

Serial API

I hv created python wrapper for c++ implementation of Serial comm classes.

You should use the `_pyComm.so` shared library to import python module `pyComm` and then can use following functionalities.

```
//refer to SerialCommands.h
```

```
import pyComm
```

```
l = pyComm.Serialcommands();
```

```
l.init("/dev/ttyS0")           //opens the given port and returns success or not
```

```
l.arm_rotate(int angle)       //rotates arm by given angle
```

```
l.move(int heading, int distance) //turns to given heading and moves given dist
```

```
//get sensor data .. trouble accessing sensor_data array elements
```

```
l.get_sensor_data()           //updates sensor_data object
```