

## Zero Velocity Graph

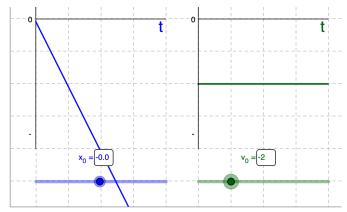
Set the acceleration to a = 0 ms<sup>-2</sup> Set the velocity slider to  $v_0$  = 0.0 ms<sup>-1</sup> Move the  $x_0$  slider between -4 m and + 4m.

- 1. Describe the effect on the position time graph as you move the  $x_0$  slider.
- 2. Using the general equation y=mx+b, identify the term that is associated with the variable  $x_0$  in the equation (y, m, x, or b)
- 3. Describe why the position slider is designated with the subscript  $x_0$ .

## Constant Velocity Graph

Set the acceleration to a = 0 ms<sup>-2</sup> Set the position to  $x_0$  = 0 m Move the velocity slider (green) from -4 ms<sup>-1</sup> to +4 ms<sup>-1</sup>

- 1. Qualitatively describe the impact of changing the velocity on the **position**-time graph.
- 2. In the image below, determine the quantitative relationship between the velocity-time graph and position-time graph.

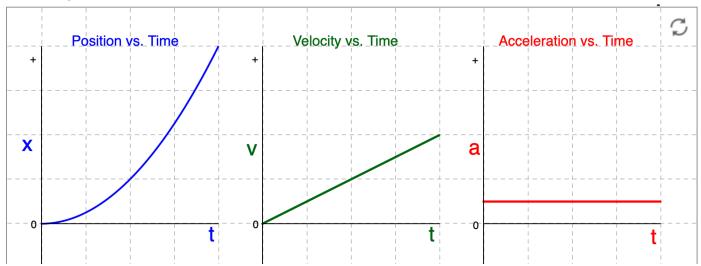


- 3. On the **position-time** graph, using the general equation y=mx+b, identify the term that is associated with the variable  $v_0$  in the equation (y, m, x, or b)
- 4. Describe why the velocity slider is designated with the subscript v<sub>0</sub>.
- 5. With the  $v_0$  slider set to +1 ms<sup>-1</sup>, move the **position** slider from -4 m to + 4 m, from a mathematical perspective, what effect does this have on the position-time graph?
- 6. Complete the following: The value of  $v_0$  determines the \_\_\_\_\_ of the \_\_\_\_ time graph.

## **Constant Acceleration Graph**

Set the velocity to  $v_0 = 0 \text{ ms}^{-1}$ Set the position to  $x_0 = 0 \text{ m}$ Move the acceleration slider (red) from -4 ms<sup>-2</sup> to +4 ms<sup>-2</sup>

In the image below, the  $a = +0.5 \text{ ms}^{-2}$ ,  $v_0 = 0 \text{ms}^{-1}$ , and  $x_0 = 0 \text{ m}$ .



- 1. Describe the mathematical relationship of each of the graphs.
- 2. Based on your experimentation with the acceleration slider, outline the relationship between the value of the acceleration graph and the shape of the velocity-time graph.
- 3. In the simulation the position and velocity sliders are represented by  $x_0$  and  $v_0$  respectively. Explain why the acceleration slider is not designated with  $a_0$ .