera on your cell phone)				
that takes photographs or videos a	nd format on a				
	meras, which expose chemical film strips to light, a				
	that converts light photons into and				
	ge. Below is a picture of the lens, image sensor, and				
_	n a digital camera using visible light (image courtesy				
LUCID). For more information on d					
•	nderstanding-digital-image-sensors/#				
Sensor Functions:					
Photoelectric Conversion Convers prices in the sectrons					
2. Charge Accumulation Colects generated charge as signal charge	The state of the s				
3. Transfer Signal Noves signal charge to detecting node	A State of the sta				
4. Signal Detection Converts signal change rion electrical signal los	Spiece and Company				
5. Analog to Digital Conversion	Window.				
Converts voltage into agital value					
Near Infrared (NIR) & Infrared (IR	i) image sensors				
use sensors that v	work quite similar to that of, but they				
	hat is NIR				
	that is to the				
	550nm to 950nm) while Infrared radiation (IR),				
sometimes referred to simply as	, is a region of the electromagnetic spectrum				
	onger wavelengths (wavelengths of about 700 nm to				
1mm). The NIR & IR response is f	ree from (Image courtesy of Optics				
for Hire)					
0,75 µm 1.4 µm 3 µm	8 μm 15 μm 1000 μm				
Near- infrared wave Short wave	Medium Long Far-infrared wave wave				
Gamma X Rays Ultraviolet Rays Rays	Infrared Microwave Radio Waves				

1 mm 10³ μm

1 pm 10-6 μm

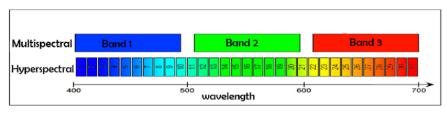
1 nm 10-3 μm

1 km 10° μm

1 m 106 μm

Multi-spectral image sensors

Multispectral imagery is produced by sensors that measure		within		
several specific sections (also called band	ls) of the	. Multispectral		
sensors usually have between	different band measurements in	pixel of the		
images they produce. Examples of bands in these sensors typically include				
, visible red band,	near infrared band, etc.			
imagery consists of much narrower bands	and discrete contiguous wavelength	is or		
"" within the EMS bands. A hy	perspectral image could have			
of bands.				



(Jasinski, et al., 2010)