

# **ADAMAS UNIVERSITY**

SCHOOL OF ENGINEERING & TECHNOLOGY

Department of Mechanical Engineering

# B.Tech in Mechanical Engineering Programme Course File (Theory)

Course Code & Name: MEE11002 & Engineering

Mechanics

Course Coordinator: Mr. Sudip Chakraborty



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002



**Semester: II** 

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7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **THEORY COURSE FILE CONTENTS**

## **Check list Course Outcomes Attainment**

S. No.	Contents	Available (Y/N/NA)	Date of Submission	Signature of HOD
1.	Authenticated Syllabus Copy	Y		_
2.	Individual Time Table	Y		
3.	Students' Name List (Approved Copy)	Y		
4.	Course Plan, PO, PSO, COs, CO-PO Mapping, COA Plan, Session Plan and Periodic Monitoring	Y		
5.	Previous Year End Semester Question Papers	Y		
6.	Question Bank (All Units - Part A, Part B & C)	Y		
7.	Dissemination of Syllabus and Course Plan to Students	Y		
8.	Lecture Notes - Unit I, II & III	Y		
9.	Assessment - Tutorials / Assignments / Class Test / Open Book Test / Quiz / Project / Seminar / Role Play if any (Before Mid Term)			
10.	<ul> <li>Mid Term Examination</li> <li>A. Question Paper / Any Other Assessment Tools Used</li> <li>B. Sample Answer Scripts (Best, Average, Poor) if required</li> <li>C. Evaluation Sheet</li> <li>D. Slow Learners List and Remedial Measures</li> </ul>			
11.	Lecture Notes – Unit IV & V			
12.	Sample Documents and Evaluation Sheet for Internal Assessment – Tutorials / Assignments / Class Test / Open Book Test / Quiz / Project / Seminar / Role Play if any (After Mid Term)			
13.	Course End Survey (Indirect Assessment) & Consolidation			
14.	End Term Examination  A. Question Paper & Answer Key  B. Sample Answer Scripts (Best, Average, Poor) if			



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	required		
	C. Evaluation Sheet		
	<b>D.</b> Slow Learners List and Remedial Measures.		
15.	Content Beyond the Syllabus (Proof)		
16.	Innovative Teaching Tools Used for TLP		
17.	Details of Visiting Faculty Session / Industry Expert / Guest Lecture / Seminar / Field Visit / Webinars / Flipped Class Room / Blended Learning / Online Resources etc.		
18.	Consolidated Mark Statement		
19.	CO Attainment (Mid Term + Internal Assessment + End Term)		
20.	Gap Analysis & Remedial Measures		
21.	CO - PO Attainment	_	
22.	Class Record (Faculty Logbook)		

Signature of HOD/ Dean	Signature of Faculty
Date:	Date:



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## Syllabus Copy

Course Code: MEE11002	Course Name: Engineering Mechanics	L	Т	P	С
Version 1.0		3	1	0	4
Pre-requisites/Exposur	12 <sup>th</sup> level Physics, Mathematics				
e					
Co-requisites					

## **Course Objectives:**

- 1. To enable learners to solve force problems related to practical world.
- 2. To be able to determine the centroid, centre of gravity and moment of inertia.
- 3. To learn the effect of friction on equilibrium.
- 4. To learn kinematics, kinetics of particle and rigid body, related principles.
- 5. To introduce the concepts of Dynamic motion

#### **Course Content**

## Module 1

#### **Basics of Statics and Concurrent Forces**

**Statics of Particles:** Force System: Force, classification & representation, force as a vector, composition and resolution of forces, principle of superposition and transmissibility of forces.

11 lecture hours

**Statics of Rigid bodies:** Equilibrium of coplanar force system, free body diagrams, determination of reactions, equilibrium of a body under three forces, Lami's theorem. Moment of a force about a point and an axis, moment of coplanar force system, Varignan's theorem.

## Module 2: 18 lecture hours

#### **Parallel and Distributed Forces**

Parallel forces in a plane, Distributed Parallel forces in a plane, couple, resolution of a force into a force and a couple, moment of a couple.

**Centroid and Moment of Inertia:** Determination of centre of gravity, centre of mass and centroid by direct integration and by the method of composite bodies, area moment of inertia of composite plane figures and mass moment of inertia, radius of gyration, parallel axis theorem, Pappas theorems, polar moment of inertia.

## Module 3: 13 lecture hours



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**Friction:** Introduction to static and dynamic friction, laws of dry friction, cone of friction, block friction, ladder friction, wedge friction, application of friction in machines.

Module 4: 8 lecture hours

**Virtual Work** Virtual displacement, principle of virtual work.

Module 5: 10 lecture hours

**Introduction to Dynamics** Laws of motion, Projectile motion, D'Alembert's Principle, Work and energy, impulse and momentum, impact of bodies.

## **Text Books**

- 1. Engineering Mechanics [Vol-I & II] by Meriam&Kraige, 5th ed. Wiley India
- 2. Engineering Mechanics by S.S. Bhavikatti and K.G. Rajashekarappa New Age International
- 3. Mechanics of Solids by Crandall, Dahl and Sivakumar-MC Graw Hill ,5th Edition 2015, New Delhi

## **Reference Books**

- 1. Engineering Mechanics: Statics & Dynamics by I.H.Shames, 4th ed. PHI
- 2. Engineering Mechanics by Timoshenko, Young and Rao, Revised 4th ed. TMH

#### **Web Resources:**

- https://nptel.ac.in/courses/112/106/112106286
- https://nptel.ac.in/courses/112/103/112103108



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## **Faculty Individual Time Table**

ADAMAS UNIVERSITY, KOLKATA										
	SCHOOL OF ENGINEERING MECHANICS									
		DEPAR	TMENT OF ME	ECHANICAL	ENGINEERI	ING				
			Prograi	mme: B.Tec	h					
Course Code & Course: MEE11002, Engineering Mechanics Faculty Coordinator: Mr. Sudip Chakraborty										
Day & Time	09.30 - 10.30	10.30 - 11.30	11.30 - 12.30	12.30 - 1.30	01.30 - 02.30	02.30 - 03.30	03.30 - 04.30	04.30 - 05.30		
Monday										
Tuesday				<b>.</b>						
Wednesday				LU NC						
Thursday										
Friday										

Signature of HOD	Signature of Class Coordinator
Date:	Date:



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## **Students Name List**

Name	Registration Number	Roll Number
Ravi lal	AU/2020/0004600	UG/02/BTBIOME/2020/002
Gaurav gain	AU/2020/0005281	UG/02/BTBIOME/2020/008
Soumyadeep Samaddar	AU/2020/0005498	UG/02/BTBIOME/2020/003
SPANDAN BHATTACHAARYA	AU/2020/0005499	UG/02/BTBIOME/2020/004
Arjya Das	AU/2020/0004536	UG/02/BTCE/2020/003
Rohit Kumar Shit	AU/2020/0004463	UG/02/BTCE/2020/002
SUNANDA JANA	AU/2020/0004275	UG/02/BTCSE/2020/002
Ritushna roy	AU/2020/0004466	UG/02/BTCSE/2020/009
Md Alnas Hossain	AU/2020/0004540	UG/02/BTCSE/2020/032
Nikhil Kumar Jha	AU/2020/0004565	UG/02/BTCSE/2020/035
RAJA BANIK	AU/2020/0004580	UG/02/BTCSE/2020/041
Arshad Raja	AU/2020/0004583	UG/02/BTCSE/2020/042
Hritik Kumar Dutta	AU/2020/0004593	UG/02/BTCSE/2020/046
SHIULI MAHATA	AU/2020/0004596	UG/02/BTCSE/2020/047
SOUGATA DUTT	AU/2020/0004472	UG/02/BTCSE/2020/012
Protyush Kr Chatterjee	AU/2020/0004479	UG/02/BTCSE/2020/018
Vivek Raj	AU/2020/0004549	UG/02/BTCSE/2020/033
Soyata Saha	AU/2020/0004562	UG/02/BTCSE/2020/034
SUPRATIM TARUN NATH	AU/2020/0004276	UG/02/BTCSE/2020/003
Atanu Pramanick	AU/2020/0004529	UG/02/BTCSE/2020/027
Ayan Kumar Das	AU/2020/0004530	UG/02/BTCSE/2020/028



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SURAJ MAJUMDER	AU/2020/0004462	ИС /02 /РТССЕ /2020 /007
Prima Giri	AU/2020/0004468	UG/02/BTCSE/2020/007
ADUIDCIT DUATTACUADICE	ATT /2020 /000 / 4 / 1	UG/02/BTCSE/2020/011
ABHIPSIT BHATTACHARJEE	AU/2020/0004451	UG/02/BTCSE/2020/004
Arkadeep Chatterjee	AU/2020/0004464	UG/02/BTCSE/2020/008
Indranil Das	AU/2020/0004494	UG/02/BTCSE/2020/022
ANIRBAN ROY	AU/2020/0005542	UG/02/BTCSE/2020/052
nandini roy	AU/2020/0004569	UG/02/BTCSE/2020/036
ALOK DUTTA	AU/2020/0004250	UG/02/BTCSE/2020/001
SOUMYADWIP MAITY	AU/2020/0004557	UG/02/BTCSEAIML/2020/006
Rohit kumar Roy	AU/2020/0004563	UG/02/BTCSEAIML/2020/009
Md Sohail Irfan	AU/2020/0004578	UG/02/BTCSEAIML/2020/013
SUBARNA BHOWMIK	AU/2020/0004572	UG/02/BTCSEAIML/2020/011
Chandrachur Majhi	AU/2020/0004588	UG/02/BTCSEAIML/2020/015
Sabyasachi Paul	AU/2020/0004587	UG/02/BTCSECSF/2020/006
Arya Paul	AU/2020/0004465	UG/02/BTECE/2020/001
Utsab Bose	AU/2020/0004486	UG/02/BTECE/2020/002
ROHIT RAJ HALDER	AU/2020/0004566	UG/02/BTECE/2020/004
Arka Jyoti Das	AU/2020/0004560	UG/02/BTEE/2020/002
Saptarshi Bhattacharjee	AU/2020/0004481	UG/02/BTEE/2020/001
Suman Hait	AU/2020/0004471	UG/02/BTME/2020/001
Koushik Ghosh	AU/2020/0004484	UG/02/BTME/2020/002
Reetam Mondal	AU/2020/0004555	UG/02/BTME/2020/005
Rakesh Kumar Mozumder	AU/2020/0004495	UG/02/BTME/2020/004



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Signature of HOD/Dean

**Signature of Class Coordinator** 

Date: Date:

## **COURSE PLAN**

Target	60% (marks)
Level-1	50% (population)
Level-2	60% (population)
Level-3	70% (population)

## 1. Method of Evaluation

UG
Internal Assessment (30%)
(Quizzes/Tests, Assignments & Seminars etc.)
Mid Semester Examination (20%)
End Semester Examination (50%)

## 2. Passing Criteria

Scale	UG
Out of 10 Point Scale	CGPA – "5.00" Min. Individual Course Grade – "C" Passing Minimum – 35

## 3. Pedagogy

- Direct Instruction
- Kinesthetic Learning
- Flipped Classroom
- Differentiated Instruction
- Expeditionary Learning
- Inquiry Based Learning
- Game Based Learning
- Personalized Learning
- 4. Topics introduced for the first time in the program through this course



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• (New Topics Related to this Course – Syllabus Revision if any/Content Beyond Syllabus)

## 5. References:

Text Books	Web Resources	Journals	Reference Books
3	2		2

Signature of HOD/Dean	Signature of Faculty
Date:	Date:



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## **GUIDELINES TO STUDY THE SUBJECT**

#### **Instructions to Students:**

- 1. Go through the 'Syllabus' in the LMS in order to find out the Reading List.
- 2. Get your schedule and try to pace your studies as close to the timeline as possible.
- 3. Get your on-line lecture notes (Content, videos) at <u>Lecture Notes</u> section. These are our lecture notes. Make sure you use them during this course.
- 4. check your LMS regularly
- 5. go through study material
- 6. check mails and announcements on blackboard
- 7. keep updated with the posts, assignments and examinations which shall be conducted on the blackboard
- 8. Be regular, so that you do not suffer in any way
- 9. Cell Phones and other Electronic Communication Devices: Cell phones and other electronic communication devices (such as Blackberries/Laptops) are not permitted in classes during Tests or the Mid/Final Examination. Such devices MUST be turned off in the class room.
- 10. **E-Mail and online learning tool:** Each student in the class should have an e-mail id and a pass word to access the LMS system regularly. Regularly, important information Date of conducting class tests, guest lectures, via online learning tool. The best way to arrange meetings with us or ask specific questions is by email and prior appointment. All the assignments preferably should be uploaded on online learning tool. Various research papers/reference material will be mailed/uploaded on online learning platform time to time.
- 11. **Attendance:** Students are required to have minimum attendance of 75% in each subject. Students with less than said percentage shall NOT be allowed to appear in the end semester examination.

This much should be enough to get you organized and on your way to having a great semester! If you need us for anything, send your feedback through e-mail <a href="mailto:sudip.chakraborty@adamasuniversity.ac.in">sudip.chakraborty@adamasuniversity.ac.in</a> Please use an appropriate subject line to indicate your message details.

There will no doubt be many more activities in the coming weeks. So, to keep up to date with all the latest developments, please keep visiting this website regularly.



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## **RELATED OUTCOMES**

## ${\bf 1.} \ \ \, {\bf The\ expected\ outcomes\ of\ the\ Program\ are:}$

P01	<b>Engineering knowledge:</b> Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
P02	<b>Problem analysis:</b> Identify, formulate, research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
P03	<b>Design/development of solutions:</b> Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
P04	<b>Conduct investigations of complex problems:</b> Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
P05	<b>Modern tool usage:</b> Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.
P06	<b>The engineer and society:</b> Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
P07	<b>Environment and sustainability:</b> Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development
P08	<b>Ethics:</b> Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
P09	<b>Individual and team work:</b> Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
PO10	<b>Communication:</b> Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
P011	<b>Project management and finance:</b> Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
P012	<b>Lifelong learning:</b> Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.



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## 2. The expected outcomes of the Specific Program are: (up to 3)

PSO1	Plan the manufacturing of given mechanical components and systems using engineering analysis & design tools, process planning and modern manufacturing methods
PSO2	Understand the dynamics of machine components and design components including power transmission, pressure vessels, IC engine components
PSO3	Determine the performance of thermal and fluid systems including IC engines, refrigeration and air-conditioning, and power generating systems

## 3. The expected outcomes of the Course are: (minimum 4 and maximum 6)

CO1	On completion of this course, the students will be able to Apply conditions of equilibrium of bodies subjected to forces
CO2	Determine the centroid, centre of gravity and moment of inertia of various one dimensional and two-dimensional objects
CO3	Analyse motion under the effect of dynamic friction
CO4	Apply the concept of virtual work for bodies in equilibrium
CO5	Apply the D'Alembert's Principle for reducing the problem of kinetics to equivalent statics problem.

## 4. Co-Relationship Matrix

Indicate the relationships by 1- Slight (Low) 2- Moderate (Medium) 3-Substantial (High)

Program Outcomes Course Outcomes	P0 1	P0 2	PO 3	PO 4	PO 5	P0 6	PO 7	PO 8	PO 9	PO1 0	P01 1	PO1 2	PSO 1	PSO 2	PSO 3
CO1	03	03	-	-	-	-	-	-	-	-	-	-	-	-	-
CO2	03	03	-	-	-	-	-	-	-	-	-	-	-	-	-
соз	03	03	-	-	-	-	-	-	-	-	-	-	-	-	-
CO4	03	03	-	-	-	-	-	-	-	-	-	-	-	-	-
CO5	03	03	-	-	-	-	-	-	-	-	-	-	-	1	-
Average	03	03	-	-	-	-	-	-	-	•	-	-	-	0.2	-



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## 5. Course Outcomes Assessment Plan (COA):

Course Outcomes	Internal As (30 Ma		Mid Term	End Term	Total (100 Marks)	
	Before Mid Term	After Mid Term	Exam (20 Marks)	Exam (50 Marks)		
CO1	6	NA	10	4	20	
CO2	6	NA	10	4	20	
CO3	NA	8	NA	12	20	
CO4	NA	7	NA	13	20	
CO5	NA	3	NA	17	20	
Total	12	18	20	50	100	

<sup>\*</sup> Internal Assessment – Tools Used: Tutorial, Assignment, Seminar, Class Test etc.



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## **OVERVIEW OF COURSE PLAN OF COURSE COVERAGE**

## **Course Activities:**

S.			Planned					
No	Description	From	То	No. of Sessio n	From	то	No. of Sessio n	Remark s
1.	Basics of Statics and Concurrent Forces	05/04/202 1	26/04/202 1	11				
2.	Parallel and Distributed Forces	28/04/202 1	02/06/202 1	18				
3.	Friction	03/06/202 1	24/06/202 1	13				
4.	Virtual Work	25/06/202 1	08/07/202 1	8				
5.	Introductio n to Dynamics	09/07/202 1	28/07/202 1	10				

Total No. of Instructional periods available for the course: 60 Sessions

Signature of HOD/Dean	Signature of Faculty
Date:	Date:



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## SESSION PLAN UNIT-I

	Session Plan					Actual Delivery					
Le ct.	Date	Topics to be Covered	CO Map ped	Le ct.	Date	Topics Covered	CO Achie ved				
1	05/04/ 2021	Introduction to the course & Prerequisite knowledge	CO1								
2	07/04/ 2021	Introduction, Force & Two-Dimensional Force system	CO1								
3	08/04/ 2021	Resolution of Force & their Application	CO1								
4	09/04/ 2021	Composition of Force & their Application	CO1								
5	12/04/ 2021	Concept of particle and Rigid body, Vector	CO1								
6	15/04/ 2021	Concept of particle and Rigid body, Vector	CO1								
7	16/04/ 2021	Introduction to equilibrium and concept of Lami's Theorem	CO1								
8	19/04/ 2021	Concept of Free body Diagram	CO1								
9	22/04/ 2021	Equation of Equilibrium.	CO1								
1	23/04/ 2021	Numerical Problem related to Free body diagram	CO1								
1	26/04/ 2021	Numerical Problem related to Free body diagram of circular body	CO1								

Remarks: Signature of Faculty



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## SESSION PLAN UNIT-II

Session Plan					Actual Delivery					
Le ct.	Date	Topics to be Covered	CO Map ped	Le ct.	Date	Topics Covered	CO Achie ved			
1	28/04/ 2021	Moment of a force about a point and an axis	CO2							
2	29/04/ 2021	Moment of forces and their numerical problems	CO2							
3	30/04/ 2021	Distributed Parallel forces in a plane & Concept of Varignan's theorem.	CO2							
4	03/05/ 2021	Couple and their numerical problems	CO2							
5	05/05/ 2021	Introduction to Center of Mass and Centroid	CO2							
6	06/05/ 2021	Centroid of Mass	CO2							
7	10/05/ 2021	Centroid of Line and Area (Triangle, Circular section, Quadrilateral, Composite Area etc.).	CO2							
8	12/05/ 2021	Numerical problem related to CG	CO2							
9	14/05/ 2021	Numerical problem related to CG of 2-Dimensional body	CO2							
1 0	17/05/ 2021	Numerical problem related to CG of 3-Dimensional body	CO2							
1	19/05/ 2021	Mass Moment of Inertia of Symmetrical bodies	CO2							



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1 2	20/05/ 2021	Area Moment of Inertia	CO2		
1 3	21/05/ 2021	Introduction, M.I of Plane figures w.r.t an axis on its plane	CO2		
1 4	24/05/ 2021	M.I of plane figures w.r.t an axis perpendicular to its plane	CO2		
1 5	27/05/ 2021	Parallel axis theorem.	CO2		
1 6	28/05/ 2021	Numerical problem related to MI	CO2		
1 7	31/05/ 2021	Numerical problem related to MI of geometrical 2-Dimentional body	CO2		
1 8	02/06/ 2021	Numerical problem related to MI of Unsymmetrical body	CO2		

Signature of Faculty

Date:



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## **SESSION PLAN**

## UNIT-III

Session Plan				Actual Delivery			
Le ct.	Date	Topics to be Covered	CO Map ped	Le ct.	Date	Topics Covered	CO Achie ved
1	03/06/2 021	Introduction to Friction	CO3				
2	04/06/2 021	Concept of Friction-Angle of friction and angle of repose	CO3				
3	07/06/2 021	Law of Coulomb Friction	CO3				
4	09/06/2 021	Static & Dynamic Friction	CO3				
5	10/06/2 021	Limiting Friction, Coefficient of Friction	CO3				
6	11/06/2 021	Application of Friction in Machines	CO3				
7	14/06/2 021	Numerical problem related to friction when the body rest on horizontal plane	CO3				
8	16/06/2 021	Numerical problem related to friction when the body is in inclined plane	CO3				
9	17/06/2 021	Numerical problem related to friction when the body is under maximum and minimum force.	CO3				
1 0	18/06/2 021	Concept of ladder friction	CO3				



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1 1	21/06/2 021	Numerical Problem related to Ladder Friction	CO3		
1 2	23/06/2 021	Concept of Wedge friction	CO3		
1 3	24/06/2 021	Numerical Problem related to wedge friction	CO3		

Remarks:

**Signature of Faculty** 

Date:



**Semester: II** 

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## SESSION PLAN UNIT-IV

				<u>JNIT-</u>	<u> 1V</u>		-
		Session Plan				Actual Delivery	
Le ct.	Date	Topics to be Covered	CO Map ped	Le ct.	Date	Topics Covered	CO Achie ved
1	25/06/2 021	Concept of Virtual Work & Principle of Virtual Work	CO4				
2	28/06/2 021	Application of Principle of Virtual Work on Beams Carrying Point Load	CO4				
3	30/06/2 021	Numerical Problem related to virtual work on Beams carrying Point Load	CO4				
4	01/07/2 021	Application of Principle of Virtual Work on Beams Carrying Uniformly Distributed Load.	CO4				
5	02/07/2 021	Numerical Problem related to virtual work on Beams carrying Uniformly Distributed Load.	CO4				
6	05/07/2 021	Application of Principle of Virtual Work on Ladders	CO4				
7	07/07/2 021	Numerical Problem related to virtual work on Ladder	CO4				
8	08/07/2 021	Application of Principle of Virtual	CO4				



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

	Work on Lifting			
	Machines			

Remarks:

Signature of Faculty

Date:

## SESSION PLAN UNIT-V

	Se	ession Plan	-	JINI I		Actual Delivery	
Le ct.	Date	Topics to be Covered	CO Map ped	Le ct.	Date	Topics Covered	CO Achie ved
1	09/07/202 1	Newton's Laws of Motion	CO5				
2	14/07/202 1	Concept of Motion of a Lift.	CO5				
3	15/07/202 1	D'Alembert's Principle & related to few numerical problems.	CO5				
4	16/07/202 1	Indicated Power, Brake Power, Efficiency of an Engine	CO5				
5	19/07/202 1	Concept of Projectile motion & important terms related to projectile motion.	CO5				
6	21/07/202	Derive the Equation of the Path of a Projectile	CO5				



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

 7. Course
 : Engineering Mechanics
 L: 3

 8. Program
 : B.Tech
 T: 1

 9. Target
 : 60%
 P: 0

 C: 4

7	22/07/202 1	Time of Flight of a Projectile on a Horizontal Plane	CO5		
8	23/07/202 1	Horizontal Range of a Projectile	CO5		
9	26/07/202 1	Maximum Height of a Projectile on a Horizontal Plane	CO5		
1 0	28/07/202	Numerical Problem related to projectile motion.	CO5		

Remarks:

**Signature of Faculty** 

Date:



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **PERIODIC MONITORING**

## Actual date of completion and remarks, if any

Components		From	То	From	То
Duration (Me	ention from and to	05/04/202	16/06/202	17/06/2021	02/08/202
Γ	Dates)		1	17/00/2021	1
Percentage o	f Syllabus covered	50	)%	50	%
Lectures	Planned	1	23	24	45
Lectures	Taken				
Tutorials	Planned	1	8	9	15
Tutoriais	Taken				
	Planned	1	1(MID)	1	1(END)
	Taken				
Test/Quizzes/ Mid Semester/ End Semester	CO's Addressed	CO1 & CO2	CO1 & CO2	CO3, CO4, CO5	CO1, CO2, CO3, CO4, CO5
End Semester	CO's Achieved	CO1 & CO2	CO1 & CO2	CO3, CO4, CO5	CO1, CO2, CO3, CO4, CO5
	Planned	1	1	•	1
Assignments	Taken				
Assignments	CO's Addressed	CO1	CO2	CO3	CO4, CO5
	CO's Achieved	CO1	CO2	CO3	CO4, CO5
Signatu	Signature of Faculty				
Head of th	Head of the Department				
OBE C	oordinator				

Signature of HOD/ Dean Signature of Faculty

Date Dat



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **PERIODIC MONITORING**

## Attainment of the Course (Learning) Outcomes:

Components	Attainment level	Action Plan	Remarks
	CO1:	Submission Target 28/04/2021	Assignment Questions Covered
			the Basics of Statics and
			Concurrent Forces
	CO2:	Submission Target 03/06/2021	Covered Parallel and
Assignment			Distributed Forces
	CO3:	Submission Target 25/06/2021	Covered Friction
	CO4:	Submission Target 29/07/2021	Assignment Questions Covered
	CO5:		the virtual Work &
			Introduction to Dynamics
	CO1:	Conducted on 17/05/2021	Basics of Statics and
	CO2:		Concurrent Forces & Basics of
Quiz/Test etc.			Statics and Concurrent Forces
Quiz/ Test etc.	CO3:	Conducted on 30/07/2021	Friction, virtual Work &
	CO4:		Introduction to Dynamics
	CO5:		
	CO1:		Question Bank Given for CO1 &
	CO2:		CO2 to understand the Pattern
Mid Semester			of Exam
Miu Semester	CO3:		
	CO4:		
	CO5:		
	CO1:		
	CO2:		
End Semester	CO3:		Question Bank Given for al COs
	CO4:		to understand the Pattern of
	CO5:		Exam
	CO1:		
	CO2:		
Any Other	CO3:		
	CO4:		
	CO5:		

Signature of HOD/ Dean

**Signature of Faculty** 

Date

Date



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

#### **Sample Question Paper- Set 1**



# ADAMAS UNIVERSITY SCHOOL OF ENGINEERING & TECHNOLOGY

END -SEMESTER EXAMINATIONS (JUNE 2019)
NAME OF THE PROGRAM: B. Tech

DEPARTMENT: ME/CSE/ECE/EE/CE/BIOTECH SUBJECT NAME: Engineering Mechanics

SEMESTER: II
Total No of Pages: 2

**SUBJECT CODE: EME41104** 

Time: 3 Hrs. Maximum Marks: 40

#### Group- A (Question no. 1 is compulsory.)

1	Answer	all the	Five	Ouestions
1.	THISWEL	an unc	LIVE	Oucsuons

 $(5 \times 1 Marks = 5 Marks)$ 

- (i) The Lami's Theorem is applicable only for
  - (A) Coplaner forces (B) Concurrent forces (C) Coplaner & concurrent forces (D) All of these
- (ii) The moment of inertia of rectangular section 3 cm wide and 4 cm deep about X-X axis
  - (A) 16 cm4
- (B)18 cm4
- (C)20 cm4
- (D)14 cm4
- (iii) If the resultant of two equal forces has the same magnitude as either of the forces, then the angle between the two forces is
  - $(A) 30^{\circ}$
- (B)  $60^{\circ}$
- (C)  $90^{\circ}$
- (D) 120°
- (iv) The maximum frictional force, which comes into play, when a body just begins to slide over the surface of the other body, is known as (A) Limiting friction (B) static friction (C) Dynamic friction (D) None of these
- (v) The moment of inertia of a triangular section of base (b) and height (h) about an axis through its c. g and parallel to the base is given by the relation.
  - (A) bh3/36
- (B) bh3/12
- (C) bh3/24
- (D) bh3/48

#### Group-B

Answer any three questions

 $(3 \times 5 Marks = 15 Marks)$ 

- 2. Explain:
  - (a) Varignon's principle of moments
  - (b) Polygon law of forces

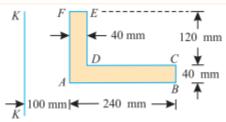


**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty
 7. Course : Engineering Mechanics
 8. Course Code: MEE11002
 9. L: 3

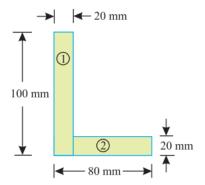
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

3. Figure 7.12 shows an area ABCDEF.

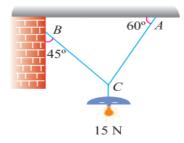


Compute the moment of inertia of the above area about axis K-K.

4. Find the centroid of an unequal angle section  $100 \text{ mm} \times 80 \text{ mm} \times 20 \text{ mm}$ . (5)



5. An electric light fixture weighting 15 N hangs from a point C, by two strings AC and BC. The string AC is inclined at 60° to the horizontal and BC at 45° to the horizontal as shown in Figure 1. Using Lami's theorem, determine the forces in the string's AC and BC. (5)



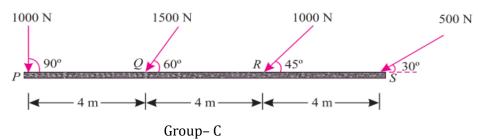
6. A horizontal line PQRS is 12 m long, where PQ = QR = RS = 4 m. Forces of 1000 N, 1500 N, 1000 N and 500 N act at P, Q, R and S respectively with downward direction. The lines of action of these forces make angles of  $90^{\circ}$ ,  $60^{\circ}$ ,  $45^{\circ}$  and  $30^{\circ}$  respectively with PS. Find the magnitude, direction and position of the resultant force.



**Semester: II** 

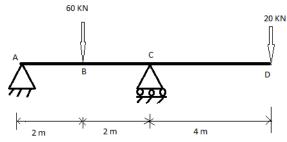
6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

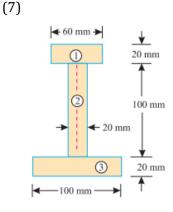


Answer any two questions  $(2 \times 10 Marks = 20 Marks)$ 

- 7. (a) Explain principle of transmissibility?
  - (b) Find out the reaction forces at support as shown in figure below using principle of virtual work.



- 8. (a) Derive perpendicular axis theorem of moment of inertia.
  - (b) An I-section is made up of three rectangles as shown in Figure below. Find the moment of inertia of the section about the horizontal axis.



- 9. (a) Explain Laws of friction?
  - (b) An effort of 200 N is required just to move a certain body up an inclined plane of angle 15° the force acting parallel to the plane. If the angle of inclination of the plane is made 20° the effort required, again applied parallel to the plane, is found to be 230 N. Find the weight of the body and the coefficient of friction.



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9. Target : 60% P: 0
C: 4

## **Question Bank Sample**

W O	
DAMAS	
UNIVERSITY	
PURSUE EXCELLENCE	

School: School Of Engineering & Technology
Course Code: EME41102

Department: ME/EE/CSE/CE/ECE/Bio-Tech
Course Name: Engineering Mechanics

Program: B.Tech Semester: 2<sup>nd</sup>

Sl. No	Question	Level of Difficulty (Easy/ Medium/ Difficult)	Knowledge Level (Bloom's Taxonomy)	Course Outcome (CO)
	Part A (Multiple Choice Question	ıs) (1 mark e	ach)	
1.	The Forces, which meet at one point, but their lines do not lie in a plane, are called,  a) Coplanar non-concurrent forces b) Non-coplanar concurrent forces c) Non-coplanar non-concurrent forces d) Intersecting forces	Easy	U	1
2.	A single force and a couple acting in the same plane upon a rigid body,  a) Balance each other b) Cannot balance each other c) Produce moment of a couple d) Are equivalent	Medium	R	1
3.	If a rigid body is in equilibrium under the action of three forces, then  a) These forces are equal b) The lines of action of these forces meet in a point c) The lines of action of these forces are parallel d) (b) and (c) above e) None of the above.  Part B (Definition/Naming Ques	Difficult	Ap	1



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

1.	State Varigon's Theorem?	Easy	U	1
2.	What is the different between a resultant force and equilibrant force?	Medium	Ар	1
3.	Explain the concept of Free body diagram with example. Also write down necessary and sufficient conditions of equilibrium for coplanar and nonconcurrent system.	Difficult	R	1
	Part C (Short Questions) (3-4	marks each	)	
1.	Explain the concept of Free body diagram with example. Also write down necessary and sufficient conditions of equilibrium for coplanar and nonconcurrent system.	Easy	U	1
2.	For what condition the moment of a force will be Zero? Explain	Medium	Ap	1
3.	A force of magnitude 500N is passing through the origin and a point A (0.2,1,0)m. Write the couple form of the force	Difficult	R	1
	Part D (Explanation Based Question	ns) (5 mark	s each)	
1.	Show that the algebraic sum of the resolved part of a number of forces in a given direction, is equal to the resolved part of their resultant in the same direction.	Easy	U	1
2.	Show that if three coplanar forces, acting at a point be in equilibrium, then each force is proportional to the sine of the angle between the other two.	Medium	Ap	1
3.	ABCD is a square, each side being 20cm and E is a middle point AB. Forces of 7, 8, 12, 5, 9 and 6 KN act on the lines of directions AB, EC, BC, BD, CA and DE respectively. Find the magnitude, direction and position of the resultant force.	Difficult	U	1
	Part E (Questions Based on Reason	ing) (5 mark	s each)	
1.	The resultant of two forces P and Q is R. If the Q is doubled, the new resultant is perpendicular to P. Prove that Q=R	Easy	Ар	1



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2.	A uniform wheel of 600 mm diameter, weighing 5 kN rests against a rigid rectangular block of 150 mm height as shown in Fig. Find the least pull, through the centre	Medium	Ар	1
	of the wheel, required just to turn the wheel over the corner A of the block. Also find the reaction on the block. Take all the surfaces to be smooth.	Diffili		
3.	A machine component of length 2.5 metres and height 1 metre is carried upstairs by two men, who hold it by the front and back edges of its lower face. If the machine component is inclined at 30° to the horizontal and weighs 100 N, find how much of the weight each man supports?	Difficult	Ap	1
	Part F (Application Based Questions	s) (5-10 mar	ks each)	•
1.	Two equal heavy spheres of 50 mm radius are in equilibrium within a smooth cup of 150 mm radius. Show that the reaction between the cup of one sphere is double than that between the two spheres.	Easy	Ap	1
2.	Three cylinders weighting 100 N each and of 80 mm diameter are placed in a channel of	Medium	Ар	1



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	180 mm width as shown in Fig Determine the pressure exerted by (i) the cylinder A on B at the point of contact, (ii) the cylinder B on the base.			
3.	Two identical prismatic bars PQ and RS each weighing 75 N are welded together to form a Tee and are suspended in a vertical plane as shown in Fig. Calculate the value of $\theta$ , that the bar PQ will make with vertical when a load of 100 N is applied at S.	Difficult	Ар	1
	Part G (Short Notes) (5 m	arks each)		
1.	Rigid Body	Easy	U	1
2.	Static and Dynamics of rigid body	Medium	R	1
3.	Stable, Unstable and Natural Equilibrium	Difficult	U	1

Part A (Multiple Choice Questions) (1 mark each)				
1.	The moment of inertia of a solid sphere of	Easy		
	mass 'm' and radius 'r' is, a) $2mr^2/3$			
	b) 2mr <sup>2</sup> /5		U	2
	c) mr²			
	d) mr <sup>2</sup> /2			
2.	The moment of inertia of a square of side $a$ about	Medium		
	its diagonal is,			
	a) a <sup>4</sup> /8		R	2
	b) a <sup>4</sup> /12			



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	c) a <sup>4</sup> /36			
3.	d) $a^4/16$ The centre of gravity a <i>T</i> -section 100 mm × 150	Difficult		
3.	$mm \times 50 \text{ mm from its bottom is,}$	Difficult		
	a) 50mm		U	2
	b) 75mm			_
	c) 87.5mm			
	d) 125mm			
	Part B (Definition/Naming Ques	tions) (2 ma	rks each)	-
1.	Distinguish between centre of gravity and centroid.	Easy	U	2
2.	What is Routh's rule for finding out the moment of inertia of an area?	Medium	R	2
3.	Distinguish between area and mass moment of inertia of a body.	Difficult	R	2
	Part C (Short Questions) (3-4	marks each	i)	•
1.	Describe the various methods of finding out the	Easy		
	centre of gravity of a body.		U	2
2.	State the parallel and perpendicular axis theorem	Medium	R	2
	applied to moment of Inertia.	Diffi and		
3.	Distinguish between Axis of Symmetry and Axis of revolution.	Difficult	R	2
	Part D (Explanation Based Question	ns) (5 mark	s each)	
1.	State and prove the theorem of perpendicular axis applied to moment of inertia.	Easy	U	2
2.	Prove the parallel axis theorem in the	Medium		
	determination of moment of inertia of areas with		R	
	the help of a neat sketch.			2
3.	Derive an equation for moment of inertia of the	Difficult		
	hollow circular sections about centroidal axis:		R	2
	Part E (Questions Based on Reason	ing) (5 mark	ks each)	
1.	A body consisting of a cone and hemisphere of	Easy		
	radius r fixed on the same base rests on a table, the		Ap	
	hemisphere being in contact with the table. Find			
				2



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1	the greatest height of the cone, so that the			
	combined body may stand upright			
2.	A frustum of a solid right circular cone has an axial hole of 50 cm diameter as shown in Fig. Determine the centre of gravity of the body	Medium	Ар	2
3.	Figure shows an area ABCDEF. Compute the moment of inertia of the above area about axis K-K.  F  E  40 mm  120 mm $A$ $A$ $A$ $A$ $A$ $A$ $A$	Difficult	Ар	2
	Part F (Application Based Questions	s) (5-10 mar	ks each)	
1.	When will the product of inertia of an area become	Easy	_	
	Zero?		Ap	2
2.	A square hole is punched out of circular lamina, the diagonal of the square being the radius of the circle as shown in Fig. Find the centre of gravity of the remainder, if r is the radius of the circle	Medium	Ар	2 2



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Part G (Short Notes) (5 marks each)				
1.	Centroid	Easy	U	2
2.	Parallel and perpendicular axis theorem	Medium	U	2
3.	Radius of Gyration	Difficult	U	2

Part A (Multiple Choice Questions) (1 mark each)				
1.	The force of friction between two bodies in contact,  (a) Depends upon the area of their contact  (b) Depends upon the relative velocity between them  (c) Is always normal to the surface of their contact  (d) All of the above	Easy	U	3
2.	The magnitude of the force of friction between two bodies, one lying above the other, depends upon the roughness of the,  (a) Upper body (b) Lower body (c) Both the bodies (d) The body having more roughness	Medium	U	3
3.	The force of friction always acts in a direction opposite to that  (a) In which the body tends to move  (b) In which the body is moving  (c) Both (a) and (b)  (d) None of the two	Difficult	U vlva a a a b	3
1.	Part B (Definition/Naming Ques	Easy	<u> </u>	
	Define coefficient of friction and limiting friction.		R	3
2.	State the laws of friction.	Medium	R	3
3.	What is angle of friction and angle of repose	Difficult	R	3



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	Part C (Short Questions) (3-4	marks each	n)	
1.	Prove that the angle of repose and angle of friction are equal for freely falling down of a body in any inclined plane.	Easy	U	3
2.	Write down the application of friction.	Medium	U	3
3.	Find the horizontal force required to drag a body of weight 100 N along a horizontal plane. If the plane, when gradually raised up to 15°, the body will begin to slide.	Difficult	Ap	3
	Part D (Explanation Based Question	ns) (5 mark	s each)	
2.	A body of weight 300 N is lying on a rough horizontal plane having a coefficient of friction as 0.3. Find the magnitude of the force, which can move the body, while acting at an angle of 25° with the horizontal.  Two blocks A and B of weights 1 kN and 2 kN respectively are in equilibrium position as shown in Fig. If the coefficient of friction between the two blocks as	Easy Medium	Ap	3
3.	well as the block B and the floor is 0.3, find the force (P) required to move the block B.  Two blocks A and B, connected by a horizontal rod and frictionless hinges are supported on two rough planes as shown in Fig.	Difficult	Ap	



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	The coefficients of friction are 0.3 between block A and the horizontal surface, and 0.4 between block B and the inclined surface. If the block B weighs 100 N, what is the smallest weight of block A, that will hold the system in equilibrium?			3
	Part E (Questions Based on Reason	ing) (5 mark	ks each)	
1.	A load of 1.5 kN, resting on an inclined rough plane, can be moved up the plane by a force of 2 kN applied horizontally or by a force 1.25 kN applied parallel to the plane. Find the inclination of the plane and the coefficient of friction	Easy	Ар	3
2.	Two loads, W1  (equal to 1 kN )  and W2 resting on two inclined rough planes OA and OB are connected by a  horizontal link PQ as shown in Fig. Find the maximum and minimum values of W2 for which the equilibrium can exist. Take angle of friction for both the planes as 20°	Medium	Ар	3
3.	A block (A) weighing 1 kN rests on a rough inclined plane whose inclination to the horizontal is 45°. This block is connected to another block (B) weighing 3 kN rests on a rough horizontal plane by a weightless rigid bar	Difficult	Ар	3



**Semester: II** 

7	5. Name of the Faculty: Mr. Sudip Chakraborty 7. Course : Engineering Mechanics 8. Program : B.Tech 9. Target : 60%	Co	ourse Code: MEE1 L: 3 T: 1 P: 0 C: 4	1002
	inclined at an angle of 30° to the horizontal as shown in Fig. Find horizontal force (P) required to be applied to the block (B) just to move the block (A) in upward direction. Assume angle of limiting friction as 15° at all surface where there is sliding			
	Part F (Application Based Questions	s) (5-10 mar	ks each)	
1.	A load of 500 N is lying on an inclined plane, whose inclination with the horizontal is 30°. If the coefficient of friction between the load and the plane is 0.4, find the minimum and maximum horizontal force, which will keep the load in equilibrium.	Easy	Ар	3
2.	A rectangular prism (W) Horizontal string 7  weighing 150 N, is lying on an inclined plane whose inclination with the horizontal is shown in Fig. The block is tied up by a horizontal string, which has a tension of 50 N. From fundamentals find (i) the frictional force on the block (ii) the normal reaction of the inclined plane, (iii) the coefficient of friction between the surface of contact.	Medium	Ар	3
3.	Two blocks A and B of weight 100 N and 300 N respectively are resting on a rough inclined plane as shown in Fig. Find	Difficult	Ар	



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	the value of the angle ( $\theta$ ) when the block B is about to slide. Take coefficient of friction between the two blocks as well as block B and the inclined plane as 0.25.			3	
Part G (Short Notes) (5 marks each)					
1.	Limiting Friction	Easy	R	3	
2.	Coefficient of Friction	Medium	R	3	
3.	Angle of Friction	Difficult	R	3	

	Part A (Multiple Choice Question	ns) (1 mark ea	ch)	
1.	The term 'virtual work' refers to  (a) actual work done by virtual forces  (b) virtual work done by actual forces  (c) virtual work done by virtual forces	Easy	U	4
2.	The principle of virtual work is applicable for the bodies in equilibrium (a) Agree (b) Disagree	Medium	U	4
3.	The principle of virtual work can be applied for all types of (a) possible displacements (b) impossible displacement (c) none of the two	Difficult	U	4
	Part B (Definition/Naming Ques	tions) (2 marl	ks each)	
1.	What is the concept of virtual work?	Easy	R	4
2.	What is beam? Write down the name of different types of beam.	Medium	R	4
3.	Explain the concept of zero, negative and positive work done.	Difficult	R	4
	Part C (Short Questions) (3-4	marks each)		•



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1.	State the principle of virtual work	Easy	U	4
2.	Explain the principle of virtual work applied in lifting machine	Medium	4	
3.	Explain the principle of virtual work on beams carrying point load	Difficult	Ap	4
	Part D (Explanation Based Question	ns) (5 mark	s each)	
1.	State the principle of virtual work, and explain how it can be used for solving problems in statics.	Easy	U	4
2.	How will apply the principle of virtual work in finding out the forces in a framed structure.	Medium	R	4
3.	State the principle of virtual work	Difficult R		
	Part E (Questions Based on Reason	ing) (5 mark	s each)	
1.	A block of weight  (W) rests on the smooth surface inclined at 20° with the horizontal. The block is supported by an effort (P) hung from a pulley as shown in Fig. Using the principle of virtual work, obtain expression for (P) in terms of (W), when the system is at rest.	Easy	Ар	4
2.	The diameter of the pulleys in a differential pulley block are 300 mm and 250 mm respectively. Using the principle of virtual work and neglecting friction, find the value of the effort required to lift a load of 3 kN.	Medium	Ap	4
3.	Five rods AB, BC, CD, DA and DB each of equal length and cross-section are pin-jointed together, so as to form a plane frame ABCD. The frame is suspended from the top most joint A. A weight (W) is attached at the lower most joint C. Neglecting	Difficult	Ар	4



Semester: II

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 7. Course
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 L: 3

 8. Program
 : B.Tech
 T: 1

 9. Target
 : 60%
 P: 0

 C: 4

	self-weight of the frame and using the method of			
	virtual work, find magnitudes of the thrust in the			
	member BD.			
	Part F (Application Based Questions	s) (5-10 mar	ks each)	
1.	A simply supported beam AB of span 4 m is	Easy		
	subjected to a point load of 10 kN at a distance of			
	1.5 m from A. Using the principle of virtual work,		Ap	4
	determine the reactions at the two supports.			
2.	Two 15 kN 12 kN	Medium		
	beams $A \longrightarrow B \longrightarrow C \longrightarrow D \longrightarrow E \longrightarrow F$ .			
	AD and $\longrightarrow 1 \text{ m} \longrightarrow 2  $			
	DF of		A	
	spans 6m and 4m respectively are hinged at C and		Ap	4
	supported at A, D and F. The beams are loaded as			
	shown in Fig. Using the principle of virtual work,			
	find the reaction at D			
3.	A simply 5 kN/m 2 m 2 m	Difficult		
	A management of the second state of the second			
	supported beam of span 4 m is carrying a			
	uniformly distributed load of 5 kN/m as shown in		Ap	4
	Fig. Using the principle of virtual work, find the		•	
	reactions at A and B.			
	Part G (Short Notes) (5 m	arks each)		
1.	Virtual Work for Beam Problem	Easy	U	4
2.	Virtual Work for Lifting Machine	Medium	U	T T
			0	4
3.	Vartual Work for Ladder	Difficult	U	4
			l	4



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

	Part A (Multiple Choice Question	ns) (1 mark ea	ich)		
1.	The time of flight of a projectile on a horizontal plane is (a) $2u \sin\alpha/g$ (b) $2u\cos\alpha/g$ (c) $2u \sin\alpha/2g$ (d) $u \cos 2\alpha/2g$	Easy	U	5	
2.	The horizontal range of a projectile is maximum when the angle of projectile is (a) 30° (b) 45° (c) 60° (d) 75°	Medium R			
3.	The time of flight of a projectile on an upward inclined plane depends upon (a) angle of projection (b) angle of inclination of the plane (c) both 'a' and 'b' (d) none of the above	Difficult U 5			
	Part B (Definition/Naming Ques	tions) (2 mar	ks each)		
1.	What is a projectile? Give an example of a projectile.	Easy	Ap	5	
2.	Define the terms: velocity of projection and angle of projection	Medium	U	5	
3.	Obtain an equation for the trajectory of a projectile, and show that it is a parabola	Difficult R 5			
	Part C (Short Questions) (3-4	ł marks each)			
1.	Derive an expression for the maximum height and range of a projectile traversed by a stone, thrown with an initial velocity of u and an inclination of $\alpha$ .	Easy	R	5	
2.	At what angle, the projectile should be projected in order to have maximum range? Justify your answer by calculations.	Medium	R	5	
3.	Derive a relation for the velocity and direction of motion of a projectile: (a) after a given interval of time t from the instant of projection. (b) at a given height h above the point of projection.	Difficult	R	5	
	Part D (Explanation Based Question	ons) (5 marks	each)		
1.	How would you find out (a) time of flight (b) range of a projectile, when projected upwards on an	Easy	Ap	5	



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

2.	inclined plane? What happens to the above equations, when the same projectile is projected on the same plane, but in a downward direction?  A bullet is fired at such an angle, over a horizontal plane, that its horizontal range is equal to its greatest height. Find the angle of projection	n? ontal <b>Medium</b>			
<u> </u>	Derive the equation of path of the projectile.		U	5	
	Part E (Questions Based on Reason	ing) (5 mark	ks each)		
1.	Derive the equation of Maximum hight of a projectile on a horizontal range.	Easy	Ap	5	
2.	Derive the equation of time of flight on a projectile in horizontal range.	Medium	Ap 5		
3.	A particle is projected from the base of a hill whose shape is that of a right circular cone with axis vertical. The projectile grazes the vertex and strikes the hill again at a point on the base. If $\theta$ be the semi-vertical angle of the cone, h its height, u the initial velocity of the projectile and $\alpha$ the angle of projection $\tan \alpha = 2 \cot \theta  \text{and}  u^2 = gh\left(2 + \frac{1}{2}\tan^2\theta\right).$ measured from the horizontal, show that where g is acceleration due to gravity.	Difficult	Ар	5	
	Part F (Application Based Questions	s) (5-10 mar	ks each)		
1.	A ball is projected upwards with a velocity of 15 m/s at an angle of 25° with the horizontal. What is the horizontal range of the ball?	Easy	Ар	5	
2.	A bullet is fired with a velocity of 100 m/s at an angle of 45° with the horizontal. How high the bullet will rise?	Medium Ap 5		5	
3.	If a particle is projected inside a horizontal tunnel which is 5 metres high with a velocity of 60 m/s, find the angle of projection and the greatest possible range.	/s,   An		5	



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

 7. Course
 : Engineering Mechanics
 L: 3

 8. Program
 : B.Tech
 T: 1

 9. Target
 : 60%
 P: 0

 C: 4

	Part G (Short Notes) (5 marks each)				
1.	Trajectory.	Easy	U	5	
2.	Velocity of projection	Medium	U	5	
3.	Angle of projection	Difficult	R	5	



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

#### **Evaluation Sheet - Internal Assessment**

		Name of the Student	Internal Assessment (30)				
Roll	Registration		Assignmen	Class Test	Case Study	etc.	Tota
Number	Number		t				l

Signature of HOD/Dean	Signature of Faculty
Date:	Date:



Semester: II

6. N	Name of the Faculty: Mr. Sudip Chakraborty	Course Code: MEE11002
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7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **Evaluation Sheet - Mid Semester**

Roll Number	Registration Number	Name of the Student	Marks (20)

Signature of HOD/Dean	Signature of Faculty
Date:	Date:



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **Planning for Remedial Classes - Mid Semester**

			_		Remedia	al Cla	isses H	leld			End Sem	
Sl. No.	Name of Student	Roll No.	Reg. No.	Mid Sem						Class test on the	Marks	Improve ment
				Marks						basis of		(Y/N)
										Remedial Classes		(1/N)
										Classes		
					Date							
					Venue							
					Time							
1.												
2.												
C:									C	-t		

Signa	ture	of F	HOD	/ D	ean

Signature of Faculty

Date: Date:



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty
 7. Course : Engineering Mechanics
 8 Course Code: MEE11002
 9 L: 3

8. Program : B.Tech T: 1
9. Target : 60% P: 0

C: 4

# COURSE END SURVEY INDIRECT ASSESSMENT

Sample format for Indirect Assessment of Cou	urse outcomes:
--	----------------

JAME:
ROLL
VO.:
REG. NO:
COURSE:
PROGRAM:

Please rate the following aspects of course outcomes of

Use the scale 1-5 (Poor – Excellent)

Course	Statement	1	2	3	4	5
Outcomes						
C01						
CO2						
CO3						
CO4						
CO5						



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

#### **INDIRECT ASSESSMENT CONSOLIDATION**

	ADAMAS UNIVERSITY, KOLKATA							
	SCHOOL OF							
	DEPARTMENT O	F						
	CO Indirect Assessi	ment						
Programme:		Academic Year:2020-21						
Batch: 2020-22								
Course Code &								
Name:								
Course Outcome	Students Feed Back (5)	Attainment (100)						
CO1								
CO2								
CO3								
CO4								
CO5								
etc.								
Signature of HOD/D	Dean	Signature of Faculty Date:						



Semester: II

6.	Name of the Fac	ulty: Mr. Sudip Chakraborty	Course Code: MEE11002
7.	Course	: Engineering Mechanics	L: 3
8.	Program	: B.Tech	T: 1
9.	Target	: 60%	P: 0

P: 0 C: 4

# **Evaluation Sheet (End Semester)**

Roll Number	Registration Number	Name of the Student	Marks (50)

Signature of HOD/Dean	Signature of Faculty
Date:	Date:



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **Planning for Remedial Classes - End Semester**

Sl. No.	Name of Student	Roll No.	Re g. No.	End Sem Marks	Remedial Classes Held					Class test on the basis of Remedial Classes	Supple Exam Marks	Improvem ent (Y/N)	
					Venue Time								
1.													
2.													

Signature of HOD/ Dean

Signature of Faculty

Date Date



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

## **Consolidated Mark Statement**

			Total Marks			
			Mid	Internal	End	Total
			Semeste	Assessmen	Semeste	(100)
Roll	Registration		r	t	r	
Number	Number	Name of the Student	(20)	(30)	(50)	

Signature of Dean/HOD	Signature of Faculty
Date:	Date:



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

#### **CO ATTAINMENT - GAP ANALYSIS & REMEDIAL MEASURES**

# ADAMAS UNIVERSITY, KOLKATA SCHOOL OF DEPARTMENT OF

#### **CO ATTAINMENT - GAP ANALYSIS & REMEDIAL MEASURES**

Batch :	2020-22			-		Academic	Year: 2020-21	
Course Code & Name			Name of the Coordinator			Year & Semester		
						I & I		
СО	Direct Assessmen t	Indirect Assessmen t	CO Attainmen t	Targe t	CO Attainmen t Gaps	Action for Bridge the Gap	Target Modificatio n	
CO1								
CO2								
CO3								
CO4								
CO5								

Signature of HOD/Dean Signature of Faculty

Date: Date:



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

**Attainment** 

#### **CO-PO ATTAINMENT**

#### ADAMAS UNIVERSITY, KOLKATA **SCHOOL OF DEPARTMENT OF CO-PO ATTAINMENT Programme** I & Academi 2020 Year & Sem: I c Year: -21 Batch:2020-22 PO PO **PSO PSO PSO** PO PO PO **PO** PO **Course Code Course Name** CO-PO **PO4** P05 P06 P08 0 2 10 **12** 2 3 1 1 11 Relationship **Mapping** Value

Signature of HOD/Dean Signature of Faculty

Date:



**Semester: II** 

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002

7. Course : Engineering Mechanics L: 3
8. Program : B.Tech T: 1
9. Target : 60% P: 0
C: 4

#### **PO ATTAINMENT OF THE COURSE**

Signature of HOD/Dean	Signature of Faculty
Date:	Date:



Semester: II

6. Name of the Faculty: Mr. Sudip Chakraborty Course Code: MEE11002