

Linear Algebra MAT313 Fall 2022

Professor Sormani

Lesson 20

Linear Combinations, Spans, Linear Independence, and Basis of a Subspace of Euclidean Space

*You will cut and paste the photos of your notes and completed classwork and a **selfie taken holding up the first page of your work** in a googledoc entitled:*

MAT313F22-lesson20-lastname-firstname

and share editing of that document with me sormanic@gmail.com.

*If you have a question, type **QUESTION** in your googledoc next to the point in your notes that has a question and email me with the subject **MAT313 QUESTION**. I will answer your question by inserting a photo into your googledoc or making an extra video.*

This lesson has four parts with homework for each part and everyone must learn all four parts, but you may choose to do them on different dates. Instead of playlists, the videos can be found right next to the notes. Alternatively you can watch the full [313F21-10 Playlist](#).

Classwork is the notes for the lesson.

Part 1: Linear Combinations and Spans

including solutions sets of homogeneous systems

Watch [Video 313F20-10-1](#)

Note this lesson was Lesson 10 in the past.



Lesson 10 Part I

Linear Combinations and Spans

Recall:

Defn Scalar Multiplication

$R \in \mathbb{R}$ and $\vec{v} \in \mathbb{R}^m$ then

$$R\vec{v} = R \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{pmatrix} = \begin{pmatrix} Rv_1 \\ Rv_2 \\ \vdots \\ Rv_m \end{pmatrix} \quad \begin{matrix} \text{ith entry} \\ [R\vec{v}]_i = R[v]_i \end{matrix}$$

Defn Addition of vectors in \mathbb{R}^m

$\vec{v}, \vec{w} \in \mathbb{R}^m$

$$\vec{v} + \vec{w} = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{pmatrix} + \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_m \end{pmatrix} = \begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \\ \vdots \\ v_m + w_m \end{pmatrix} \quad \begin{matrix} \text{ith entry} \\ [v+w]_i = v_i + w_i \end{matrix}$$

New Defn:

A linear combination of two vectors \vec{v} and \vec{w} by two real numbers a, b is $a\vec{v} + b\vec{w}$

$$a \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{pmatrix} + b \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_m \end{pmatrix} = \begin{pmatrix} av_1 + bw_1 \\ av_2 + bw_2 \\ \vdots \\ av_m + bw_m \end{pmatrix}$$

Show by combining scalar multiplication +

$$[a\vec{v} + b\vec{w}]_i = a[v]_i + b[w]_i$$

Linear Algebra

Abstract_Algebra... Linear Algebra Proofs and Domi... Unti

New Defn:

A linear combination of two vectors \vec{v}_1 and \vec{v}_2 by two real numbers a_1, a_2 is $a_1\vec{v}_1 + a_2\vec{v}_2$

$$a_1 \begin{pmatrix} v_{11} \\ v_{21} \\ \vdots \\ v_{m1} \end{pmatrix} + a_2 \begin{pmatrix} v_{12} \\ v_{22} \\ \vdots \\ v_{m2} \end{pmatrix} = \begin{pmatrix} av_1 + bv_1 \\ av_2 + bv_2 \\ \vdots \\ av_m + bv_m \end{pmatrix}$$

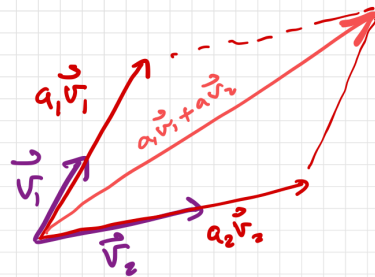
Shown by combining scalar mult + vector +

$$[a_1\vec{v}_1 + a_2\vec{v}_2]_i = a_1[\vec{v}_1]_i + a_2[\vec{v}_2]_i$$

Linear Algebra

Linear Algebra Untitled Notebook Abstract_Algebra_1-5

New Defn: Given a collection of vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3, \dots, \vec{v}_k \in \mathbb{R}^m$ a linear combination $\sum_{i=1}^k a_i \vec{v}_i = a_1\vec{v}_1 + a_2\vec{v}_2 + \dots + a_k\vec{v}_k$ where $a_1, a_2, \dots, a_k \in \mathbb{R}$





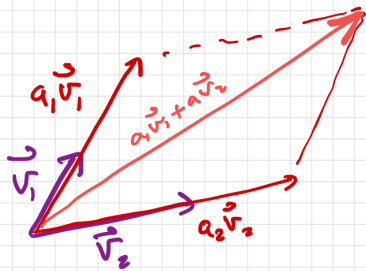
New Defn: Given a collection of vectors

$$\vec{v}_1, \vec{v}_2, \vec{v}_3 \dots \vec{v}_k \in \mathbb{R}^m$$

a linear combination

$$\sum_{i=1}^k a_i \vec{v}_i = a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_k \vec{v}_k$$

where $a_1, a_2, \dots, a_k \in \mathbb{R}$



Recall our solution sets of homogeneous systems

$$\begin{cases} x_1 \\ x_2 \\ \vdots \\ x_m \end{cases} = x_2 \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix} + x_3 \begin{pmatrix} w_1 \\ \vdots \\ w_m \end{pmatrix}$$

Summed up
free variables
 times directions

Linear Combo of the Directions.

3:38 AM Mon Sep 14

Linear Algebra

Abstract_Algebr... Linear Algebra Proofs and Domi... Unti

New Defn Given a collection of vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \in \mathbb{R}^m$ the span $\langle \vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \rangle$ is the set of all linear combinations:

$$= \left\{ a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_k \vec{v}_k : a_i \in \mathbb{R} \right\}$$

free

$$= \left\{ \sum_{i=1}^k a_i \vec{v}_i : a_i \in \mathbb{R} \right\}$$

run free through \mathbb{R}

Linear Algebra

Linear Algebra Untitled Notebook Abstract_Algebra_1-5

$\langle \vec{v}_1, \vec{v}_2 \rangle = \{ a_1 \vec{v}_1 + a_2 \vec{v}_2 \mid a_i \in \mathbb{R} \}$

Example $\langle \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rangle$

$$= \left\{ a_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + a_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \mid a_i \in \mathbb{R} \right\}$$

$$= \left\{ \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \mid a_i \in \mathbb{R} \right\}$$

$$= \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \mid x, y \in \mathbb{R} \right\}$$

xy plane

For HW hints see [Video 313F20-10-2](#)

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Linear Algebra

HW1 Is $\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \in \langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rangle$?
xy plane

HW2 Is $\begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix} \in \langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rangle$?

HW3 Is $\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \in \langle \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \rangle$?

HW4 Is $\begin{pmatrix} 1 \\ 4 \\ 4 \end{pmatrix} \in \langle \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \rangle$?

Linear Algebra

HW5 Is $\begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{pmatrix} \in \langle \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 2 \\ 2 \\ 2 \end{pmatrix} \rangle$?

Do HW1-5 before Part 2. Note that to solve HW5 there are five equations and three unknowns: you need to solve a system for a, b, and c. Then reduce that system to Echelon form. You do not need to find a, b, and c but must check if that system has a solution by checking any row of zeroes in Echelon form ends in a zero.

Part 2: Subspaces of m dimensional Euclidean Space

Watch [Video 313F20-10-3](#) for the definition of a subspace:

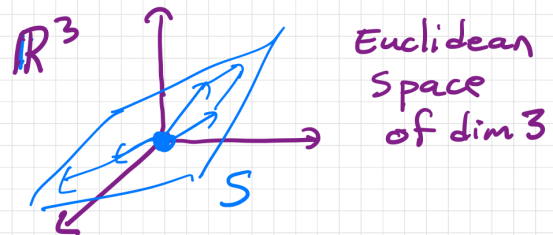
Lesson 10 Part 2 Subspaces

Recall $\vec{v} \in \mathbb{R}^m$ vectors

\mathbb{R}^m Euclidean Space
of dimension m

$\mathbb{R}^1 = \text{real line (dim=1)}$
↔

\mathbb{R}^2 ↔ Euclidean
plane (dim=2)

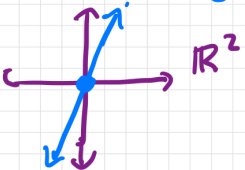


A subspace $S \subset \mathbb{R}^m$
is a collection of vectors
that includes $\vec{0}$ and
is "closed under addition"
($\forall \vec{v}, \vec{w} \in S \vec{v} + \vec{w} \in S$)
and "closed under scalar mult"
($\forall R \in \mathbb{R} \vec{v} \in S, R\vec{v} \in S$)

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Linear Algebra

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Example $S = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ mx \end{pmatrix} : x \in \mathbb{R} \right\} \subset \mathbb{R}^2$

check this is a subspace

$\vec{0} \in S$? yes at $x=0$ $\begin{pmatrix} 0 \\ m \cdot 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

closed under addition? yes

$\vec{v}, \vec{w} \in S$ $\vec{v} = \begin{pmatrix} x_1 \\ mx_1 \end{pmatrix}$ $\vec{w} = \begin{pmatrix} x_2 \\ mx_2 \end{pmatrix}$

$\vec{v} + \vec{w} = \begin{pmatrix} x_1 \\ mx_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ mx_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ m(x_1 + x_2) \end{pmatrix}$

$= \begin{pmatrix} x_1 + x_2 \\ m(x_1 + x_2) \end{pmatrix} \in S$

Yes because $x_1 + x_2 \in \mathbb{R}$

Linear Algebra

Linear Algebra Untitled Notebook Abstract_Algebra_1-5

closed under scalar?

$R \in \mathbb{R}$ $\vec{v} \in S$ $\vec{v} = \begin{pmatrix} x \\ mx \end{pmatrix}$

$R\vec{v} = R \begin{pmatrix} x \\ mx \end{pmatrix} = \begin{pmatrix} Rx \\ Rmx \end{pmatrix} = \begin{pmatrix} Rx \\ m(Rx) \end{pmatrix}$

$\in S$ because $Rx \in \mathbb{R}$

Yes

So S is a subspace of \mathbb{R}^2 .

See [Video 313F20-10-3not](#) for examples of spaces that are not subspaces as in the following three photos. You may choose to only watch the parabola.

An example of a set $S \subseteq \mathbb{R}^2$ which is not a subspace.

Check $\vec{0} \in S = \{(x, y) : y = x^2\}$

$\vec{0} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \leftarrow 0 = 0^2 \checkmark$

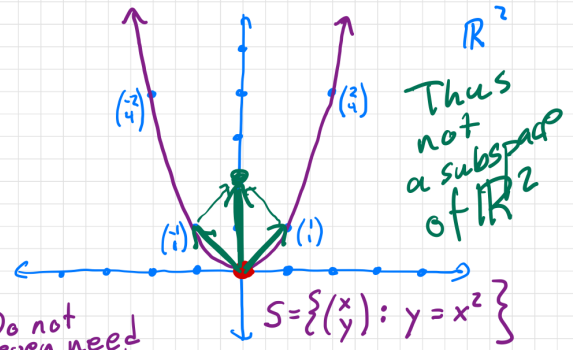
Check S is closed under add.

Given $\vec{v}, \vec{w} \in S$ show $\vec{v} + \vec{w} \in S$

$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$ where $v_2 = v_1^2$ } because they are in S
 $\vec{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$ where $w_2 = w_1^2$

$\vec{v} + \vec{w} = \begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \end{pmatrix}$ Check this is in S

$v_2 + w_2 \stackrel{?}{=} (v_1 + w_1)^2$
 $= v_1^2 + 2v_1w_1 + w_1^2$
 $= v_2 + 2v_1w_1 + w_2$



Do not even need to check closed under scalar because it already fails closed under addition when $2v_1w_1 \neq 0$

Counter example: Not closed under addition
 $\vec{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $\vec{w} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$\vec{v} + \vec{w} = \begin{pmatrix} 1 + (-1) \\ 1 + 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix} \notin S$ because $2 \neq 0^2$

$$S = \left\{ \begin{pmatrix} \cos \theta \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \sin \theta \end{pmatrix} : \theta \in \mathbb{R} \right\}$$

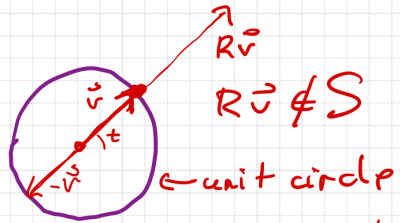
Is this closed under scalar mult?

Take $\vec{v} \in S$ $\vec{v} = \begin{pmatrix} \cos t \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \sin t \end{pmatrix}$

So $\vec{v} = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix}$

Check $R\vec{v} \in S$:

$$R\vec{v} = R \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} = \begin{pmatrix} R \cos t \\ R \sin t \end{pmatrix}$$



Is $R\vec{v} \in S$? FAILS

$$\begin{pmatrix} R \cos t \\ R \sin t \end{pmatrix} = \begin{pmatrix} \cos \theta \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \sin \theta \end{pmatrix}$$

try to solve for θ

$R \cos t = \cos \theta$?
 $R \sin t = \sin \theta$?
How to solve? No solution unless $R=1$

No solution.
Notice $\frac{(R \cos t)^2 + (R \sin t)^2}{R^2} = \frac{(\cos t)^2 + (\sin t)^2}{1} = 1$

$$S = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \mid y = 5x + 2 \right\}$$

Show S fails
to have $\vec{0} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$0 \stackrel{?}{=} 5 \cdot 0 + 2 = 2$$

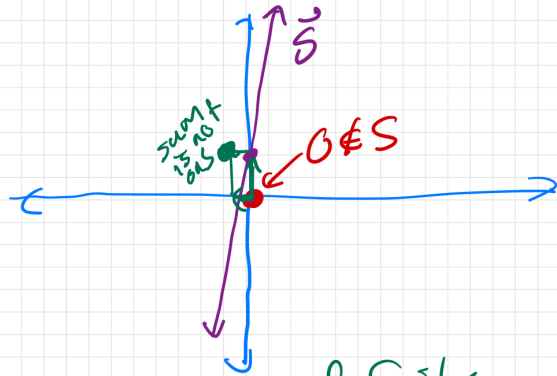
Fails

Show S fails closed
under addition

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \quad v_2 = 5v_1 + 2$$

$$\vec{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \quad w_2 = 5w_1 + 2$$

$$\vec{v} + \vec{w} = \begin{pmatrix} v_1 + w_1 \\ v_2 + w_2 \end{pmatrix} \quad \begin{array}{l} \text{Checks} \\ v_2 + w_2 \stackrel{?}{=} 5(v_1 + w_1) + 2 \\ \text{this will fail} \end{array}$$



The proof fails

$$v_2 + w_2 \stackrel{?}{=} 5(v_1 + w_1) + 2$$

$$(5v_1 + 2) + (5w_1 + 2) \stackrel{?}{=} 5v_1 + 5w_1 + 2$$

$$2 \neq 0?!$$

Counter example

- Choose any two vectors on S and add them. Show the sum is not on S

$$S = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \mid y = 5x + 2 \right\}$$

Show S fails
to have $\vec{0} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

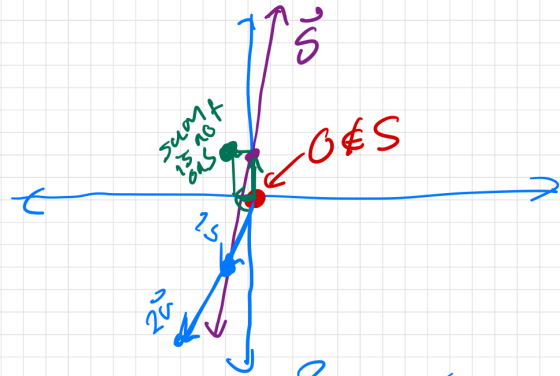
$$0 \stackrel{?}{=} 5 \cdot 0 + 2 = 2$$

Fails

Show closed under
scalar fails.

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \quad v_2 = 5v_1 + 2$$

$$R\vec{v} = \begin{pmatrix} Rv_1 \\ Rv_2 \end{pmatrix} \quad \text{check} \\ Rv_2 \stackrel{?}{=} 5(Rv_1) + 2 \\ R(5v_1 + 2) \stackrel{?}{=} 5Rv_1 + 2$$

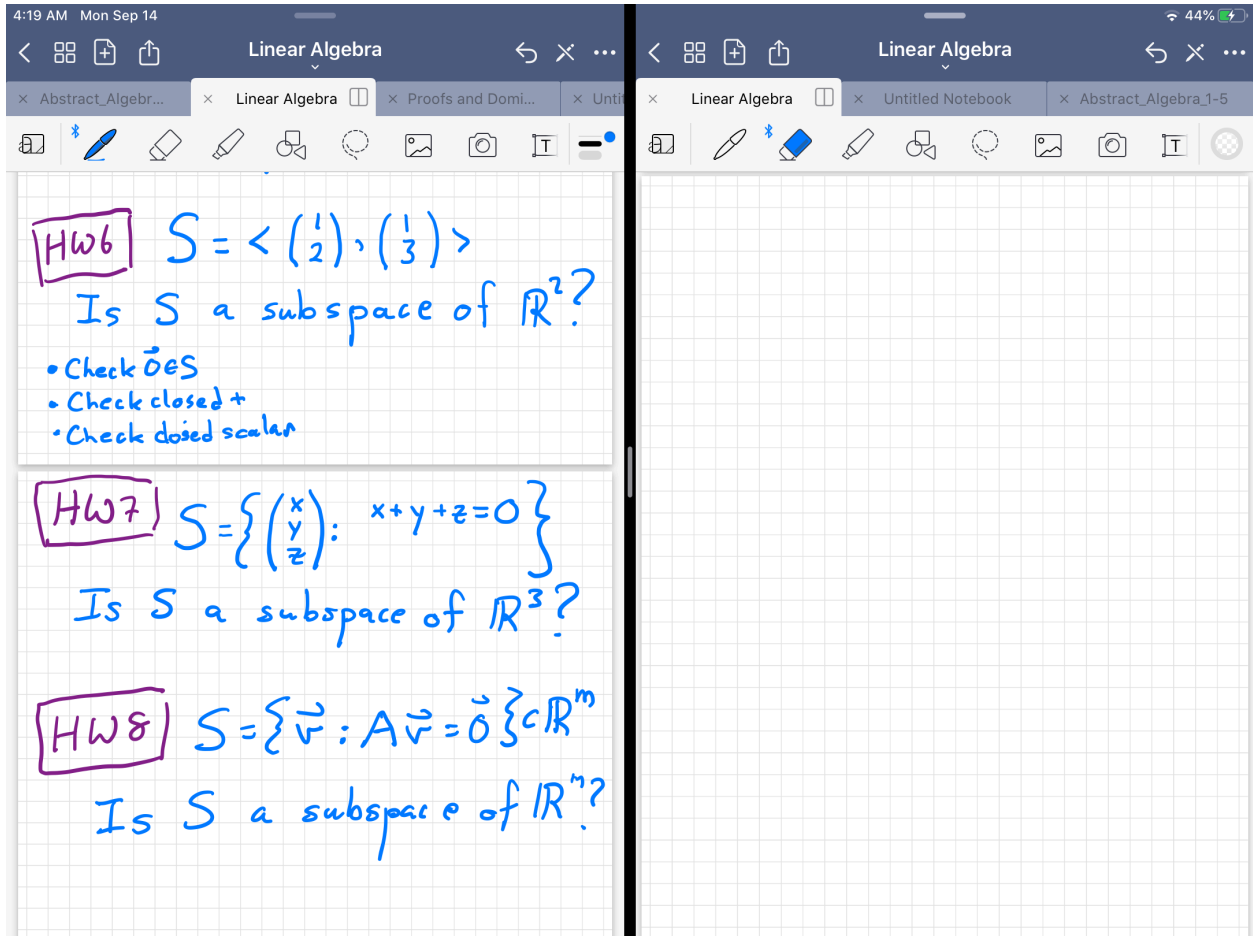


$$R \cdot 5v_1 + R \cdot 2 \stackrel{?}{=} 5Rv_1 + 2$$

$$R \cdot 2 = 2 \quad \text{fails unless } R=1.$$

Not closed under scalar

Counter example:
take any v on the line
and mult by any $R \neq 1$



Complete the above HW before starting Part 3.

For HW6 -HW8 be sure to check the 0 vector is in the set, and that it is closed under addition and closed under scalar. For HW hints see [Video 313F20-10-4](#) and if necessary more hints in [Video 313F20-10-4more](#) if you are having trouble.

Be sure to check these HW hints videos above before submitting your work.

Part 3: linearly independent vectors

Watch [Video 313F20-10-5a](#) for the definition and then [Video 313F20-10-5b](#) for classwork and hw hints:

Linearly Independent Vectors

Defn: A collection of vectors, $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$,
is linearly independent if

$$\underbrace{\sum_{j=1}^k t_j \vec{v}_j}_{\text{linear combination}} = \vec{0} \iff \text{all the } t_j = 0 \text{ for } j=1,2,\dots,k$$

$$t_1 \vec{v}_1 + t_2 \vec{v}_2 + \dots + t_k \vec{v}_k = \vec{0}$$

solve for t_1, t_2, \dots, t_k
to this homogeneous system.

Watch [Video 313F20-10-5b](#) for the following classwork and HW9-10 hints:

Classwork:
Are $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix}$ lin. indep.?

$$t_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + t_3 \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1t_1 + 0t_2 + 2t_3 \\ 0t_1 + 1t_2 + 3t_3 \\ 0t_1 + 0t_2 + 0t_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

no leaders
in a
column
so a free
variable

$$\left[\begin{array}{ccc|c} \boxed{1} & 0 & 2 & 0 \\ 0 & 0 & \boxed{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R_2 \rightarrow \frac{1}{3}R_2} \left[\begin{array}{ccc|c} \boxed{1} & 0 & 2 & 0 \\ 0 & 0 & \boxed{1} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

2 leaders and one free variable

The solution set is not just $\{\vec{0}\}$

There are t_1, t_2, t_3 not all zero
such that

$$t_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + t_3 \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Thus $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix}$ is not lin indep.

HW9 Are $\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$ $\begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$
linearly independent?
Hint solve $t_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + t_2 \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} + t_3 \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

HW10 Are $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ $\begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$
linearly independent?
Show all work!

Hint: no free variables $\Leftrightarrow \begin{pmatrix} t_1 \\ \vdots \\ t_k \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$
then your vectors are lin. indep

However if there are free variables
then vectors are not lin. indep.

Hint: You do not need to write the
solution set.

Complete the above HW before starting Part 4

Part 4: Basis of a subspace

Watch [Video 313F20-10-6better](#) which includes homework hints:

Lesson 10 Part **IV**Basis of a SubspaceDefn

Suppose $S \subset \mathbb{R}^m$ is a subspace
we say $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ is
a "basis" for S if

$$S = \langle \vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \rangle$$

and

$\vec{v}_1, \dots, \vec{v}_k$ are linearly
independent

Example:

$$S = \left\{ \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} : x, y \in \mathbb{R} \right\}$$

$\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ are a basis.

To see this we check

$$S = \langle \vec{v}_1, \vec{v}_2 \rangle$$

proof:

$$\langle \vec{v}_1, \vec{v}_2 \rangle = \left\{ t_1 \vec{v}_1 + t_2 \vec{v}_2 \mid t_1, t_2 \in \mathbb{R} \right\}$$

$$= \left\{ t_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \mid t_1, t_2 \in \mathbb{R} \right\}$$

$$= \left\{ \begin{pmatrix} t_1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ t_2 \\ 0 \end{pmatrix} \mid t_1, t_2 \in \mathbb{R} \right\}$$

$$= \left\{ \begin{pmatrix} t_1 \\ t_2 \\ 0 \end{pmatrix} \mid t_1, t_2 \in \mathbb{R} \right\} = S$$

Also check
linearly indepfree variable
 $t_1 = x$ $t_2 = y$

$$t_1 \vec{v}_1 + t_2 \vec{v}_2 = \vec{0} \iff t_1 = 0 \text{ and } t_2 = 0.$$

Lesson 10 Part IVBasis of a SubspaceDefnSuppose $S \subset \mathbb{R}^m$ is a subspacewe say $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ is
a "basis" for S if

$$S = \langle \vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \rangle$$

and

 $\vec{v}_1, \dots, \vec{v}_k$ are linearly
independent

$$t_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} t_1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ t_2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} t_1 \\ t_2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$t_1 = 0 \text{ and } t_2 = 0$$

So they are lin indep

Span + Lin Indep

Thus they are
a basis.

$\text{Null}(A)$ is a subspace
we know how to find it

$\{ \vec{v} = \text{free variables times directions} \}$

$= \langle \text{span of the directions} \rangle$

To find the basis of a null space

- Find the direction vectors
- Check they are lin. indep.

Solution to a homogeneous system

Example

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{Find } \text{Null}(A) = ?$$

Find it and find its basis

$$\left(\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

already Echelon Form

$$1x + 0y + 0z = 0 \quad x = 0$$

$$0x + 1y + 0z = 0 \quad y = 0$$

$$0 = 0$$

$$z = z \text{ (free)}$$

$$\text{Null}(A) = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix} = z \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \mid z \in \mathbb{R} \right\}$$

↑
direction

$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ is a basis

$$\text{Null}(A) = \langle \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rangle$$

and $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ is lin indep

$$t \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \downarrow \\ t = 0$$



Example:

$$\begin{pmatrix} 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} = A$$

Find basis for $\text{Null}(A)$

Find $\text{Null}(A)$

$$\left(\begin{array}{cccc|c} 1 & 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

already
reduced echelon

$$x_1 + 0x_2 + 0x_3 + 2x_4 = 0$$

$$x_3 = 0$$

$$x_1 = -2x_4$$

$$x_2 = x_2 \text{ (free)}$$

$$x_3 = 0$$

$$x_4 = x_4 \text{ (free)}$$

$$\text{Null}(A) = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \end{pmatrix} \mid x_2, x_4 \in \mathbb{R} \right\}$$

$$= \left\langle \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\rangle \text{ span Null}(A)$$

Next check the directions
are linearly indep.



$$t_1 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ t_1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -2t_2 \\ 0 \\ 0 \\ t_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -2t_2 \\ t_1 \\ 0 \\ t_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$-2t_2 = 0$$

$$t_1 = 0$$

$$0 = 0$$

$$t_2 = 0$$

$$t_1 = 0$$

$$t_2 = 0$$

Therefore $\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \end{pmatrix}$

are linearly indep

Since they also span null(A)

They are a basis for $\text{null}(A)$

HW 11 $S = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} : \begin{cases} 2x + y + z = 0 \\ x + y + z = 0 \\ 3x + 2y + 2z = 0 \end{cases} \right\}$

Find a basis for S .

Step 1 Solve it

Step 2 Check the direction vectors are lin indep

The basis is the direction vectors.

HW 12 $A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \end{pmatrix}$

Find the basis for $\text{Null}(A)$

← Same Step 1 and Step 2.

Next lesson:
How to find a basis of an S which is defined by a span of vectors that are not linearly indep.

There are **12 homework problems** above. Here's the **full playlist for the lesson** to check if you watched everything..

Don't forget to help your team with extra credit. Just search for team in your googledocs.

Check your homework using these [solutions](#). Email me if your answers are different because they might also be correct.

Share with Professor Sormani at sormanic@gmail.com. Please email questions to Professor Sormani.

Note this lesson was Lesson 10 in the past.